P24C02A

I²C-Compatible Serial E²PROM

Datasheet V2.1

General Description

The P24C02A is I²C-compatible Serial EEPROM (Electrically Erasable Programmable Memory) device. It contains a memory array of 2Kbits (256 bytes), which is organized in 8 bytes per page.

Features

- Single Supply Voltage and High Speed Mode
  - 400 KHz/1 MHz clock from 1.7 V to 5.5 V
- Low power CMOS technology
  - Read current 0.2 mA (400 kHz, typical)
  - Write current 0.8 mA (400 kHz, typical)
- Schmitt Trigger, Filtered Inputs for Noise Suppression
- Sequential & Random Read Features
- Page Write Modes, Partial Page Writes Allowed
- Write protect of the whole memory array
- Self-timed Write Cycle (5 ms maximum)
- High Reliability
  - Endurance: 1 Million Write Cycles
  - Data Retention: 100 Years
  - ESD HBM: 4 kV
  - Latch-up Capability: +/- 200 mA(25 C)
- Package: PDIP8, SOP8(150mil), TSSOP8, UDFN8, MSOP8, SOT23-5 and TSOT23-5

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1. Pin Configuration

1.1 Pin Configuration

Figure 1-1 Pin Configuration



PDIP8/SOP8(150mil)/TSSOP8/UDFN8/MSOP8 **SOT23-5/TSOT23-5**

1.2 Pin Definition

Table 1-1 Pin Definition

Pin	Name	Type	Description
1	E0	Input	Slave Address Setting
2	E1	Input	Slave Address Setting
3	E2	Input	Slave Address Setting
4	Vss	Ground	Ground
5	SDA	I/O	Serial Data Input and Serial Data Output
6	SCL	Input	Serial Clock Input
7	WCB	Input	Write Control, Low Enable Write
8	V_{CC}	Power	Power

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1.3 Pin Descriptions

Serial Clock (SCL): The SCL input is used to positive-edge clock data in and negative-edge clock data out of each device.

Serial Data (SDA): The SDA pin is bidirectional for serial data transfer. This pin is open drain driven and may be wire-OR'ed with any number of other open-drain or open-collector devices.

Device Addresses (E2, E1, E0): The E2, E1 and E0 pins are device address inputs. Typically, the E2, E1 and E0 pins are for hardware addressing and a total of 8 devices can be connected on a single bus system. If these pins are left floating, the E2, E1 and E0 pins will be internally pulled down to Vss.

Write Control (WCB): The Write Control input, when WCB is connected directly to V_{CC}, all write operations to the memory are inhibited. When connected to Vss, allows normal write operations. If the pin is left floating, the WCB pin will be internally pulled down to Vss.

Supply Voltage(V_{CC}): V_{CC} is the supply voltage.

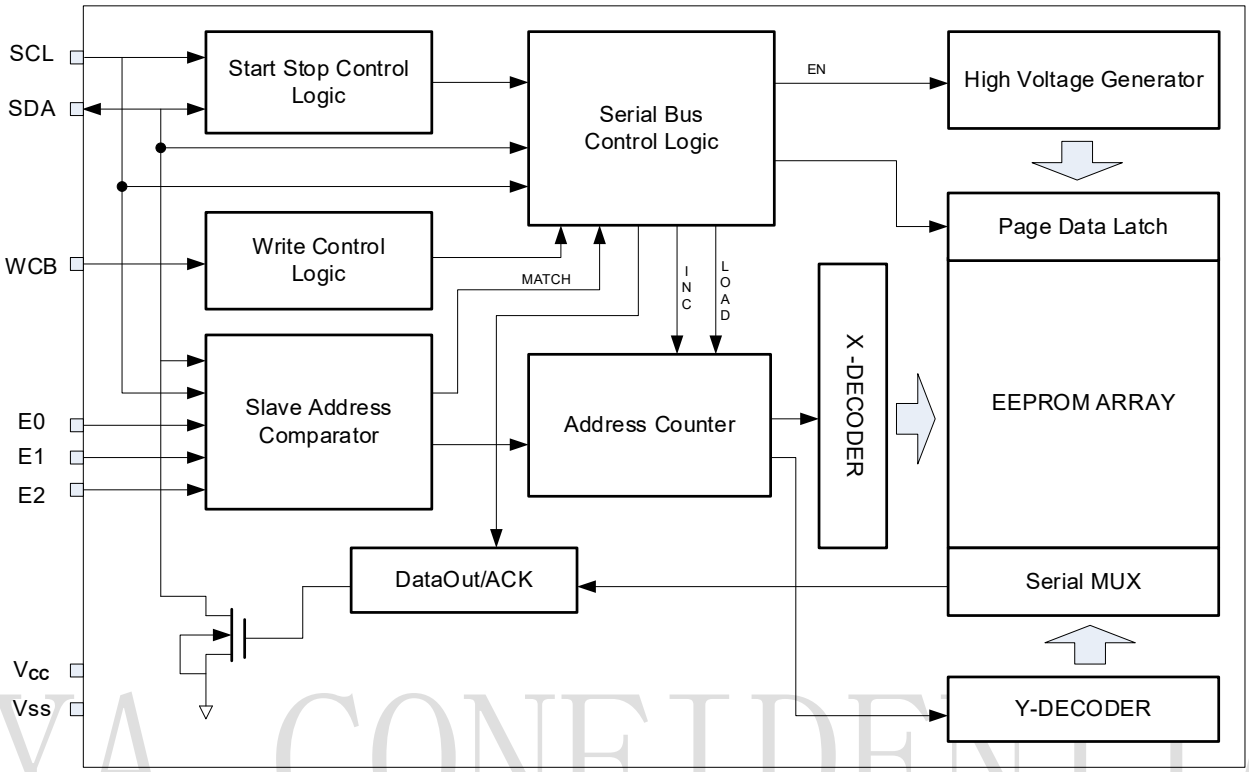
Ground(Vss): Vss is the reference for the V_{CC} supply voltage.

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2. Block Diagram

Figure 2-1 Block Diagram



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3. Electrical Characteristics

Table 3-1 Absolute Maximum Ratings [1]

Symbol	Parameter	Min.	Max.	Units
T_{STG}	Storage Temperature	-65	150	°C
T_A	Ambient operating temperature	-40	125	°C
V_{CC}	Supply Voltage	-0.5	6.5	V
V_{IO}	Input or output range	-0.5	6.5	V
I_{OL}	DC output current (SDA=0)	-	5	mA

Note: [1] Stresses above those listed under “Absolute Maximum Ratings” may cause permanent damage to the device. This is a stress rating only and functional operation of the device at those or any other conditions above those indicated in the operational listings of this specification is not implied. Exposure to maximum rating conditions for extended periods may affect device reliability.

Table 3-2 Pin Capacitance [1]

Symbol	Parameter	Max.	Units	Test Condition
$C_{I/O}$	Input / Output Capacitance (SDA)	8	pF	$V_{I/O}$= Vss
C_{IN}	Input Capacitance (E0, E1,E2,WCB,SCL)	6	pF	V_{IN}= Vss

Note: [1] Test Conditions: T_A = 25°C, f_{SCL} = 1MHz, Vcc = 5.0V.

Table 3-3 DC Characteristics (Unless otherwise specified, V_{CC} = 1.7V to 5.5V, T_A = –40°C to 125°C)

Symbol	Parameter	Min.	Typ.	Max.	Unit	Test Condition
Vcc	Supply Voltage	1.7	-	5.5	V	
Isb	Standby Current	-	-	1.0	uA	Vcc = 3.3V
		-	-	3.0	uA	Vcc = 5.5V
I_{CC1}	Supply Current(Read)	-	0.2	0.4	mA	Vcc=5.5V, f_{SCL} = 400KHz
I_{CC2}	Supply Current(Write)	-	0.8	1.6	mA	Vcc=5.5V, f_{SCL} = 400KHz
I_{LI}	Input Leakage Current	-	0.10	1.0	μA	V_{IN} = V_{CC} or Vss
I_{LO}	Output Leakage Current	-	0.05	1.0	μA	V_{OUT} = V_{CC} or Vss
V_{IL}	Input Low Level	–0.5	-	$0.3V_{CC}$	V	
V_{IH}	Input High Level	$0.7V_{CC}$	-	V_{CC}+0.5	V	
V_{OL1}	Output Low Level V_{CC} = 1.7V (SDA)	-	-	0.2	V	I_{OL} = 0.15 mA
V_{OL2}	Output Low Level V_{CC} = 3.0V (SDA)	-	-	0.4	V	I_{OL} = 2.1 mA

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Table 3-4 100kHz AC Characteristics

（Unless otherwise specified, V_{CC} = 1.7V to 5.5V, T_A = –40°C to 125°C, C_L=100pF, Test Conditions are listed in Notes [2]）

Symbol	Parameter	1.7≤V_{CC}≤5.5			Units
		Min.	Typ.	Max.	
f_{SCL}	Clock Frequency, SCL	-	-	100	kHz
t_{LOW}	Clock Pulse Width Low	4.7	-	-	μs
t_{HIGH}	Clock Pulse Width High	4	-	-	μs
t_{AA}	Clock Low to Data Out Valid	0.05	-	3.45	μs
t_I	Noise Suppression Time	-	-	0.1	μs
t_{BUF}	Time the bus must be free before a new transmission can start	4.7	-	-	μs
$t_{HD.STA}$	Start Hold Time	4	-	-	μs
$t_{SU.STA}$	Start Setup Time	4.7	-	-	μs
$t_{HD.DAT}$	Data In Hold Time	0	-	-	μs
$t_{SU.DAT}$	Data In Setup Time	0.25	-	-	μs
t_R	Inputs Rise Time[1]	-	-	1	μs
t_F	Inputs Fall Time[1]	-	-	0.3	μs
$t_{SU.STO}$	Stop Setup Time	4	-	-	μs
t_{DH}	Data Out Hold Time	0.05	-	-	μs
$t_{SU.WCB}$	WCB pin Setup Time	4	-	-	μs
$t_{HD.WCB}$	WCB pin Hold Time	4	-	-	μs
t_{WR}	Write Cycle Time	-	-	5	ms

Notes: [1] This parameter is ensured by characterization not 100% tested

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Table 3-5 AC Characteristics

（Unless otherwise specified, V_{CC} = 1.7V to 5.5V, T_A = –40°C to 125°C, C_L=100pF, Test Conditions are listed in Notes [2]）

Symbol	Parameter	1.7≤V_{CC}≤5.5			1.7≤V_{CC}≤5.5			Units
		Min.	Typ.	Max.	Min.	Typ.	Max.	
f_{SCL}	Clock Frequency, SCL	-	-	400	-	-	1000	kHz
t_{LOW}	Clock Pulse Width Low	1.3	-	-	0.4	-	-	μs
t_{HIGH}	Clock Pulse Width High	0.6	-	-	0.4	-	-	μs
t_{AA}	Clock Low to Data Out Valid	0.05	-	0.9	0.05	-	0.55	μs
t_I	Noise Suppression Time	-	-	0.1	-	-	0.05	μs
t_{BUF}	Time the bus must be free before a new transmission can start	1.3	-	-	0.5	-	-	μs
$t_{HD.STA}$	Start Hold Time	0.6	-	-	0.25	-	-	μs
$t_{SU.STA}$	Start Setup Time	0.6	-	-	0.25	-	-	μs
$t_{HD.DAT}$	Data In Hold Time	0	-	-	0	-	-	μs
$t_{SU.DAT}$	Data In Setup Time	0.1	-	-	0.1	-	-	μs
t_R	Inputs Rise Time[1]	-	-	0.3	-	-	0.3	μs
t_F	Inputs Fall Time[1]	-	-	0.3	-	-	0.1	μs
$t_{SU.STO}$	Stop Setup Time	0.6	-	-	0.25	-	-	μs
t_{DH}	Data Out Hold Time	0.05	-	-	0.05	-	-	μs
$t_{SU.WCB}$	WCB pin Setup Time	1.2	-	-	0.6	-	-	μs
$t_{HD.WCB}$	WCB pin Hold Time	1.2	-	-	0.6	-	-	μs
t_{WR}	Write Cycle Time	-	-	5	-	-	5	ms

Notes: [1] This parameter is ensured by characterization not 100% tested

[2] AC measurement conditions:

- R_L (connects to V_{CC}): 1.3k (2.5V, 5.5V), 10k (1.7V)
- Input pulse voltages: 0.3 V_{CC} to 0.7 V_{CC}
- Input rise and fall times: ≤50ns
- Input and output timing reference voltages: 0.5V_{CC}

Table 3-6 Reliability Characteristic [1]

Symbol	Parameter	Min.	Typ.	Max.	Unit
EDR [2]	Endurance	1,000,000			Write cycles
DRET [3]	Data retention	100			Years

Note: [1] This parameter is ensured by characterization and is not 100% tested

[2] Under the condition: 25°C, 3.3V, Page mode

[3] Test condition: T_A = 55°C

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Figure 3-1 Bus Timing

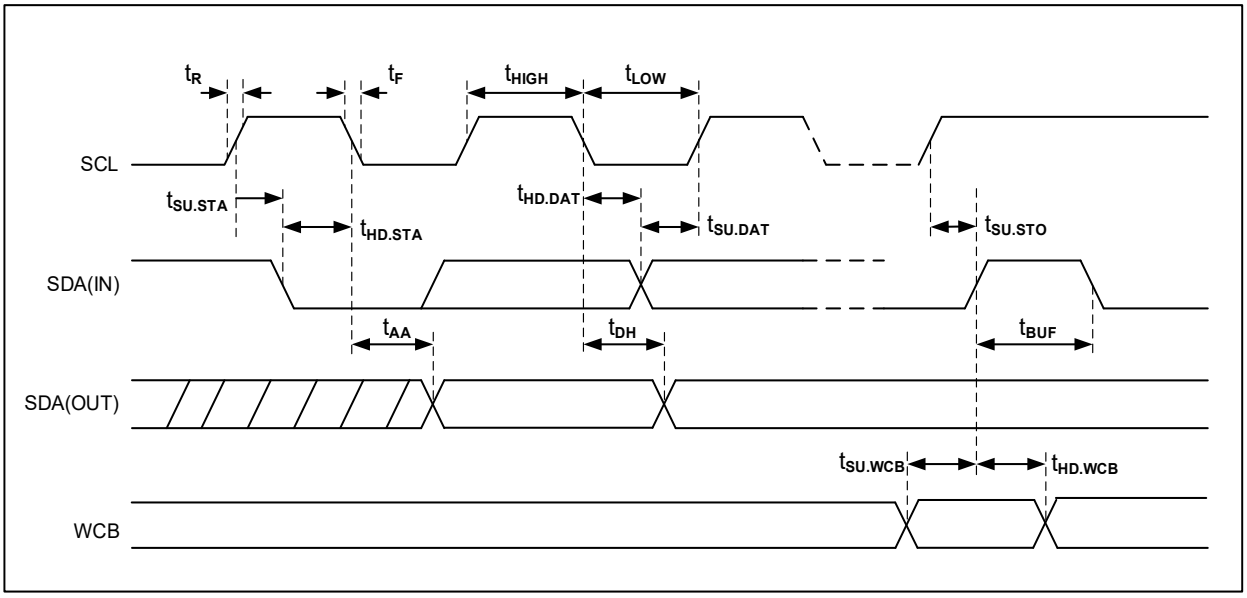
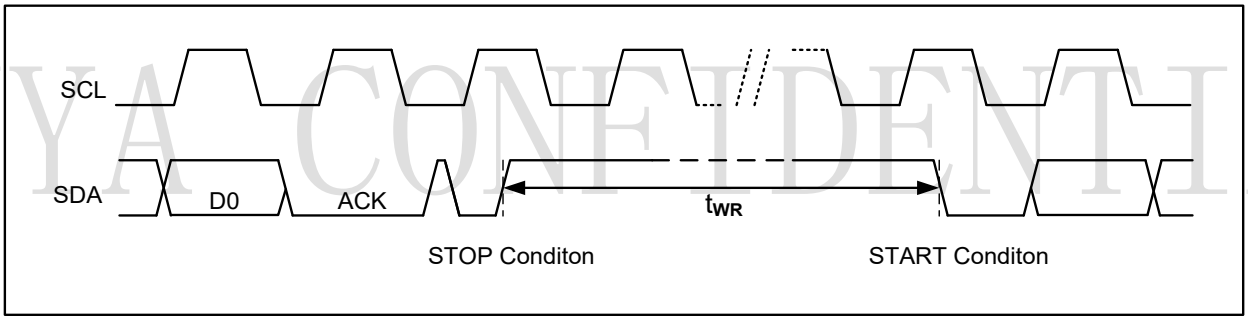


Figure 3-2 Write Cycle Timing



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Note: [1] The write cycle time t_{WR} is the time from a valid stop condition of a write sequence to the end of the internal clear/write cycle.

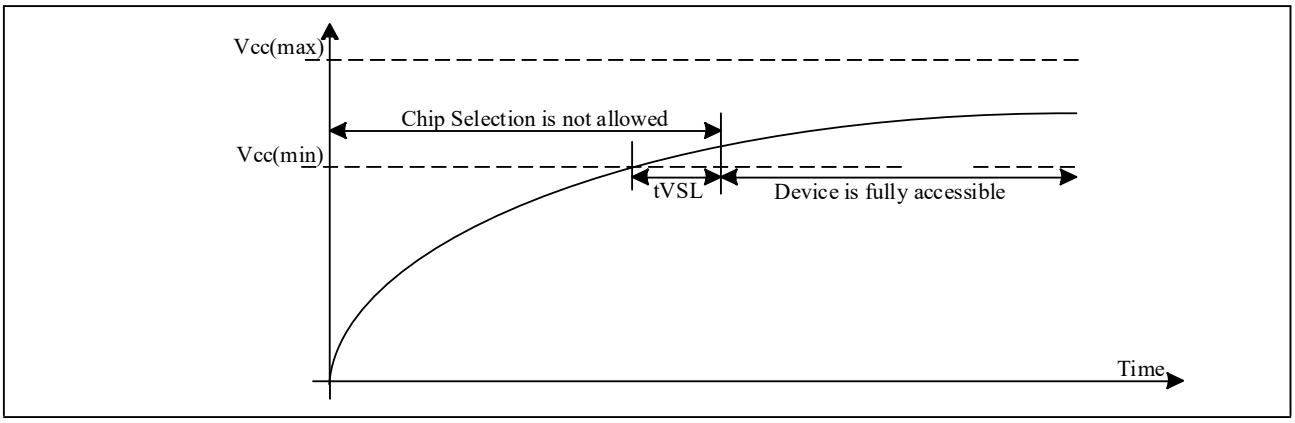
Device Power-Up

The EEPROM has a built-in power-on-reset circuit that initializes itself at the same time during power-on. Unsuccessful initialization may cause a malfunction. To operate the power-on-reset circuit normally, the following conditions must be satisfied to raise the power supply voltage.

When initialization is successfully completed by the power-on-reset circuit, the EEPROM enters the standby status. tVSL is the time required to initialize the EEPROM. No instructions are accepted during this time.

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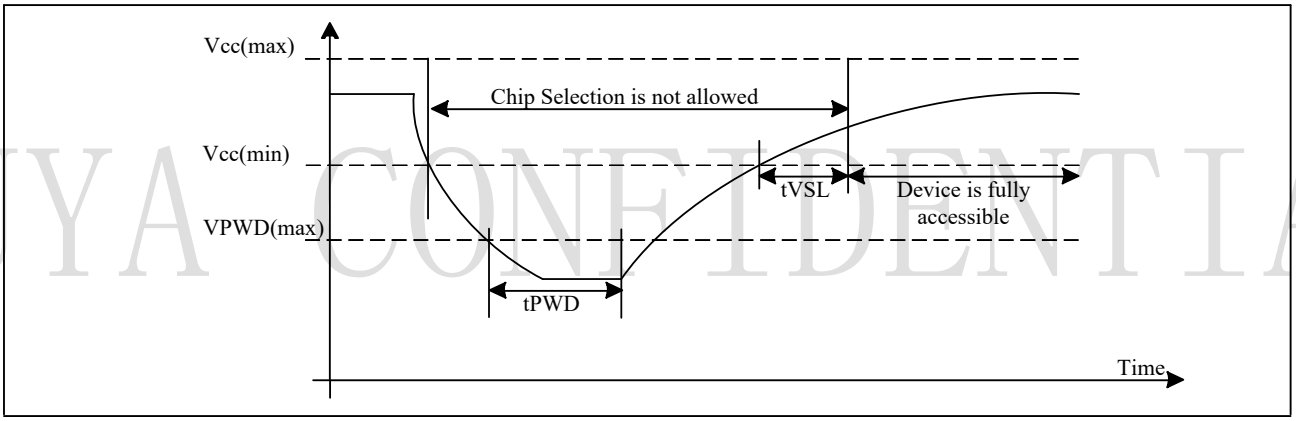
Figure 3-3 Power up Timing



Power Up/Down and Voltage Drop

For Power-down to Power-up operation, the V_{cc} of EEPROM device must below VPWD for at least tPWD timing. Please check the table below for more detail.

Figure 3-4 Power down-up Timing



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Symbol	Parameter	min	max	unit
VPWD	V_{cc} voltage needed to below VPWD for ensuring initialization will occur		0.7	V
tPWD	The minimum duration for ensuring initialization will occur	300		us
tVSL	V_{cc}(min.) to device operation	70		us
tVR	V_{cc} Rise Time	1	500000	us/V

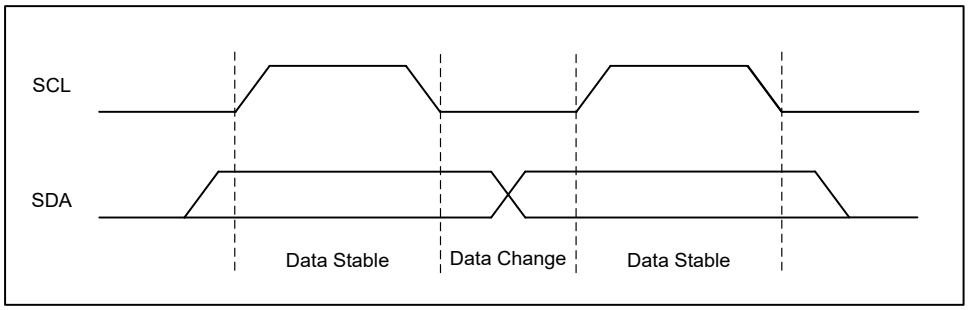
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4. Device Operation

4.1 Data Input

The SDA pin is normally pulled high with an external device. Data on the SDA pin may change only during SCL low time periods (see to Figure 4-1). Data changes during SCL high periods will indicate a start or stop condition as defined below.

Figure 4-1 Data Validity



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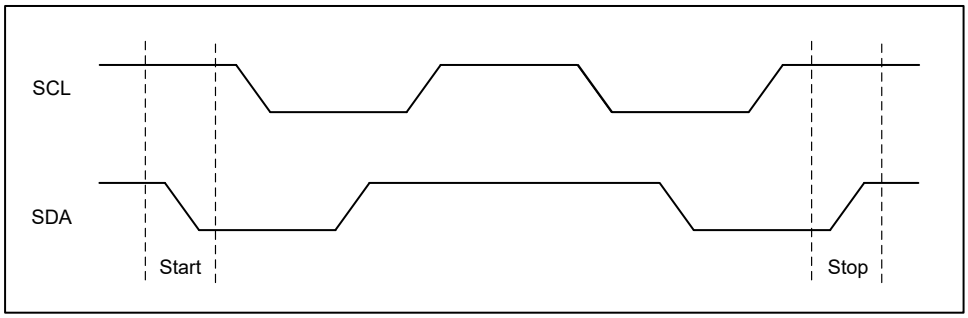
4.2 Start Condition

A high-to-low transition of SDA with SCL high is a start condition which must precede any other command (see to Figure 4-2).

4.3 Stop Condition

A low-to-high transition of SDA with SCL high is a stop condition. After a read sequence, the stop command will place the P24C02A in a standby mode (see Figure 4-2).

Figure 4-2 Start and Stop Definition

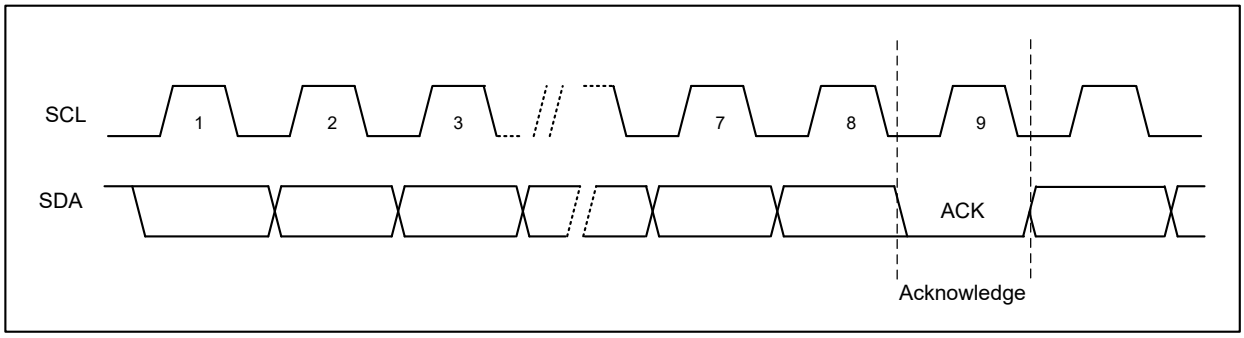


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4.4 Acknowledge (ACK)

All addresses and data words are serially transmitted to and from the P24C02A in 8-bit words. The P24C02A sends a “0” to acknowledge that it has received each word. This happens during the ninth clock cycle.

Figure 4-3 Output Acknowledge



4.5 Standby Mode

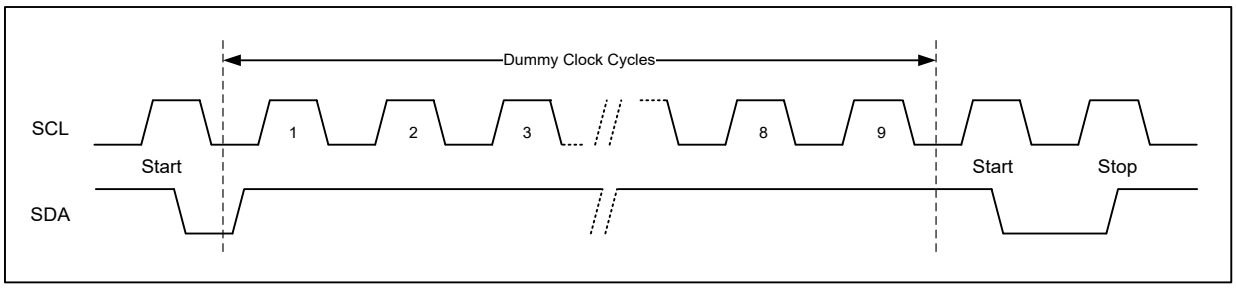
The P24C02A features a low-power standby mode which is enabled: (a) after a fresh power up, (b) after receiving a STOP bit in read mode, and (c) after completing a self-time internal programming operation

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4.6 Soft Reset

After an interruption in protocol, power loss or system reset, any two-wire part can be reset by following these steps: (a) Create a start condition, (b) Clock nine cycles, and (c) create another start bit followed by stop bit condition, as shown below. The device is ready for the next communication after the above steps have been completed.

Figure 4-4 Soft Reset



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4.7 Device Addressing

The P24C02A requires an 8-bit device address word following a start condition to enable the chip for a read or write operation (see table below). The device address word consists of a mandatory one-zero sequence for the first four most-significant bits, as shown.

Table 4-1 Device Address

Access area	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Normal Area	1	0	1	0	E2	E1	E0	R/W

Table 4-2 Word Address

Data	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Normal Area	A7	A6	A5	A4	A3	A2	A1	A0

The E2, E1 and E0 device address bits to allow as many as eight devices on the same bus. These bits must compare to their corresponding hardwired input pins.
The E2, E1 and E0 pins use an internal proprietary circuit that biases them to a logic low condition if the pins are floating.
The eighth bit of the device address is the read/write operation select bit. A read operation is initiated if this bit is high and a write operation is initiated if this bit is low. Upon a compare of the device address, the Chip will output a zero. If a compare is not made, the device will return to a standby state.

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4.8 Data Security

P24C02A has a hardware data protection scheme that allows the user to write protect the whole memory when the WCB pin is at Vcc.

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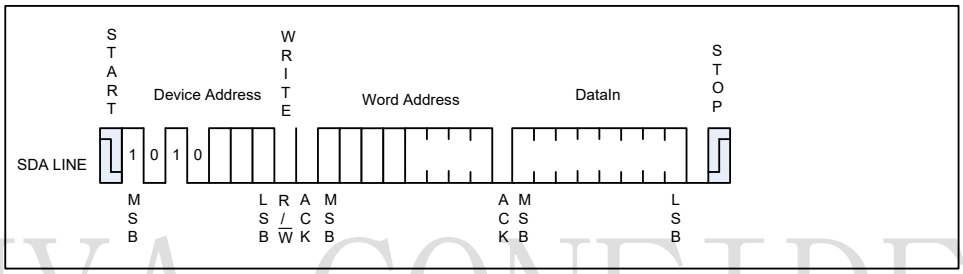
5. Instructions

5.1 Write Operations

5.1.1 Byte Write

A write operation requires an 8-bit data word address following the device address word and acknowledgment. Upon receipt of this address, the P24C02A will again respond with a “0” and then clock in the first 8-bit data word. Following receipt of the 8-bit data word, the P24C02A will output a “0” and the addressing device, such as a microcontroller, must terminate the write sequence with a stop condition. And then the P24C02A enters an internally timed write cycle, all inputs are disabled during this write cycle and the P24C02A will not respond until the write is complete (see Figure 5-1).

Figure 5-1 Byte Write

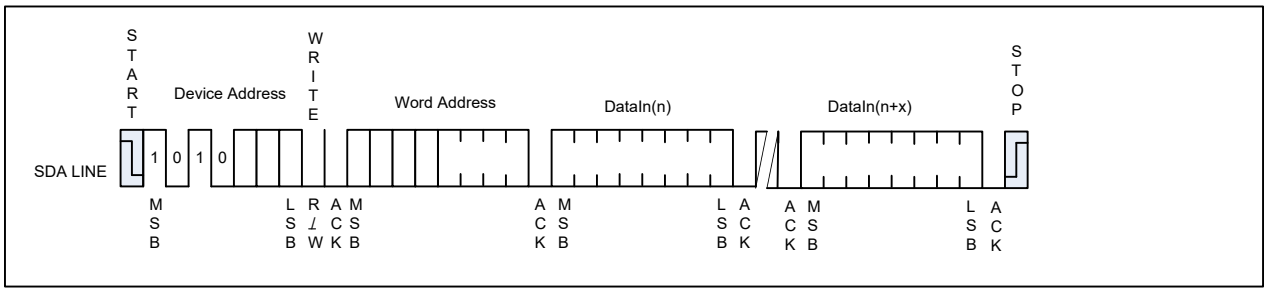


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5.1.2 Page Write

A page write is initiated the same as a byte write, but the master does not send a stop condition after the first data word is clocked in. Instead, after the P24C02A acknowledges receipt of the first data word, the master can transmit more data words. The P24C02A will respond with a “0” after each data word received. The microcontroller must terminate the page write sequence with a stop condition.

Figure 5-2 Page Write



The lower three bits of the data word address are internally incremented following the receipt of each data word. The higher data word address bits are not incremented, retaining the memory page row location. When the word address, internally generated, reaches the page boundary, the following byte is placed at the beginning of the same page. If more than eight data words are transmitted to the P24C02A, the data word address will roll-over, and previous data will be overwritten. The address roll-over during write is from the last byte of the current page to the first byte of the same page.

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5.1.3 Acknowledge Polling

Once the internally timed write cycle has started and the P24C02A inputs are disabled, acknowledge polling can be initiated. This involves sending a start condition followed by the device address word. The read/write bit is representative of the operation desired. Only if the internal write cycle has completed will the P24C02A respond with a “0”, allowing the read or write sequence to continue.

5.2 Read Operations

Read operations are initiated the same way as write operations with the exception that the read/write select bit in the device address word is set to “1”. There are three read operations: Current Address Read; Random Address Read and Sequential Read.

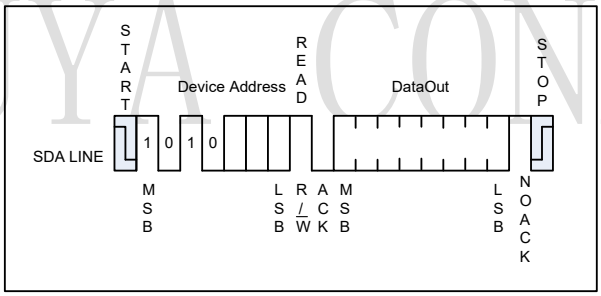
5.2.1 Current Address Read

The internal data word address counter maintains the last address accessed during the last read or write operation, incremented by one. This address stays valid between operations as long as the chip power is maintained. The address roll-over during read is from the last byte of the last memory page to the first byte of the first page.

Once the device address with the read/write select bit set to “1” is clocked in and acknowledged by the P24C02A, the current address data word is serially clocked out. The microcontroller does not respond with an input “0” but does generate a following stop condition (see Figure 5-3).

Figure 5-3 Current Address Read

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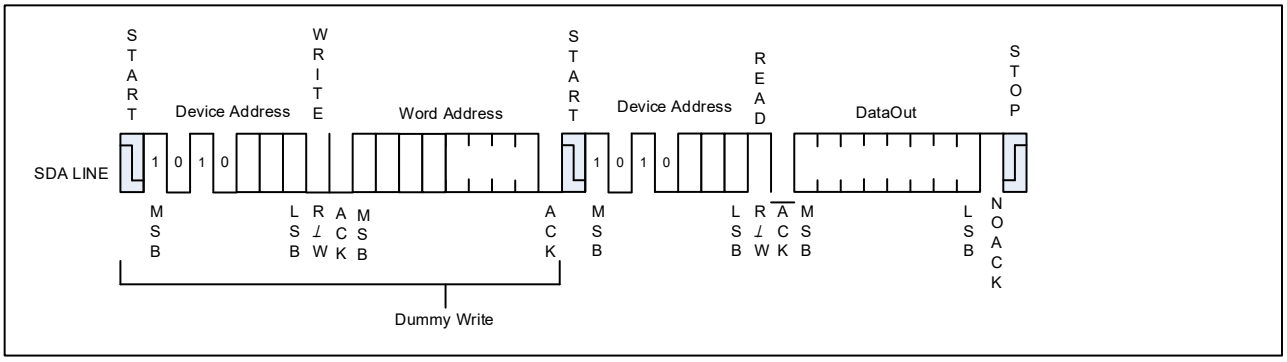


5.2.2 Random Read

A Random Read requires a “dummy” byte write sequence to load in the data word address. Once the device address word and data word address are clocked in and acknowledged by the P24C02A, the microcontroller must generate another start condition. The microcontroller now initiates a Current Address Read by sending a device address with the read/write select bit high. The P24C02A acknowledges the device address and serially clocks out the data word. The microcontroller does not respond with a “0” but does generate a following stop condition (see Figure 5-4).

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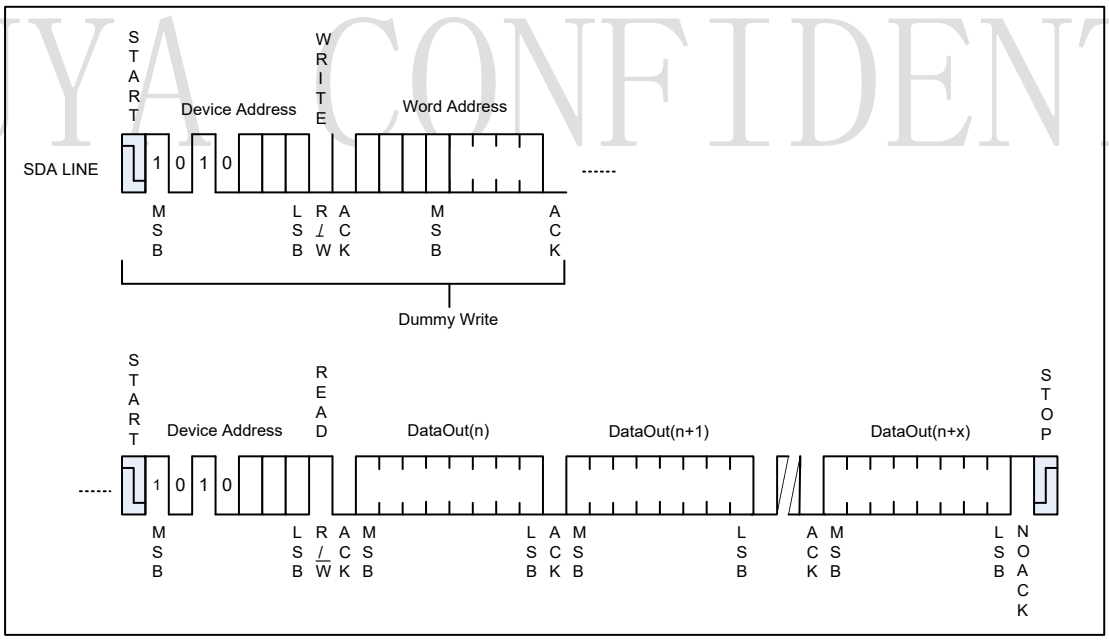
Figure 5-4 Random Read



5.2.3 Sequential Read

Sequential Reads are initiated by either a Current Address Read or a Random Address Read. After the microcontroller receives a data word, it responds with acknowledge. As long as the P24C02A receives acknowledge, it will continue to increment the data word address and serially clock out sequential data words. When the memory address limit is reached, the data word address will roll-over and the Sequential Read will continue. The Sequential Read operation is terminated when the microcontroller does not respond with a “0” but does generate a following stop condition (see Figure 5-5)

Figure 5-5 Sequential Read



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6. Ordering Code Detail

Example:

P 2 4 C 02 A – S S H – M I R

Company Designator

P = Puya Semiconductor

Product Series Name

24C = I2C-compatible Interface EEPROM

Device Densitv

02 = 2K bits

Device Version

A = Version A

Package Option

DP: PDIP8 SS: SOP8(150mil)
TS: TSSOP8 UN: UDFN8
WF: WAFER MS: MSOP8
ST: SOT23-5 UX: UDFN8
TO: TSOT23-5

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Plating Technology

H: RoHS Compliant, Halogen-free, Antimony-free

Operation Voltage

M: 1.7~5.5V
N: 1.8~5.5V
D: 2.5~5.5V

Device Grade

I: -40~85C
K: -40~105C
E: -40~125C

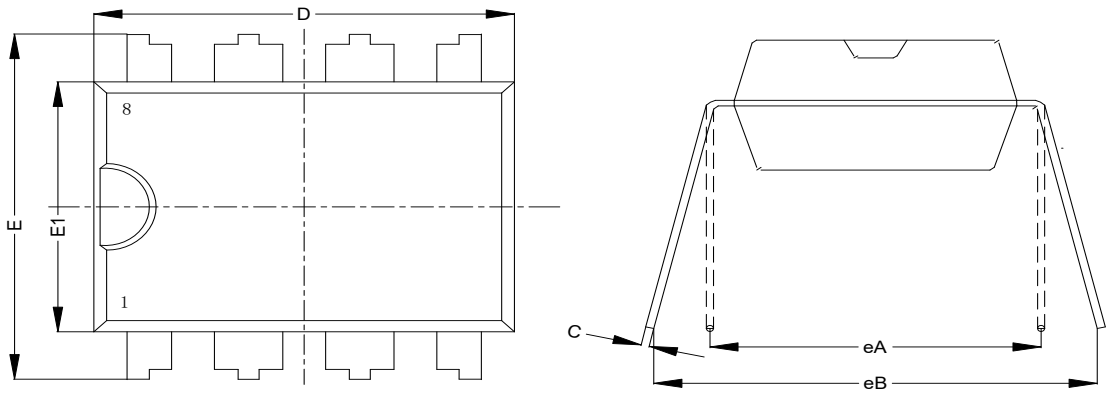
Shipping Carrier Option

W: WAFER
T: TUBE
R: TAPE& REEL

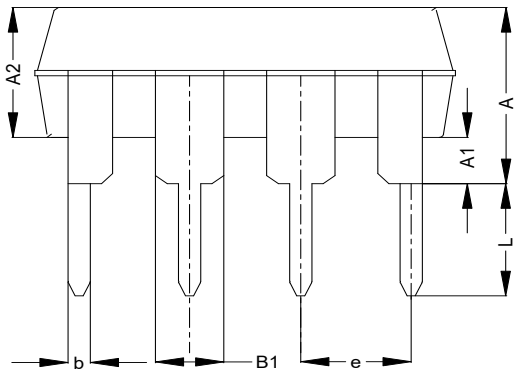
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7. Package Information

7.1 PDIP8



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Common Dimensions
(Unit of Measure=millimeters)

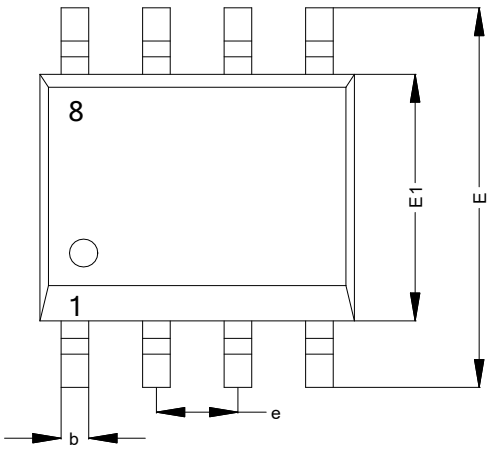
Symbol	Min	Typ	Max
A	3.600	-	5.330
A1	0.380	-	-
A2	2.920	3.300	4.950
b	0.360	-	0.570
B1	1.140	1.520	1.780
c	0.200	0.250	0.360
D	9.000	-	10.000
E	7.320	-	8.260
E1	6.100	6.350	6.600
e	2.540BSC		
eA	7.620REF		
eB	-	-	10.920
L	2.920	-	3.810

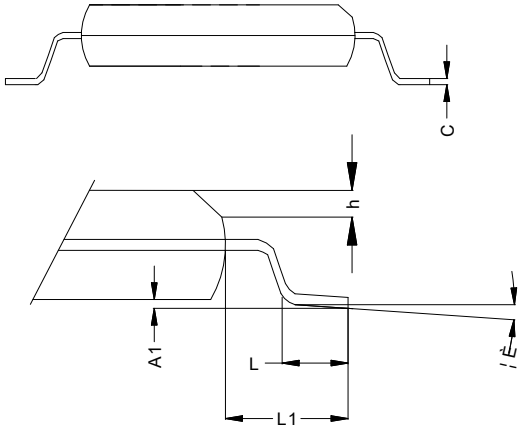
Note：1. Dimensions are not to scale

	TITLE	DRAWING NO.	REV
PUYA	Puya PDIP8 POD	QRPD-0021	1.2

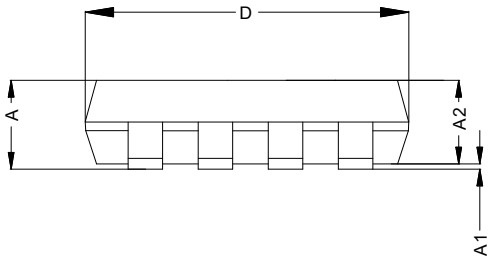
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7.2 SOP8(150mil)





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Common Dimensions

(Unit of Measure=millimeters)

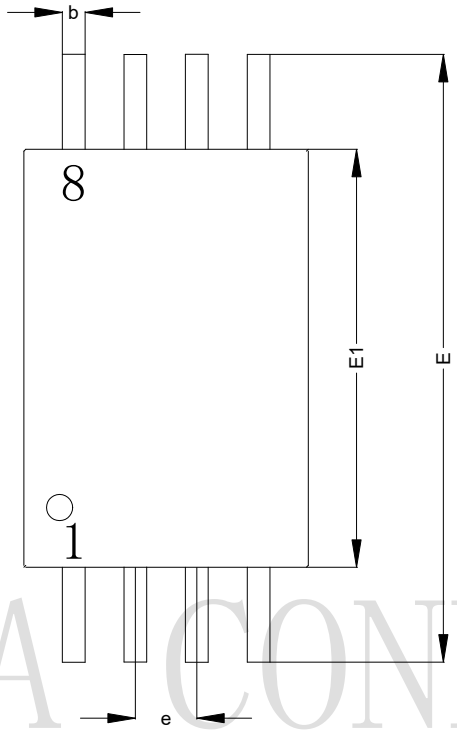
Symbol	Min	Typ	Max
A	1.350	-	1.750
A1	0.100	-	0.250
A2	1.250	-	-
b	0.310	-	0.510
c	0.170	-	0.250
D	4.800	4.900	5.000
E	5.800	6.000	6.200
E1	3.800	3.900	4.000
e	1.270BSC		
L	0.400	-	0.900
L1	1.050REF		
¦È	0	-	8¡ã
h	0.250	-	0.500

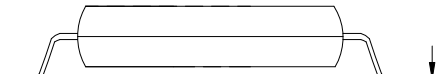
Note£ ¶. Dimensions are not to scale

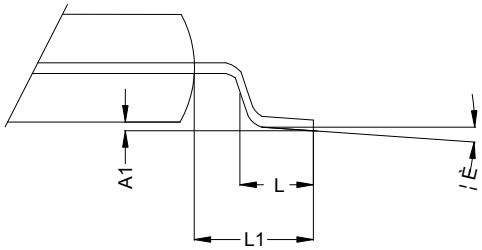
PUYA	TITLE Puya SOP8£ ¨150mil£ ©OD	DRAWING NO. QRPD-0004	REV 1.2

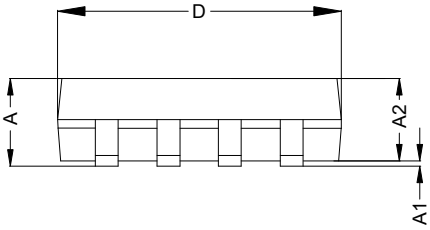
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7.3 TSSOP8









Common Dimensions
(Unit of Measure=millimeters)

Symbol	Min	Typ	Max
A	-	-	1.200
A1	0.050	-	0.150
A2	0.800	1.000	1.050
b	0.190	-	0.300
c	0.090	-	0.200
D	2.900	3.000	3.100
E	6.200	6.400	6.600
E1	4.300	4.400	4.500
e	-	0.650	-
L	0.450	-	0.750
L1	-	1.000	-
¦È	0	-	8¡ã

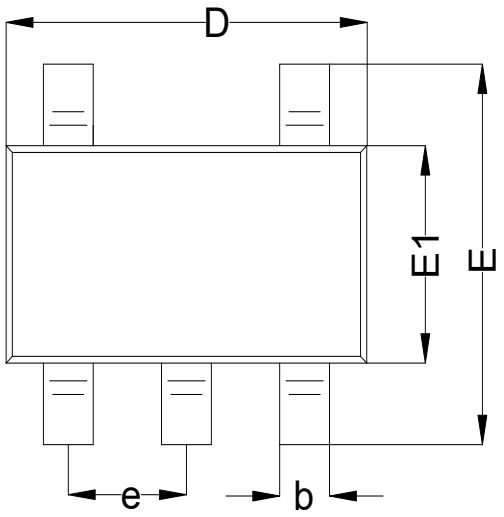
Note：1. Dimensions are not to scale

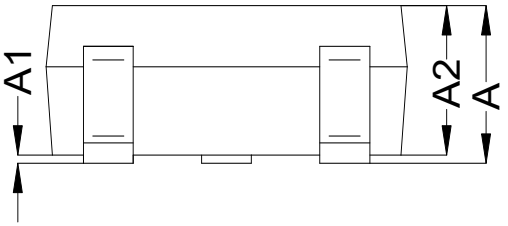
	TITLE	DRAWING NO.	REV
PUYA	PUYA TSSOP8 POD	QRPD-0019	1.1

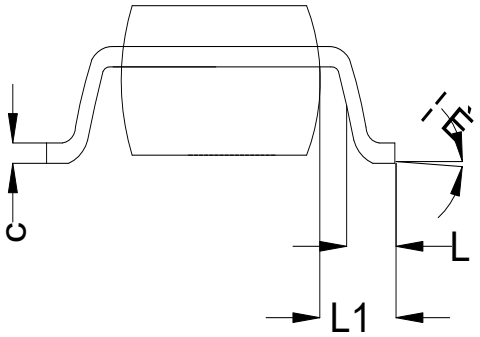
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7.4 SOT23-5







Common Dimensions
(Unit of Measure=millimeters)

Symbol	Min	Typ	Max
A	1.050	-	1.250
A1	0.000	-	0.130
A2	1.000	1.100	1.200
b	0.270	-	0.500
c	0.100	-	0.230
D	2.820	2.920	3.020
E	2.600	2.800	3.000
E1	1.500	1.600	1.700
e	0.950BSC		
L	0.300	-	0.600
L1	0.600REF		
¦È	0	-	8¡ã

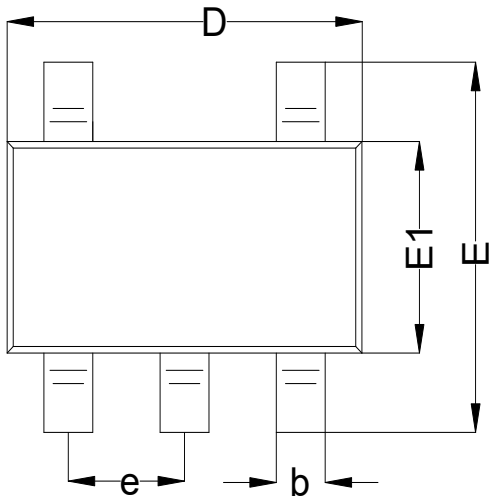
Note： Dimensions are not to scale

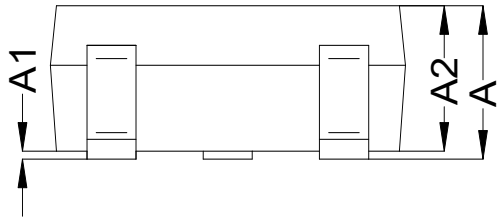
	TITLE	Drawing No.	REV
PUYA	Puya SOT23-5 POD	QRPD-0026	1.0

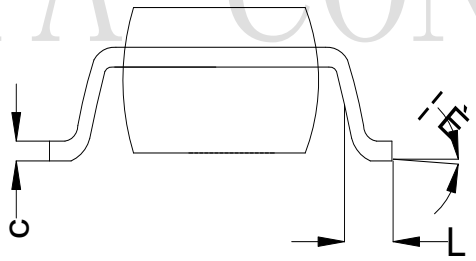
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7.5 TSOT23-5







Common Dimensions

(Unit of Measure=millimeters)

Symbol	Min	Typ	Max
A	-	-	0.950
A1	0.000	-	0.100
A2	0.700	-	0.850
b	0.350	-	0.500
c	0.100	-	0.200
D	2.800	2.910	3.020
E	2.600	2.800	3.000
E1	1.500	1.600	1.700
e	0.950BSC		
L	0.300	-	0.600
¦È	0	-	8¡ã

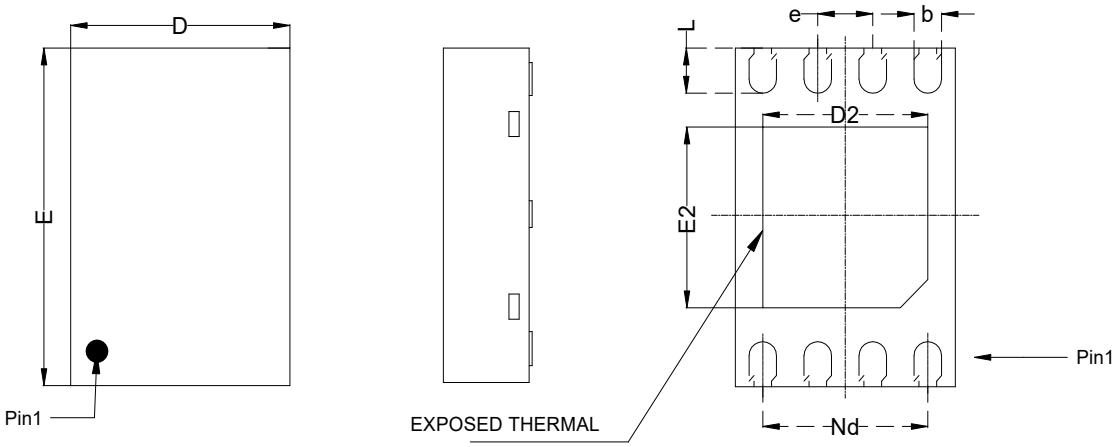
Note： Dimensions are not to scale

	TITLE	Drawing No.	REV
PUYA	Puya TSOT23-5 POD	QRPD-0027	1.0

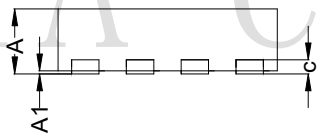
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7.6 UDFN8(UN)



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SIDE VIEW

Common Dimensions

(Unit of Measure=millimeters)

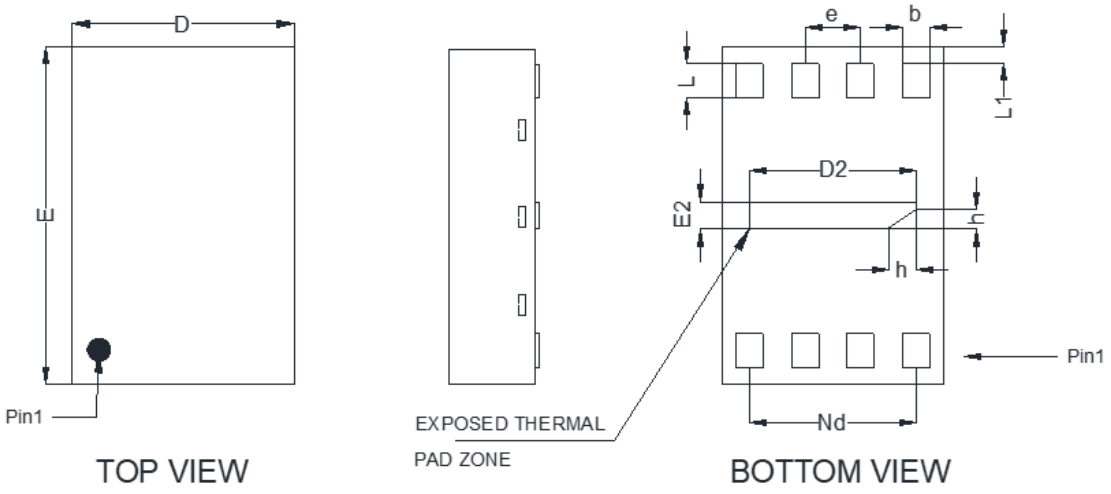
Symbol	Min	Typ	Max
A	0.45	0.50	0.55
A1	0.00	0.02	0.05
b	0.18	0.25	0.30
D	1.90	2.00	2.10
D2	1.40	1.50	1.60
E	2.90	3.00	3.10
E2	1.50	1.60	1.70
e	0.50BSC		
L	0.30	0.40	0.50
c	0.10	0.15	0.20
Nd	1.50BSC		

Note：1. Dimensions are not to scale

	TITLE	DRAWING NO.	REV
PUYA	Puya DFN8L 2x3X0.5-0.5PITCH POD	QRPD-0023	1.0

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7.7 UDFN8(UX)





SIDE VIEW

Common Dimensions

(Unit of Measure=millimeters)

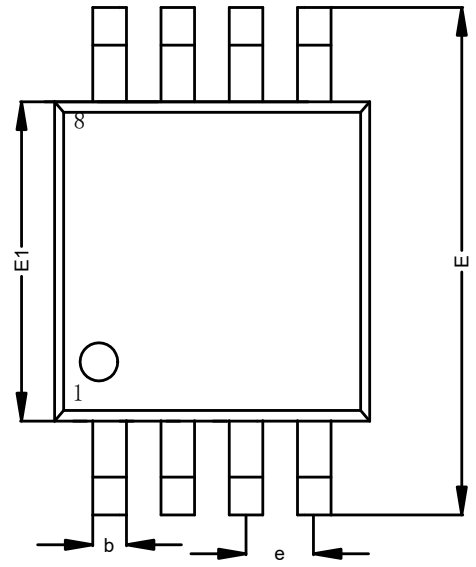
Symbol	Min	Typ	Max
A	0.50	0.55	0.60
A1	0.00	0.02	0.05
b	0.18	0.25	0.30
D	1.90	2.00	2.10
D2	1.50	1.60	1.70
E	2.90	3.00	3.10
E2	0.10	0.20	0.30
e		0.50BSC	
L	0.30	0.35	0.40
h	0.05	0.15	0.25
Nd		1.50BSC	
L1	0.05	0.10	0.15
c	0.10	0.15	0.20

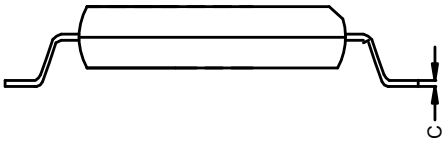
Note：1. Dimensions are not to scale

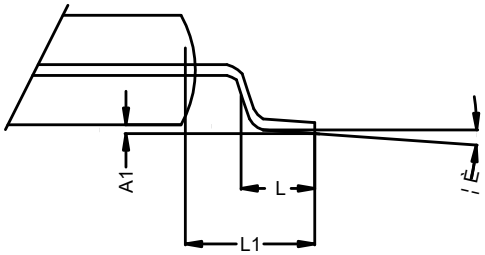
	TITLE	DRAWING NO.	REV
PUYA	USON8L(0203X0.55-0.5)	UX-8	C

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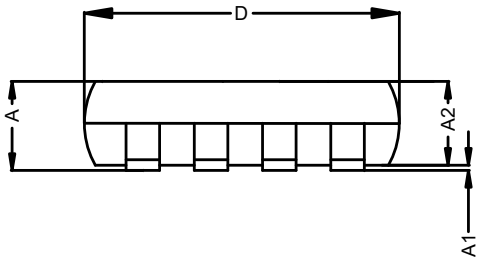
7.8 MSOP8







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Common Dimensions
(Unit of Measure=millimeters)

Symbol	Min	Typ	Max
A	-	-	1.100
A1	0.050	-	0.150
A2	0.750	0.850	0.950
b	0.280	-	0.370
c	0.150	-	0.200
D	2.900	3.000	3.100
E	4.700	4.900	5.100
E1	2.900	3.000	3.100
e	-	0.650	-
L	0.400	-	0.800
L1	-	0.950	-
¦È	0	-	8¡ã

Note：1. Dimensions are not to scale

	TITLE	DRAWING NO.	REV
PUYA	Puya MSOP8 POD	QRPD-0020	1.0

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8. Revision History

Version	Content	Date
V 0.2	Initial Release	2016-01-02
V 0.5	Add UDFN to the datasheet	2016-03-25
V 1.0	Add SOT23-5 to the datasheet	2016-05-31
V 1.1	Remove P24C02A–UI from the datasheet	2016-06-18
V 1.2	Update ESD capability	2016-06-30
V 1.3	Update all package POD	2016-09-19
V 1.4	Add TSOT23-5 Package	2017-02-20
V 1.5	Support NK series product	2020-04-08
V 1.6	Update UDFN POD and some descriptions	2021-05-12
V 1.7	Add UDFN(UX) and MSOP POD	2021-11-02
V 1.8	Add Device Power up/ Power down description	2022-03-07
V 1.9	(1) Update parameter of V_{IL} (2) Update Features	2023-03-22
V 2.0	Add Table3-4 100Khz AC Characteristics	2024-06-13
V2.1	(1) Update PDIP8 POD (2) Update SOP8(150mil) POD (3) Update TSSOP8 POD (4) Update SOT23-5 POD (5) Update TSOT23-5 POD (6) Update feature description (7) Update I_{CC1} and I_{CC2} of DC Characteristics	2025-06-16

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