SK hynix e-NAND Product Family
eMMC5.1 Compatible

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Revision History

Revision No.	History	Date	Remark
1.0	- 1st Official release	May. 20, 2015	
1.1	- Change 'FFU argument' value in 'send FW to device' from 0x6600 to 0xFFFAFFF0 (p.19)	May. 22, 2015	
1.2	- Add 'Vccq=2.7V ~ 3.6V' (p.4) - Change 'The last value of PNM' from '1' to '2' (p.65)	May. 28, 2015	
1.3	- Modify VENDOR_PROPRIETARY_HEALTH_REPORT[301-270] (p.22) - Change the typo : bit[0] value of Cache Flush Policy (p.33) - Modify 4.2.7 RPMB throughput improvement (p.43) - Change 'PON Busy Time' (p.63) - Modify CSD/EXT_CSD values of 64GB (WP_GRP_SIZE, etc.) (p.68 ~ 73)	Jul. 07, 2015	
1.4	- Modify the Typo of 64GB PNM Value (p.65) - Modify the value of TRIM multiplier (p.69)	Nov. 13, 2015	
1.5	- Modification of power value (p.56) - Modification of PSN value and usage guidance	Apr. 20, 2016	
1.6	- Added 8GB Information - Modification of PKG Ball Size Value	Jul. 21, 2016	

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1. Introduction

1.1 General Description

SK hynix e-NAND consists of NAND flash and MMC controller.
e-NAND has the built-in intelligent controller which manages interface protocols, wear leveling, bad block management, garbage collection, and ECC. e-NAND protects the data contents from the host sudden power off failure.
e-NAND is compatible with JEDEC standard eMMC5.1 specification.

1.2 Product Line-up

Density	Part Number	NAND Stack	PKG Size (mm)	Package Type
8GB	H26M41208HPR	64Gb x 1	11.5x13x0.8	153FBGA
16GB	H26M52208FPR	64Gb x 2	11.5x13x0.8	
32GB	H26M64208EMR	64Gb x 4	11.5x13x1.0	
64GB	H26M78208CMR	64Gb x 8	11.5x13x1.0	

1.3 Key Features

- **eMMC5.1 compatible**
  (Backward compatible to eMMC4.5&eMMC5.0)

- **Bus mode**
  - Data bus width : 1bit(default), 4bits, 8bits
  - Data transfer rate: up to 400MB/s (HS400)
  - MMC I/F Clock frequency : 0~200MHz
  - MMC I/F Boot frequency : 0~52MHz

- **Operating Voltage Range**
  - V_{cc} (NAND) : 2.7V - 3.6V
  - V_{ccq} (Controller) : 1.7V - 1.95V / 2.7V ~ 3.3V

- **Temperature**
  - Operation (-25℃ ~ +85℃)
  - Storage without operation (-40℃ ~ +85℃)

- **Others**
  - This product is compliance with the RoHS directive

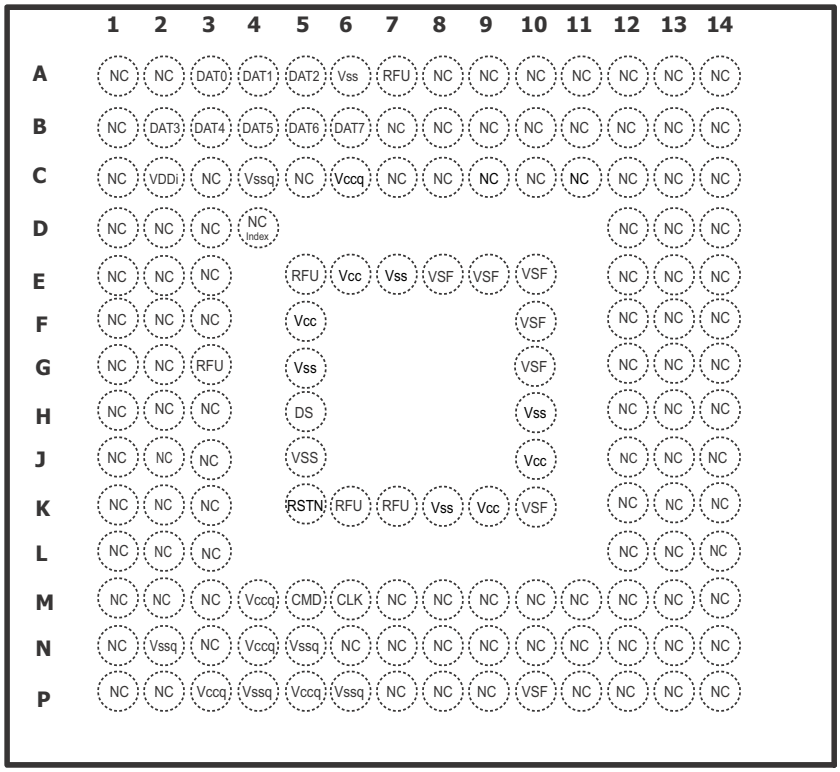
- **Supported Features**
  - HS400, HS200
  - HPI, BKOPS, **BKOP operation control**
  - Packed CMD, **CMD queuing**
  - Cache, **Cache barrier, Cache flushing report**
  - Partitioning, RPMB, RPMB throughput improve
  - Discard, Trim, Erase, Sanitize
  - Write protect, Secure write protection
  - Lock/Unlock
  - PON, Sleep/Awake
  - Reliable Write
  - Boot feature, Boot partition
  - HW/SW Reset
  - Field Firmware Update
  - Configurable driver strength
  - Health(Smart) report
  - Production state awareness
  - Secure removal type
  - Data Strobe pin, **Enhanced data strobe**

  (Bold features are added in eMMC5.1)

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2. Package Configurations

2.1 Pin connection



[Figure 1] FBGA153 Package Connection (Top view through Package)

Pin number	Name	Pin number	Name	Pin number	Name	Pin number	Name
A3	DAT0	**C4**	V_{ssq}	**G10**	VSF	**M5**	CMD
A4	DAT1	**C6**	V_{ccq}	**H5**	DS	**M6**	CLK
A5	DAT2	**E6**	V_{cc}	**H10**	V_{ss}	**N2**	V_{ssq}
A6	V_{ss}	**E7**	V_{ss}	**J5**	V_{ss}	**N4**	V_{ccq}
B2	DAT3	**E8**	VSF	**J10**	V_{cc}	**N5**	V_{ssq}
B3	DAT4	**E9**	VSF	**K5**	RSTN	**P3**	V_{ccq}
B4	DAT5	**E10**	VSF	**K8**	V_{ss}	**P4**	V_{ssq}
B5	DAT6	**F5**	V_{cc}	**K9**	V_{cc}	**P5**	V_{ccq}
B6	DAT7	**F10**	VSF	**K10**	VSF	**P6**	V_{ssq}
C2	VDDi	**G5**	V_{ss}	**M4**	V_{ccq}	**P10**	VSF

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Name	Type	Ball No.	Description
CLK	Input	M6	Clock: Each cycle directs a 1-bit transfer on the command and DAT lines.
CMD	Input	M5	Command: A bidirectional channel used for device initialization and command transfers. Command has two operating modes: 1) Open-drain for initialization. 2) Push-pull for fast command transfer.
DAT0	I/O	A3	Data I/O0: Bidirectional channel used for data transfer.
DAT1	I/O	A4	Data I/O1: Bidirectional channel used for data transfer.
DAT2	I/O	A5	Data I/O2: Bidirectional channel used for data transfer.
DAT3	I/O	B2	Data I/O3: Bidirectional channel used for data transfer.
DAT4	I/O	B3	Data I/O4: Bidirectional channel used for data transfer.
DAT5	I/O	B4	Data I/O5: Bidirectional channel used for data transfer.
DAT6	I/O	B5	Data I/O6: Bidirectional channel used for data transfer.
DAT7	I/O	B6	Data I/O7: Bidirectional channel used for data transfer.
RSTN	Input	K5	Reset signal pin
V_{cc}	Supply	E6,F5,J10,K9	V_{cc}: Flash memory I/F and Flash memory power supply.
V_{ccq}	Supply	C6,M4,N4,P3,P5	V_{ccq}: Memory controller core and MMC interface I/O power supply.
Vss	Supply	A6,E7,G5,H10,J5,K8	V_{ss}: Flash memory I/F and Flash memory ground connection.
Vssq	Supply	C4,N2,N5,P4,P6	V_{ssq}: Memory controller core and MMC I/F ground connection
VDDi		C2	VDDi: Connect 0.1uF capacitor from VDDi to ground.
DS	Out put	H5	DS: Data Strobe
VSF	Supply	E8,E9,E10,F10, G10, K10, P10	VSF: Vendor Specific Function SK hynix use E9, E10 Pin as VSF Pin
RFU	Reserved for future use		

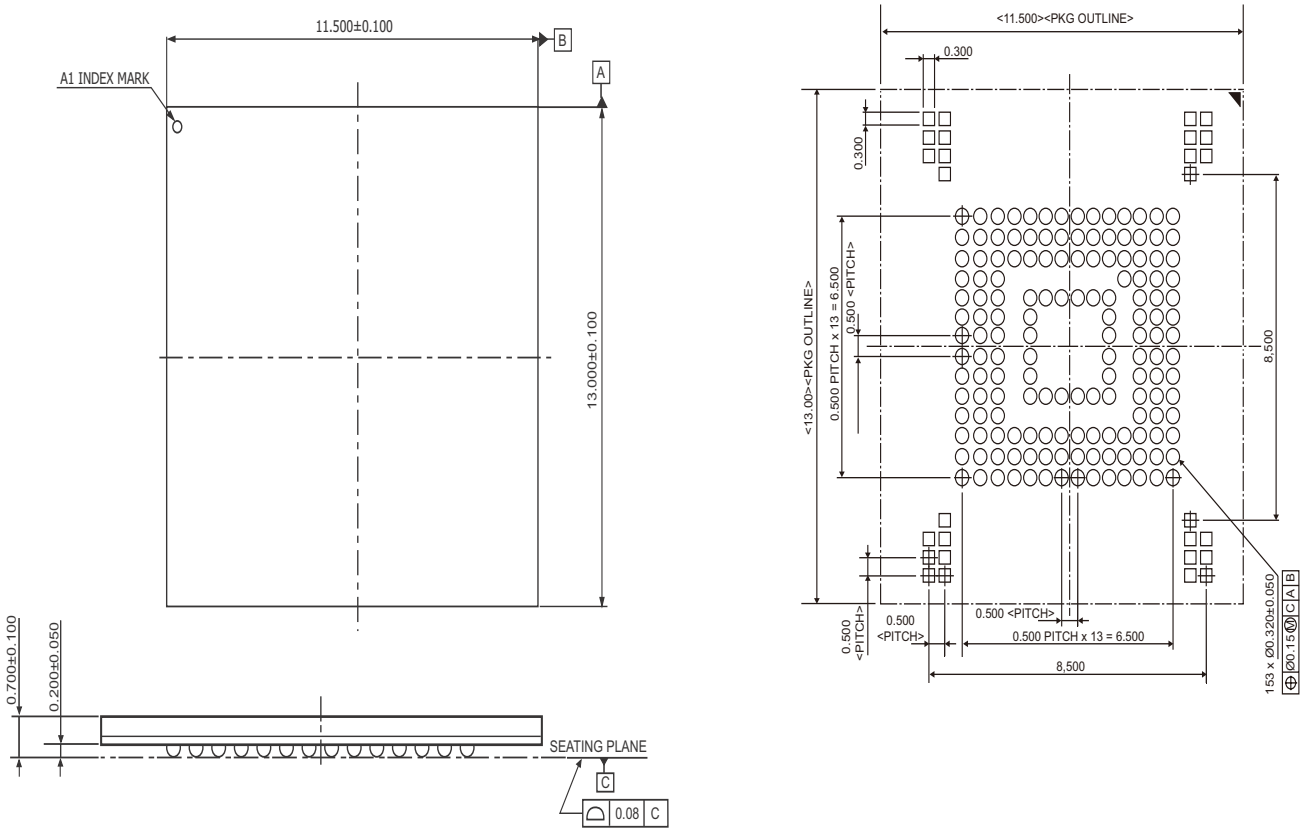
[Table 1] FBGA153 Ball Description

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2.2 Package Mechanical Drawing

2.2.1 11.5mm x13.0mm x0.8mm

Top view **Bottom view**

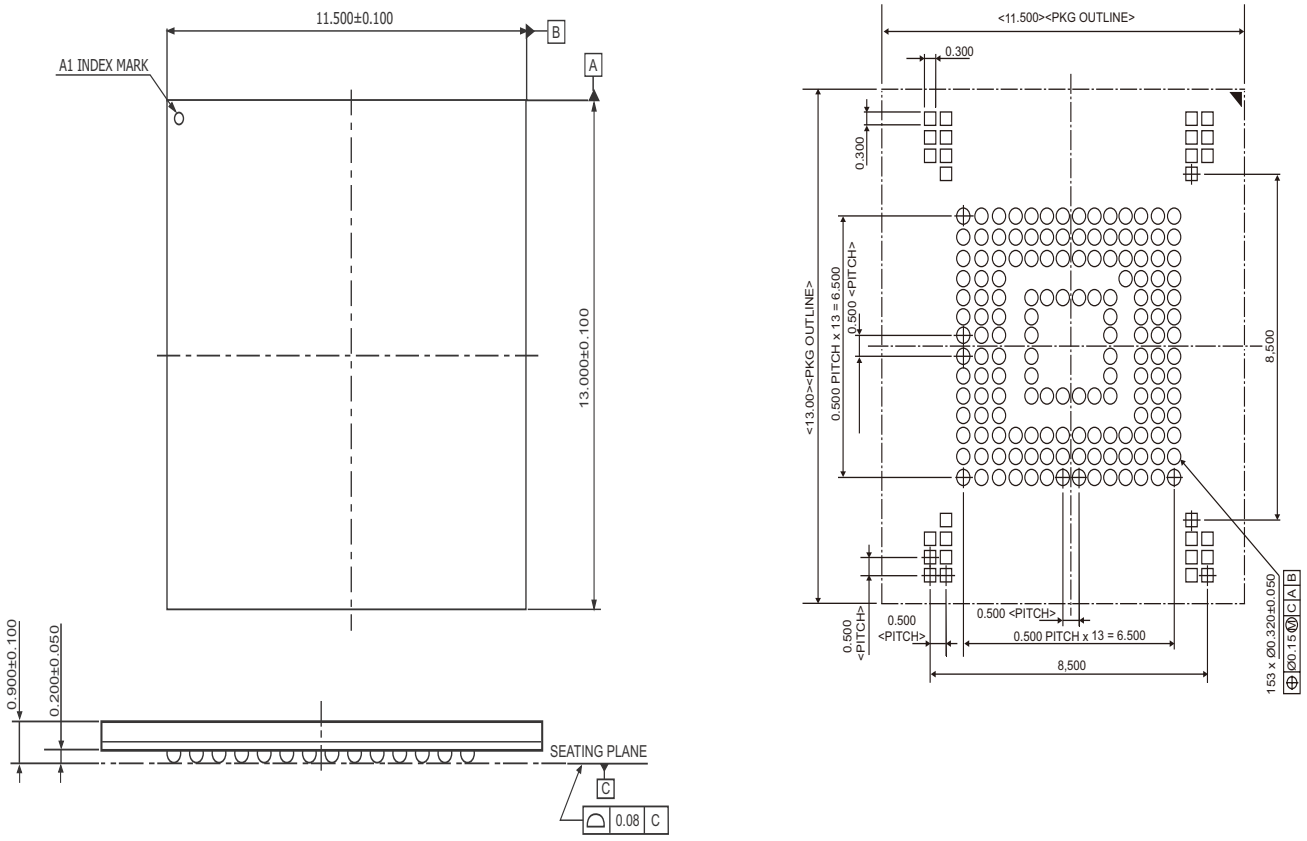


[Figure 2] 11.5mm x 13.0mm x 0.8mm Package dimension

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2.2.2 11.5mm x13.0mm x1.0mm

Top view **Bottom view**



[Figure 3] 11.5mm x13.0mm x 1.0mm Package dimension

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3. e-NAND Characteristics

3.1 Performance

Density	Sequential Write (MB/s)	Sequential Read (MB/s)
8GB (SDP)	35	200
16GB (DDP)	70	280
32GB (QDP)	140	280
64GB (ODP)	140	280

- Tool : Device level
- eMMC I/F speed : HS400
- Seq. chunk size : 512KB
- Adapted feature : Cache on
- Not 100% tested

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3.2 Power

3.2.1 Active Power Consumption During Operation

Density		I_{cc}	I_{ccq}
8GB (SDP)	Avg (mA)	100	130 (HS200) 140 (HS400)
	Peak (mA)	200	200 (HS200) 230 (HS400)
16GB (DDP)	Avg (mA)	100	130 (HS200) 140 (HS400)
	Peak (mA)	200	200 (HS200) 230 (HS400)
32GB (QDP)	Avg (mA)	180	130 (HS200) 140 (HS400)
	Peak (mA)	300	200 (HS200) 230 (HS400)
64GB (ODP)	Avg (mA)	180	130 (HS200) 140 (HS400)
	Peak (mA)	300	200 (HS200) 230 (HS400)

- Temperature : 25℃
- Average current consumption : over a period of 100ms
- Peak current consumption : averaged over a period of 20us
- Vcc : 3.3V
- Vccq : 1.8V
- Not 100% tested

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3.2.2 Low Power Mode (Idle)

Density	Room Temperature (25℃)		Hot Temperature (85℃)	
	I_{cc}	I_{ccq}	I_{cc}	I_{ccq}
8GB (SDP)	Typ. 50uA	Typ. 150uA	Max. 200uA	Max. 650uA
16GB (DDP)	Typ. 100uA		Max. 300uA	
32GB (QDP)	Typ. 200uA		Max. 400uA	
64GB (ODP)	Typ. 400uA		Max. 500uA	

- In Standby Power mode, CTRL V_{ccq} & NAND V_{cc} power supply is switched on
- No data transaction period before entering sleep status
- Not 100% tested.

3.2.3 Low Power Mode (CMD5 Sleep)

Density	Room Temperature (25℃)		Hot Temperature (85℃)	
	I_{cc}	I_{ccq}	I_{cc}	I_{ccq}
8GB (SDP)	0	Typ. 150uA	0	Max. 650uA
16GB (DDP)				
32GB (QDP)				
64GB (ODP)				

- In Sleep state, triggered by CMD5, NAND V_{cc} power supply is switched off (CTRL V_{ccq} on)
- Temperature : 25℃
- Not 100% tested.

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4. e-NAND New features (eMMC5.0 and eMMC5.1)

4.1 eMMC5.0 New features

4.1.1 HS400 mode

e-NAND supports HS400 signaling to achieve a bus speed of 400MB/s via a 200MHz DDR clock frequency. HS400 mode supports only 8-bit bus width and the 1.8V V_{ccq}. Due to the speed, the host may need to have an adjustable sampling point to reliably receive the incoming data (Read Data and CRC Response) with DS pin. e-NAND supports up to 5 Driver Strength.

Driver type values	Support	Nominal Impedance	Approximated driving capability compared to Type_0	Remark
0	Mandatory	50Ω	x 1	Default Driver Type. Supports up to 200MHz operation.
1	Optional	33Ω	x 1.5	Supports up to 200MHz operation.
2		66Ω	x 0.75	The weakest driver that supports up to 200MHz operation.
3		100Ω	x 0.5	For low noise and low EMI systems. Maximal operating frequency is decided by host design.
4		40Ω	x 1.2	

[Table 2] I/O Driver strength types

Selecting **HS_Timing** depends on Host I/F speed, default is 0, but all of value can be selected by host.

Value	Timing	Supportability for e-NAND
0x00	Selecting backward compatibility interface timing	Support
0x01	High speed	Support
0x02	HS200	Support
0x03	HS400	Support

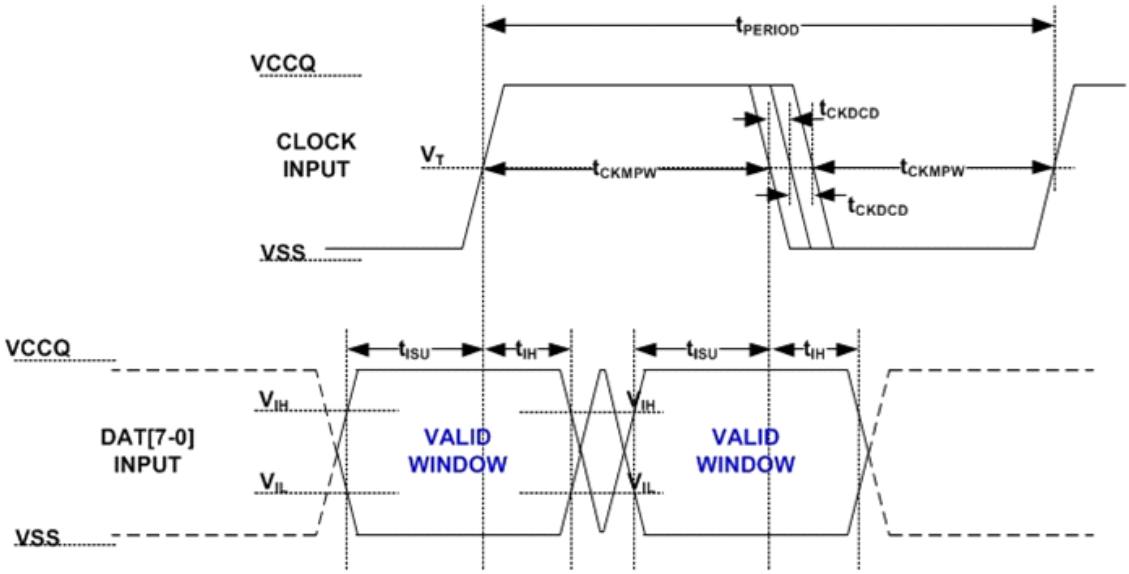
[Table 3] HS_Timing values

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4.1.1.1 Bus timing specification in HS400 mode

■ HS400 Device input timing

The CMD input timing for HS400 mode is the same as CMD input timing for HS200 mode.



[Figure 4] HS400 Device input timing

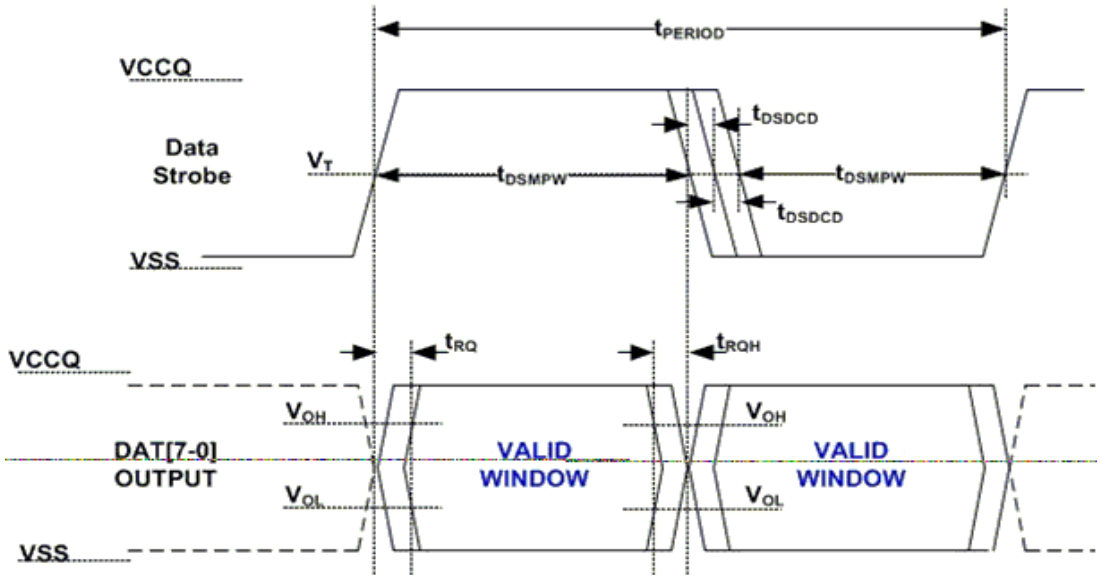
Parameter	Symbol	Min	Max	Unit	Remark
Input CLK					
Cycle time data transfer mode	t_{PERIOD}	5			200MHz(Max), between rising edges with respect to V_T
Slew rate	SR	1.125		V/ns	With respect to V_{IH}/V_{IL}
Duty cycle distortion	t_{CKDCD}	0.0	0.3	ns	Allowable deviation from an ideal 50% duty cycle. With respect to V_T. Includes jitter, phase noise
Minimum pulse width	t_{CKMPW}	2.2		ns	With respect to V_T
Input DAT (referenced to CLK)					
Input set-up time	t_{ISUddr}	0.4		ns	$C_{DEVICE} \leq 6pF$ With respect to V_{IH}/V_{IL}
Input hold time	t_{IHddr}	0.4		ns	$C_{DEVICE} \leq 6pF$ With respect to V_{IH}/V_{IL}
Slew rate	SR	1.125		V/ns	With respect to V_{IH}/V_{IL}

[Table 4] HS400 Device input timing

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■ HS400 Device output timing

Data strobe is for reading data in HS400 mode. Data strobe is toggled only during data read or CRC status response.



[Figure 5] HS400 Device output timing

Parameter	Symbol	Min	Max	Unit	Remark
Data Strobe					
Cycle time data transfer mode	t_{PERIOD}	5			200MHz(Max), between rising edges with respect to V_T
Slew rate	SR	1.125		V/ns	With respect to V_{OH}/V_{OL} and HS400 reference load
Duty cycle distortion	t_{DSDCD}	0.0	0.2	ns	Allowable deviation from the input CLK duty cycle distortion(t_{CKDCD}) With respect to V_T Includes jitter, phase noise
Minimum pulse width	t_{DSMPW}	2.0		ns	With respect to V_T
Read pre-amble	t_{RPRE}	0.4	5 (One Clock Cycle)	t_{PERIOD}	Max value is specified by manufacturer. value up to infinite is valid.
Read post-amble	t_{RPST}	0.4	2.5 (Half Clock Cycle)	t_{PERIOD}	Max value is specified by manufacturer. value up to infinite is valid.
Output DAT (referenced to Data strobe)					
Output skew	t_{RQ}		0.4	ns	With respect to V_{OH}/V_{OL} and HS400 reference load
Output hold skew	t_{RQH}		0.4	ns	With respect to V_{OH}/V_{OL} and HS400 reference load
Slew rate	SR	1.125		V/ns	With respect to V_{OH}/V_{OL} and HS400 reference load

[Table 5] HS400 Device output timing

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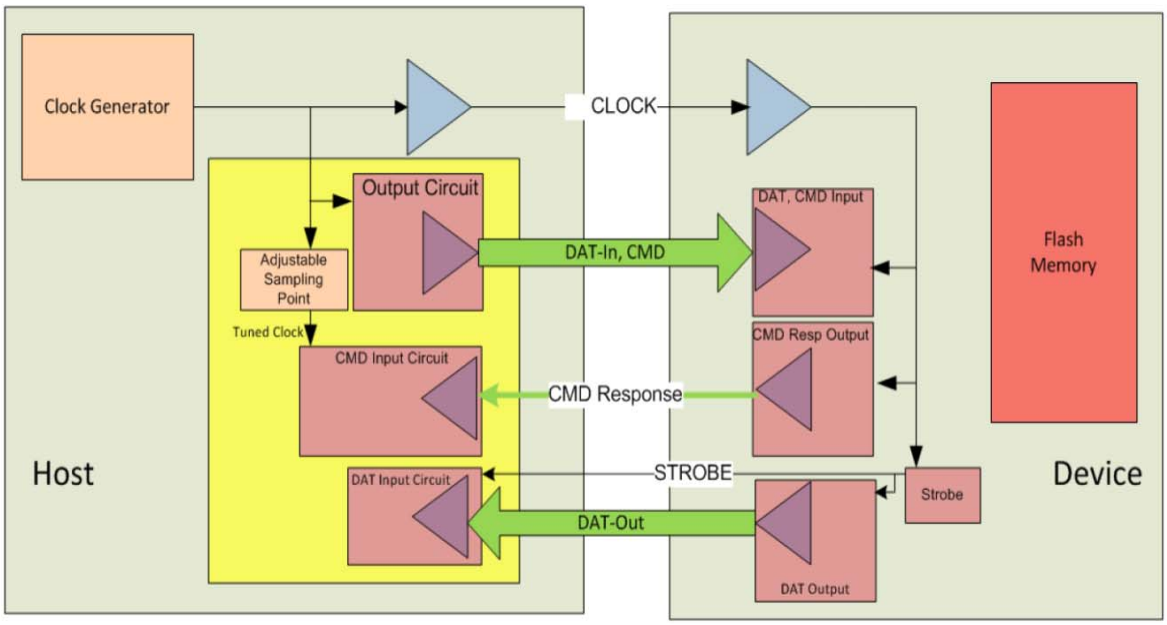
Parameter	Symbol	Min	Type	Max	Unit	Remark
Pull-up resistance for CMD	R_{CMD}	4.7		100	Kohm	
Pull-up resistance for DAT0-7	R_{DAT}	10		100	Kohm	
Pull-down resistance for Data strobe	R_{DS}	10		100	Kohm	
Internal pull up resistance DAT1-DAT7	R_{int}	10		150	Kohm	
Bus signal line capacitance	C_L			13	pF	
Single Device capacitance	C_{Device}			6	pF	

[Table 6] HS400 Device input timing

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■ Data Strobe for HS400

Data strobe is Return Clock signal used in HS400 mode. This signal is generated by the device and used for data output and CRC status response output in HS400 mode. The frequency of this signal follows the frequency of CLK. For data output each cycle of this signal directs two bits transfer(2x) on the data - one bit for positive edge and the other bit for negative edge. For CRC status response output, the CRC status is latched on the positive edge only, and don't care on the negative edge. Data strobe signal is toggled only for Data out and CRC response (Align CMD response as well as CRC response to the DS in eMMC5.1)

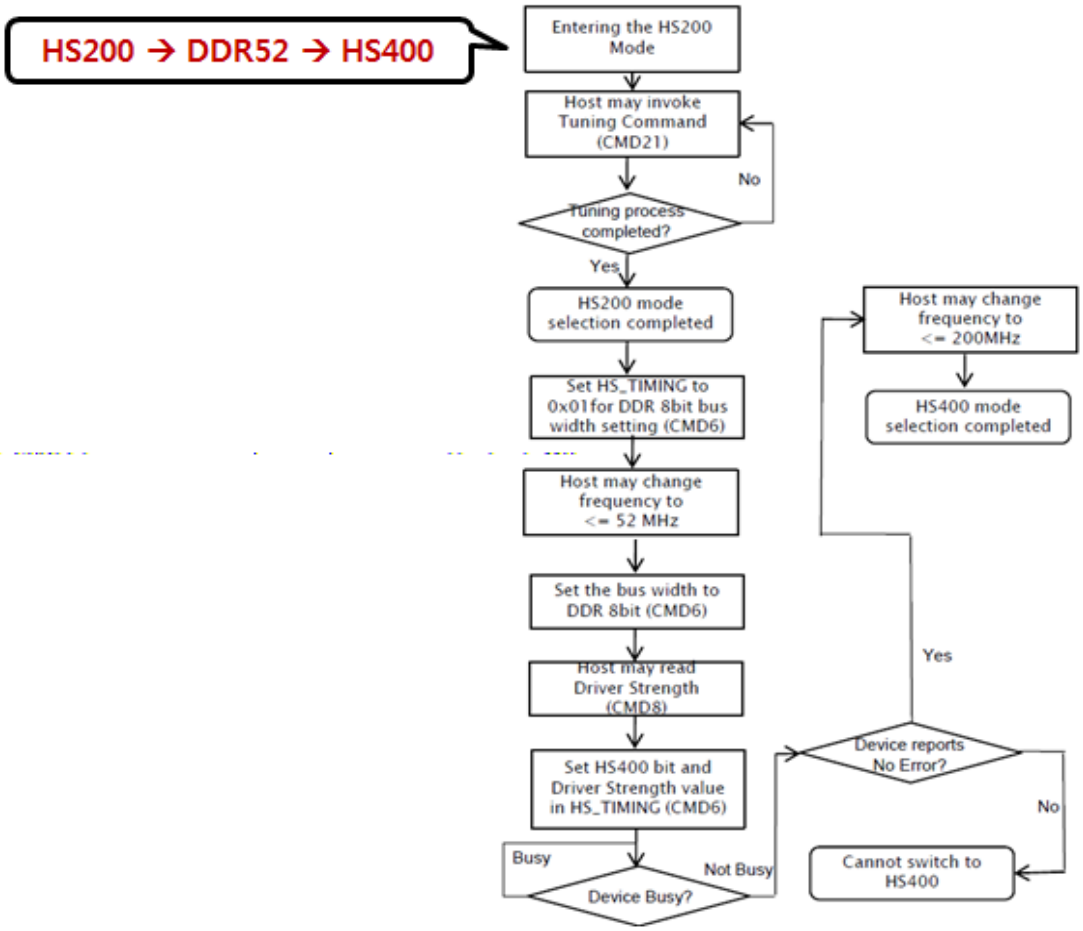


[Figure 6] HS400 Host and Device block diagram

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4.1.1.2 HS400 Mode selection

Following JEDEC standard for eMMC5.0, changing bus mode directly from HS200 to HS400 is not allowed. It has a rule for changing bus width from SDR mode to DDR mode that HS_TIMING must be set to "0x01"(HS mode : 52MHz) before setting BUS_WIDTH for DDR operation. We recommend the HS400 bus mode selection sequence as following.
(**eMMC5.1 has basically same flow, but 'enhanced strobe feature' is added. Please refer to 4.2.6 Enhanced strobe)**



[Figure 7] HS400 Bus mode selection sequence

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■ EXT_CSD register for Data strobe

- **Enhanced Strobe field in BUS_WIDTH [183]**

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Enhanced Strobe	Reserved			Bus Mode Selection			

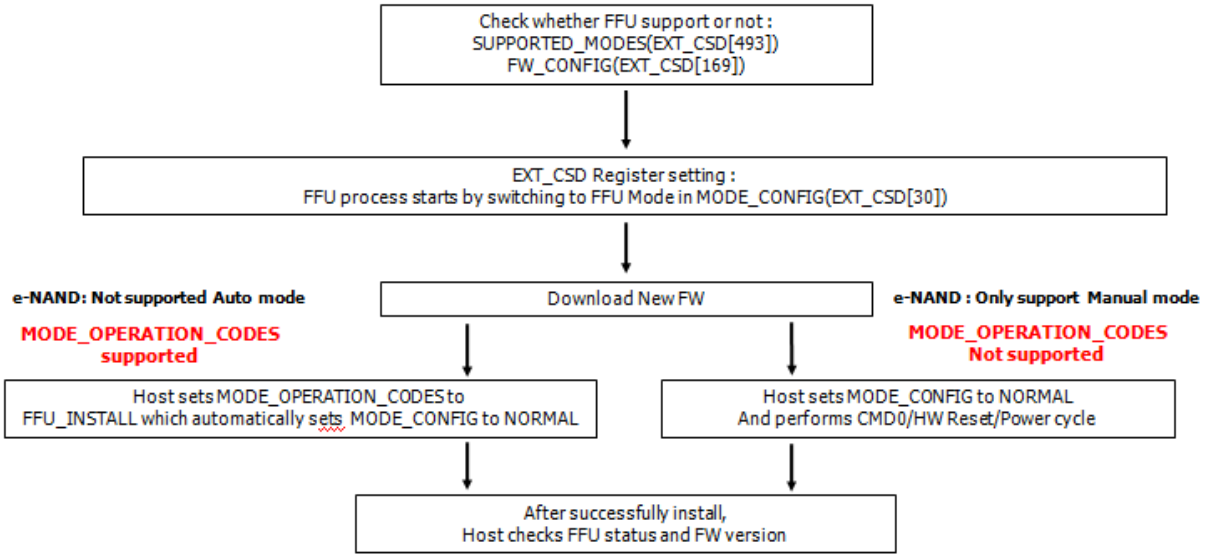
BIT[7] : 0: Strobe is provided only during data out and CTC response [Default]
1: Strobe is provided during data out, CRC response and CMD response

The support of STROBE_ENHANCED mode is optional for devices. STROBE_SUPPORT[184] register of EXT_CSD indicates whether a device supports that mode.

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4.1.2 Field firmware update (FFU)

To download a new firmware, the e-NAND requires instruction sequence following JEDEC standard.
SK hynix e-NAND only supports Manual mode (MODE_OPERATION_CODES is not supported). For more details, see as the following chart and register table given below.



[Figure 8] FFU flow chart

4.1.2.1 Field F/W update flow - CMD sequence

Operation	CMD	Remark
Set bus width (1bit or 4bit)		Bus width should be 1bit or 4bit
Set block length 512B	CMD16, arg : 0x00000200	
Enter FFU mode	CMD6, arg : 0x031E0100	
Send FW to device(Download)	CMD25, arg : 0xFFFAFFF0	Sending CMD25 is followed by sending FW data
CMD12 : Stop	CMD12, arg : 0x00000000	
CMD6 : Exit FFU mode	CMD6, arg : 0x031E0000	
CMD0/HW Reset/Power cycle		
Re-Init to trans state	CMD0, CMD1 ...	
Check if FFU is succeeded	CMD8, arg : 0x00000000	Check EXT_CSD[26] : FFU_SUCCESS If FFU_SUCCESS is 0, FFU is succeeded, otherwise FFU is failed.

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4.1.2.2 EXT_CSD Register for FFU

■ SUPPORTED_MODE[493] (Read Only)

BIT[0] : '0' FFU is not supported by the device. '1' FFU is supported by the device.

BIT[1] : '0' Vendor specific mode (VSM) is not supported by the device. '1' Vendor specific mode is supported by the device.

Bit	Field	Supportability
Bit[7:2]	Reserved	-
Bit[1]	VSM	Not support
Bit[0]	FFU	Supported

■ FFU_FEATURE[492] (Read Only)

BIT[0] : '0' Device does not support MODE_OPERATION_CODES field (Manual mode)

'1' Device supports MODE_OPERATION_CODES field (Auto mode)

Bit	Field	Supportability
Bit[7:1]	Reserved	-
Bit[0]	SUPPORTED_MODE_OPERATION_CODES	Not supported

■ FF_ARG[490-487] (Read Only)

Using this field the device reports to the host which value the host should set as an argument for read and write commands is FFU mode.

■ FF_CONFIG[169] (R/W)

BIT[0] : Update disable

0x0 : FW updates enabled. / 0x01 : FW update disabled permanently

Bit	Field	Supportability
Bit[7:1]	Reserved	-
Bit[0]	Update disable	FW updates enabled (0x0)

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■ FFU_STATUS[26] (R/W/E_P)

Using this field the device reports to the host the state of FFU process.

Value	Description
0x13 ~ 0xFF	Reserved
0x12	Error in downloading Firmware
0x11	Firmware install error
0x10	General error
0x01 ~ 0x0F	Reserved
0x00	Success

■ OPERATION_CODES_TIMEOUT[491](Read Only)

Maximum timeout for the SWITCH command when setting a value to the MODE_OPERATION_CODES field

The register is set to '0', because the e-NAND doesn't support MODE_OPERATION_CODES.

Value	Description	Timeout value
0x01 ~ 0x17	MODE_OPERATION_CODES_TIMEOUT = 100us x $2_{OPERATION_CODES_TIMEOUT}$	0 (Not defined)
0x18 ~ 0xFF	Reserved	-

■ MODE_OPERATION_CODES[29] (W/E_P)

The host sets the operation to be performed at the selected modes, in case MODE_CONFIGS is set to FFU_MODE, MODE_OPERATION_CODES could have the following values :

Bit	Description
0x01	FFU_INSTALL
0x02	FFU_ABOUT
0x00, others	Reserved

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4.1.3 Health(Smart) report

Using this feature is for monitoring device status and preventing the error and failure in advance.
Host can check device information with EXT_CSD as the register table given below.

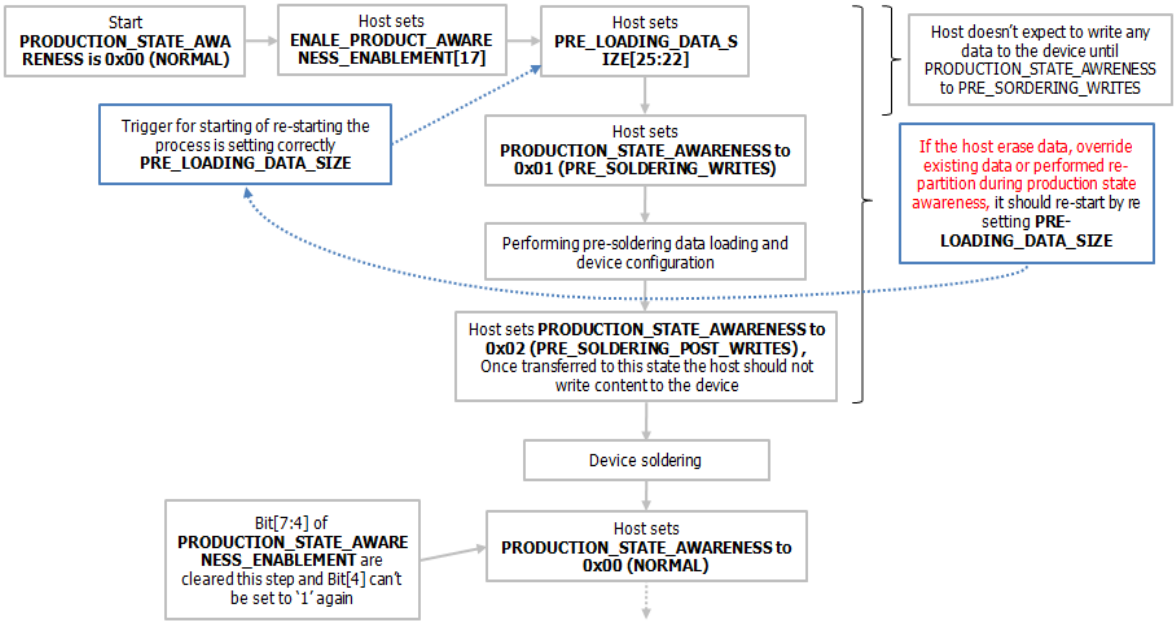
Field	CSD slice	Description
VENDOR_PROPRIETARY_HEALTH_REPORT	[301:270]	Reserved for vendor proprietary health report. (NONE)
DEVICE_LIFE_TIME_EST_TYPE_ A/B	[268:269]	Current average P/E cycle of memory of Type A(SLC) / Type B(MLC) relative to its maximum estimated capability
PRE_EOL_INFO	[267]	Consumed reserved blocks to notify before reaching the EOL (End of life) status
OPTIMAL_TRIM/WRITE_READ_SIZE	[264:266]	Minimum optimal (for the device) Erase / Write / Read unit size for the different partitions
DEVICE_VERSION	[263:262]	Device version
FIRMWARE_VERSION	[261:254]	Device FW version

[Table 7] Using EXT_CSD for health report (Read only)

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4.1.4 Production state awareness

This new feature is added for eMMC5.0 JEDEC Spec. to prevent the data break during device soldering. For this feature implementation, e-NAND supports only manual mode and PRODUCT_STATE_AWARENESS_TIMEOUT is 0x17(maximum). For more detail, see as the flow chart and register table given below.



[Figure 9] Production State Awareness manual mode flowchart

■ PRODUCTION_STATE_AWARENESS_TIMEOUT[218] (Read Only)

This field indicates maximum timeout for the SWITCH command when setting a value to the PRODUCTION_STATE_AWARENESS[133]field

Value	Description	Timeout value
0x01 ~ 0x17	Production State Timeout = 100us x $2_{PRODUCTION_STATE_AWARENESS_TIMEOUT}$	0x17 (838.86s)
0x18 ~ 0xFF	Reserved	-

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■ PRODUCTION_STATE_AWARENESS[133](R/W/E)

e-NAND doesn't support 0x03 state.

Value	Device State	Description
0x00	NORMAL (Field)	Regular operation
0x01	PRE_SOLDERING_WRITES	-
0x02	PRE_SOLDERING_POST_WRITES	Once transferred to this state the host should not write content to the device
0x03	AUTO_PRE_SOLDERING	Not supported
0x04 ~ 0x0F	Reserved	-
0x10 ~ 0x1F	Reserved for Vendor Proprietary Usage	-

■ PRODUCTION_STATE_ENABLEMENT[17]

e-NAND only supports manual mode for PRODUCTION_STATE_AWARENESS

	Enablement(R/W/E)			Capabilities(R)			
Bit7	**Bit6**	**Bit5**	**Bit4**	**Bit3**	**Bit2**	**Bit1**	**Bit0**
Reserved		Mode	Production State Awareness enable	Reserved		Auto mode Supported	Manual mode Supported
Cleared when PRODUCTION_STATE_AWARENESS is charged to Normal (either automatically or by setting PRODUCTION_STATE_AWARENESS to Normal)						This bit could be set to '1' only once	

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4.1.5 Sleep notification

Host may use to a power off notification when it intends to turn-off V_{CC} After moving the device to sleep state. Some features are added to clarify the spec for entering sleep mode when power off notification is enabled.

■ Add the SLEEP_NOTIFICATION on the interruptible Command List

CMD	Description	Is interruptible?
CMD6	SWITCH, Byte POWER_OFF_NOTIFICATION, Value POWER_OFF_LONG or SLEEP_NOTIFICATION	Yes

■ SLEEP_NOTIFICATION_TIME[216](Read Only)

Maximum timeout for the SWITCH command when notifying the device that it is about to move to sleep state by writing SLEEP_NOTIFICATION to POWER_OFF_NOTIFICATION[34]byte. (unit : 10us)

Value	Description	Timeout value
0x01 ~ 0x17	Sleep Notification Timeout = 10us x 2 ^{SLEEP_NOTIFICATION_TIME}	0xC (40.96ms)
0x18 ~ 0xFF	Reserved	-

■ POWER_OFF_NOTIFICATION[34]

Add Ox04h for the SLEEP_NOTIFICATION as a valid value

Value	Field	Description
:	:	:
0x03	POWER_OFF_LONG	Host is going to power off the device. The device shall respond within POWER_OFF_LONG_TIME
0x04	SLEEP_NOTIFICATION	Host is going to put device in sleep mode. The device shall respond within SLEEP_NOTIFICATION_TIME

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4.1.6 Secure removal type

This feature is used for how information is removed from the physical memory during a purge operation.

■ **Secure Removal Type[16]**
Among four options for secure removal type, e-NAND supports 0x3, 0x1 and 0x0 (0x2 option is not supported)
e-NAND recommends using a vendor defined removal type(type 3). If host want to erase the device physically using removal type0.
Secure erase & Secure trim time is longer than using removal type0

BIT	Description of Secure Removal Type	Description		Supportability
BIT[5:4]	Configure Secure Removal Type (R/W)	0x3	Information removed using a vendor defined	Support
		0x2	Information removed by an overwriting the addressed locations with a character, its complement, then a random character	-
		0x1	Information removed by an overwriting the addressed locations with a character followed by an erase	-
		0x0	Information removed by an erase of the physical memory	-
BIT[3:0]	Supported Secure Removal Type (R)	BIT[3]	Information removed using a vendor defined	Support
		BIT[2]	Information removed by an overwriting the addressed locations with a character, its complement, then a random character	Not support
		BIT[1]	Information removed by an overwriting the addressed locations with a character followed by an erase	Support
		BIT[0]	Information removed by an erase of the physical memory	Support

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4.2 eMMC5.1 New features

4.2.1 Command queuing

e-NAND manages an internal task queue to which the host can queue data transfer tasks to efficient operate.

4.2.1.1 CMD list for Command queuing

Index	Abbreviation	Argument	Remark
CMD44	Queued Task parameter	[31] Reliable Write Request [30] Data Direction (Read=1, Write=0) [29] Tag Request [28:25] context ID [24]Forced Programming [23] Priority (simple =0, high=1) [20:16] Task ID(31~0) [15:0] # of BLK	Encodes parameter which are necessary for queuing the task and executing the transfer
CMD45	Queued Task Address	[31:0] Block address for the transaction	The host instructs the device to queue a data transfer task
CMD46	Execute Read Task	[20:16] Task ID of the requested task which is must marked as "ready for execution" in the Queue Status Register	In order to execute a data read task (CMD46) or write task(CMD47) which is already queued
CMD47	Execute Write Task		
CMD48	CMDQ_TASK_MGMT	[31:21] reserved [20:16]: TaskID [15:4]: reserved [3:0] TM op-code	Device shall discard a specific task or entire queue (all tasks in the queue) [20:16] when TM op-code = 2h these bits represent TaskID. When TM op-code=1h these bits are reserved.

Index	Abbreviation	Argument	Remark
CMD13	SEND_STATUS	[31:16] RCA [15] **SQS** [14] Stuff bits [0] HPI	In case SQS bit = 1: indicate that this is CMD13 of CMD Queue. In response device shall send the QSR. In this case HPI bit muse be set to '0'.

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4.2.1.2 EXT_CSD Register for Command queuing

■ CMDQ_SUPPORT[308](Read only)
This field indicates whether command queuing is supported by the device.

BIT[0]: 0: Command queuing is not supported
1: Command queuing is supported

Bit	Field	Supportability
Bit[7:1]	Reserved	-
Bit[0]	CMDQ Support	Supported (0x1)

■ CMDQ_DEPTH[307](Read only)
This field is used to calculate the depth of the queue supported by the device. The maximum depth allowed by the standard is 32. The range of allowed Task IDs is 0 through N.

BIT[4:0]: N, a parameter used to calculate the Queue Depth of task queue in the device.
Queue Depth = N+1.

Bit	Field	CMD queue depth value
Bit[7:5]	Reserved	-
Bit[4:0]	N	N=31 (0x1F)

■ CMDQ_MODE_EN[15](R/W)
This field is used by the host enable command queuing mechanism if supported by the device.

BIT[0]: 0: Command queuing is disabled. Host should clear the queue empty using CMD48 prior disabling the queue.
1: Command queuing is enabled

Bit	Field	Supportability
Bit[7:1]	Reserved	-
Bit[0]	CMDQ enable	-

To maintain backward compatibility with hosts, which do not support command queuing, when the command queuing is disabled other functionality of the device is as if the device does not support command queuing.

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4.2.1.3 New register for Command queuing

■ **QSR (Queue Status Register)**

The 32bit QSR carries the state of tasks in the queue at a specific point in time.

The host has read access to this register through device response to SEND_STATUS command(CMD13 with bit[15]="1"), R1's argument will be the QSR.

Every bit in the QSR represents the task who's ID corresponds to the bit index.

If bit QSR[i]='0', the queued task with a Task ID i is not ready for execution.

The task may be queued and pending, or the Task ID is unused.

If bit QSR[i]='1', the queued task with Task ID i is ready for execution.

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4.2.1.4 Command queuing Flows

For enter the CMD Queuing Mode,
CMD_Q_EN(bit[0] of EXT_CSD[15]) is set to '1'

Initially Queue Task is empty, and then HOST issue
a **Queuing a Transaction (CMD44+CMD45)**



Checking the Queue Status (SEND_STATUS : CMD13)
HOST set the SQS bit = 1, for read the QSR.
The device responds with an R1 with the QSR in its argument.

Execution of a Queued Task (CMD46/ CMD47)

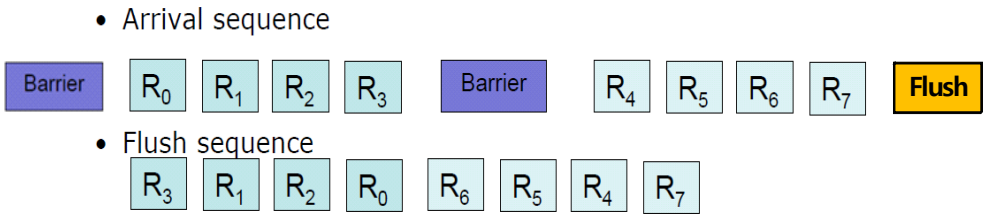


For end the CMD Queuing Mode,
HOST should clear the Queue Task to be empty, using
CMD48 before disabling the Queue.

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4.2.2 Cache Barrier

There are cases where the host is not interested in flushing the data right away, however it would like to keep an order between different cached data.
The flushing can be delayed by the device to some later idle time. Barrier commands avoid the long delay by flush commands.



4.2.2.1 EXT_CSD Register for Cache Barrier

■ BARRIER_SUPPORT[488](Read only)
This field indicates whether the device supports the barrier command.

BIT[7:0]: 0: Barrier command is not supported
1: Barrier command is supported

Bit	Field	Supportability
Bit[7:0]	BARRIER_SUPPORT	Supported (0x1)

■ FLUSH_CACHE[32](W/E_P)
A barrier command is issued by setting BARRIER bit. All data cached before the barrier shall be flushed to the non-volatile memory before any request after the barrier command.
Data in the cache shall be flushed to the non-volatile storage by setting the FLUSH bit.

BIT[1]: 0: Reset value
1: Set barrier

BIT[0]: 0: Reset value
1: Triggers the flush

Bit	Field	Supportability
Bit[7:2]	Reserved	-
Bit[1]	BARRIER	-
Bit[0]	FLUSH	-

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■ **BARRIER_CTRL[31](R/W)**

This field is used by the host enable barrier command mechanism if supported by the device.

BIT[0]: 0: Barrier feature is OFF

1: Barrier feature is ON

Bit	Field	Supportability
Bit[7:1]	Reserved	-
Bit[0]	BARRIER_EN	-

4.2.2.2 Cache barrier Flows

1. Support Barrier command

- The device exposes its barrier support capability via the BARRIER_SUPPORT (EXT_CSD byte [486])

2. Enable Barrier command

- The host shall set bit 0 of BARRIER_EN (EXT_CSD byte [31])

3. Cache on

4. Send data

5. Set Barrier

- The host shall set both BARRIER bit and FLUSH bit of the FLUSH_CACHE (EXT_CSD byte [32])

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4.2.3 Cache Flushing Report

For devices which flush cached data in an in-order manner, cache barrier commands are redundant and impose a needless overhead to the device and host.

4.2.3.1 EXT_CSD Register for Cache Flushing Report

■ CACHE_FLUSH_POLICY[240](Read only)

BIT[0]: 0: Device flushing policy is not provided by the device.

1: Device is using a FIFO policy for cache flushing

Bit	Field	Supportability
Bit[7:1]	Reserved	-
Bit[0]	FIFO	Supported (0x01)

4.2.4 BKOP Control

This feature allows the host to indicate to the device if it is expected to periodically manually start background operations by writing to the BKOPS_START field.

4.2.4.1 EXT_CSD Register for BKOP Control

■ BKOP_EN[163](R/W/E, R/W)

BIT[1](R/W/E): 0: Device shall not perform background operations while not servicing the host.

1: Device may perform background operations while not servicing the host.

BIT[0] (R/W): 0: Host does not support background operations handling and is not expected to write to BKOPS_START field.

1: Host is indicating that it shall periodically write to BKOPS_START field to manually start background operations.

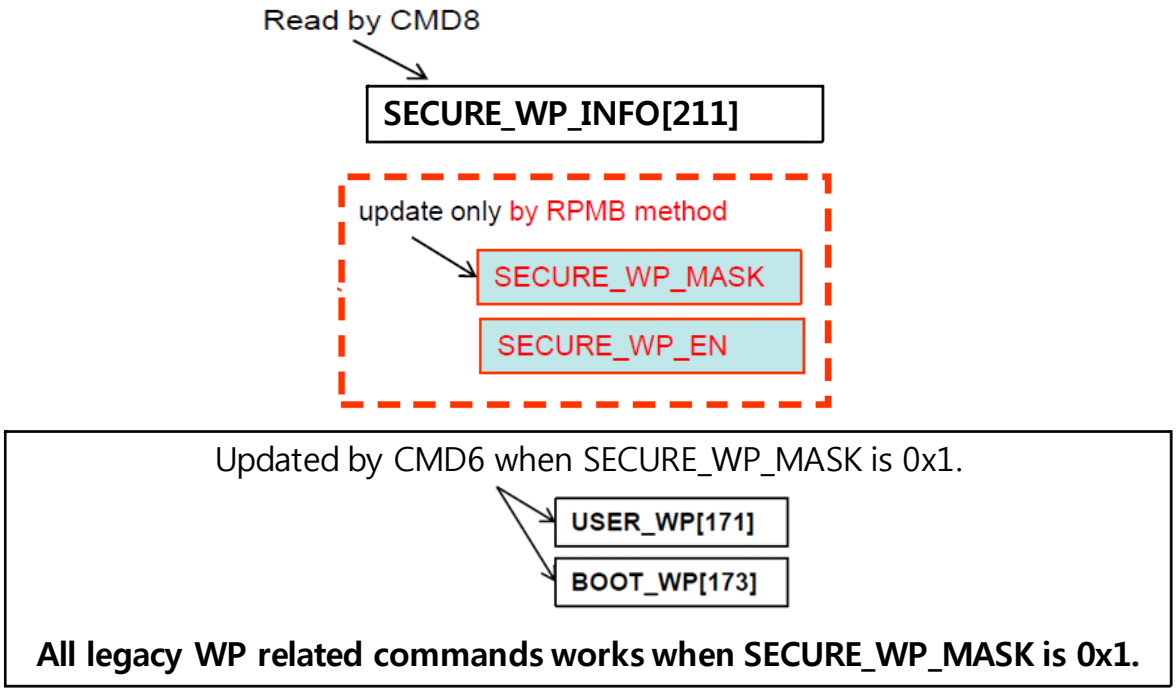
Bit	Field	Supportability
Bit[7:2]	Reserved	-
Bit[1]	AUTO_EN	-
Bit[0]	MANUAL_EN	-

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4.2.5 Secure Write Protection

Any application running on the host may issue write protection by updating fields of write protection related EXT_CSD, like USER_WP[171], BOOT_WP[173], by issuing CMD6, CMD8, CMD28 and CMD29 (Legacy mode).
However there are weak points in the legacy mode. To prevent un-authorized changes, host should enter the secure write protect mode

- In Secure WP Mode, WP related EXT_CSDs (EXT_CSD[171],[173]) can be updated only if SECURE_WP_MASK fields is 0x1.
- Secureness is provided by allowing only RPMB method to update the register for SECURE_WP_MASK.
- Automatic Write protection mode is added to prevent security hole by power-control security attack.



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4.2.5.1 EXT_CSD Register for Secure Write Protection

■ SECURE_WP_INFO[211](Read Only)

The SECURE_WP_SUPPORT field indicates whether the device is supporting secure write protection mode.
The SECURE_WP_EN_STATUS is showing the value of SECURE_WP_EN defined in Authenticated Device Configuration Area.

BIT[1] 0: Legacy Write Protection mode
1: Secure Write Protection mode

BIT[0] 0: Secure Write Protection is NOT supported by this device
1: Secure Write Protection is supported by this device

Bit	Field	Supportability
Bit[7:2]	Reserved	-
Bit[1]	SECURE_WP_EN_STATUS	-
Bit[0]	SECURE_WP_SUPPROT	Supported (0x01)

4.2.5.2 New register for Secure Write Protection

■ Authenticated Device Configuration Area

● Hidden register instead of EXT_CSD register for SECURE_WP_MODE_CONFIG, ENABLE.

● Those two SECURE_WP_MODE_CONFIG and SECURE_WP_MODE_ENABLE registers are defined in Device Configuration area, and those register should be updated only by Authenticated Device Configuration write request. (RPMB)

Name	Field	Size (Bytes)	Cell Type	Address
Reserved		253	-	[255:3]
Secure Write Protect Configuration	SECURE_WP_MODE_CONFIG	1	R/W/E_P	[2]
Secure Write Protect Enable	SECURE_WP_MODE_ENABLE	1	R/W/E	[1]
Reserved		1		[0]

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■ Authenticated Device Configuration Area (1) : SECURE_WP_MODE_ENABLE (R/W/E)

The byte is to enter/exit the secure write protection mode.
If host want a device to enter the secure Write Protection mode, host set the SECURE_WP_EN bit as '0x1' in this register using Authenticated Device Configuration Write request. This register can be read using Authenticated Device Configuration Read request. If there are already write protected groups or write protected boot partitions, those will be preserved when entering or exiting secure Write protected mode.

Bit [0] 0: Legacy Write Protection mode.
(TMP_WRITE_PROTECT[12] , PERM_WRITE_PROTECT[13] is updated by CMD27. USER_WP[171], BOOT_WP[173] and BOOT_WP_STATUS[174] are updated by CMD6.)

1: Secure Write Protection mode.
(The access to the write protection related EXT_CSD and CSD fields depends on the value of SECURE_WP_MASK bit in SECURE_WP_MODE_CONFIG field.)

The default value of this field is 0x0.

Bit	Field	Supportability
Bit[7:1]	Reserved	-
Bit[0]	SECURE_WP_MODE_ENABLE	-

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■ Authenticated Device Configuration Area (2) : SECURE _WP_MODE_CONFIG (R/W/E_P)

In secure write protected mode, the updatability of USER_WP[171], BOOT_WP[173], TMP_WRITE_PROTECT[12] and PERM_WRITE_PROTECT[13] are controlled by this mask value.

Bit [0] 0: Disabling updating WP related EXT_CSD and CSD fields. CMD27 (Program CSD) will generate generic error for setting TMP_WRITE_PROTECT[12] , PERM_WRITE_PROTECT[13]. CMD6 for updating USER_WP[171], BOOT_WP[173] and BOOT_WP_STATUS[174] generates SWITCH_ERROR. If a force erase command is issued, the command will fail (Device stays locked) and the LOCK_UNLOCK_FAILED error bit will be set in the status register. If CMD28 or CMD29 is issued, then generic error will be occurred. Power-on Write Protected boot partitions will keep protected mode after power failure, H/W reset assertion and any CMD0 reset. The device keeps the current value of BOOT_WP in the EXT_CSD register to be same after power cycle, H/W reset assertion, and any CMD0 reset.

1: Enabling updating WP related EXT_CSD and CSD fields.
(TMP_WRITE_PROTECT[12] , PERM_WRITE_PROTECT[13] , USER_WP[171], BOOT_WP[173] and BOOT_WP_STATUS[174] are accessed using CMD6, CMD8 and CMD27. If a force erase command is issued and accepted, then ALL THE DEVICE CONTENT WILL BE ERASED including the PWD and PWD_LEN register content and the locked Device will get unlocked. If a force erase command is issued and power-on protected or a permanently-write-protected write protect groups exist on the device, the command will fail (Device stays locked) and the LOCK_UNLOCK_FAILED error bit will be set in the status register. An attempt to force erase on an unlocked Device will fail and LOCK_UNLOCK_FAILED error bit will be set in the status register. Write Protection is applied to the WPG indicated by CMD28 with the WP type indicated by the bit[2] and bit[0] of USER_WP[171]. All temporary WP Groups and power-on Write Protected boot partitions become writable/erasable temporarily which means write protect type is not changed. All power-on and permanent WP Groups in user area will not become writable/ erasable temporarily. Those temporarily writable/erasable area will become write protected when this bit is cleared to 0x0 by the host or when there is power failure, H/W reset assertion and any CMD0 reset. The device keeps the current value of BOOT_WP CSD register to be same after power cycle, H/W reset assertion, and any CMD0 reset.)

The default value of this field is 0x0.

Bit	Field	Supportability
Bit[7:1]	Reserved	-
Bit[0]	SECURE_WP_MODE_CONFIG	-

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4.2.5.3 RPMB Types for accessing Authenticated Device Configuration Area

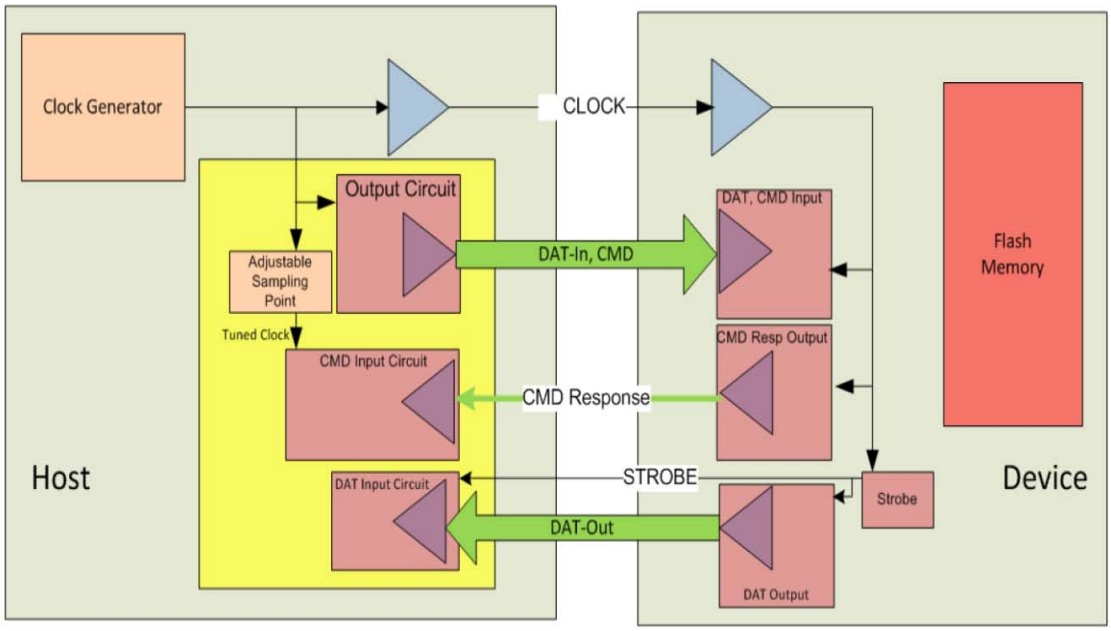
Secure WP Enable & Configuration registers are defined in Authenticated Device Configuration Area which only can be accessible by new RPMB operations.

Request Message Types	
0x0001	Authentication key programming request
0x0002	Reading of the Write Counter value –request
0x0003	Authenticated data write request
0x0004	Authenticated data read request
0x0005	Result read request
0x0006	Authenticated Device Configuration Write request
0x0007	Authenticated Device Configuration Read request
Response Message Types	
0x0100	Authentication key programming response
0x0200	Reading of the Write Counter value –response
0x0300	Authenticated data write response
0x0400	Authenticated data read response
0x0600	Authenticated Device Configuration Write response
0x0700	Authenticated Device Configuration Read response

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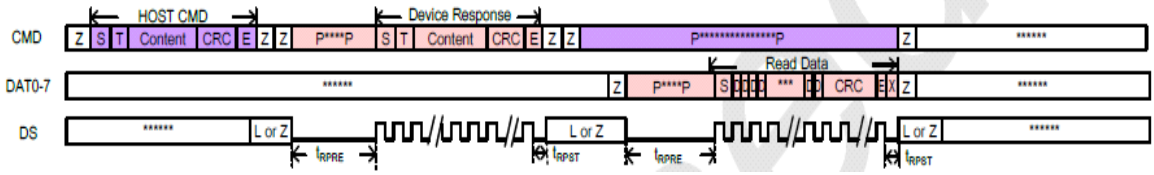
4.2.6 Enhanced strobe

In Enhanced Strobe mode DATA OUT, CRC Response and CMD Response are all synched to STROBE clocks. The timing relation between CMD Response output signals and STROBE clocks is the same as defined for DATA Out to STROBE clocks.

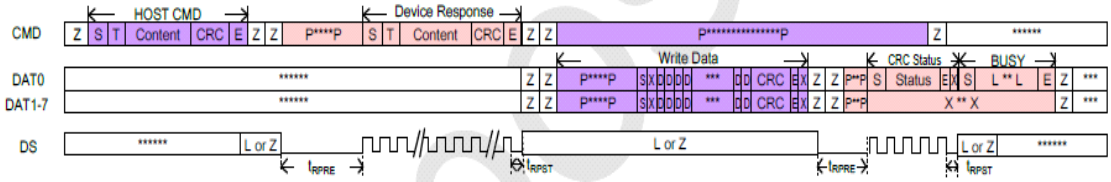


[Figure 10] HS400 Host and Device block diagram (when Enhanced Strobe is enabled)

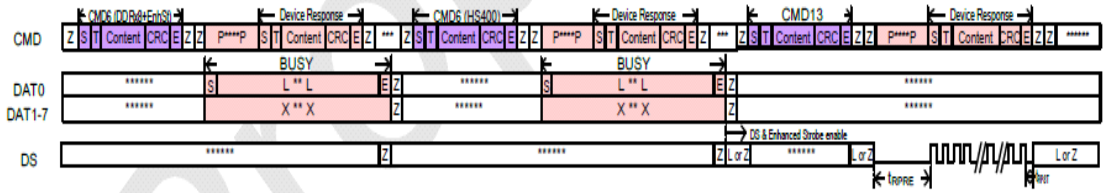
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[Figure 11] Enhanced Strobe signals for CMD Response and Data Out (Read operation)



[Figure 12] Enhanced Strobe signals for CMD Response and Data Out (Write operation)



[Figure 13] HS400 mode change with Enhanced Strobe

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4.2.6.1 EXT_CSD Register for Enhanced Strobe

■ STROBE_SUPPORT[184](Read only)

This register indicates whether a device supports Enhanced Strobe mode for operation modes that STROBE is used for HS400.

BIT[7:0]: 0: Indicates No support of Enhanced Strobe mode

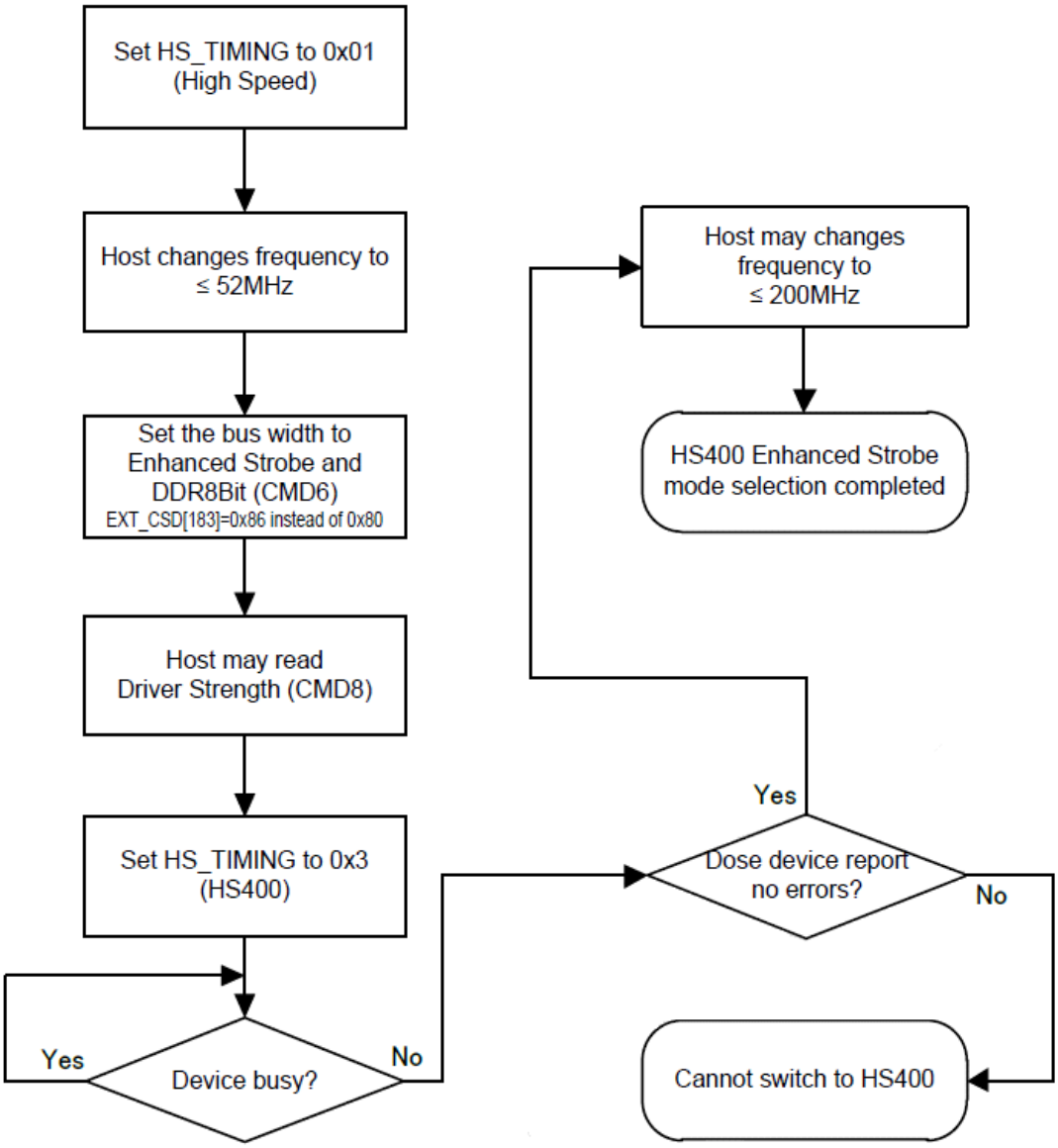
1: Indicates the device supports Enhanced Strobe mode

Bit	Field	Supportability
Bit[7:0]	**STROBE_SUPPORT**	Supported (0x01)

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4.2.6.2 HS400 mode (Enhanced Strobe) selection

This selection flow describes how to initialize the eMMC device in HS400 mode while enabling Enhanced Strobe without the need for tuning procedure.
After the host initializes the device, host check whether the device supports the HS400 mode and Enhanced Strobe by reading the DEVICE_TYPE and STROBE_SUPPORT fields in the Extended CSD register.
After power-on or software reset (CMD0), the interface timing of the device is set as the default 'Backward Compatible Timing'.
In order to switch to HS400 mode with Enhanced Strobe, host should perform the following steps.



[Figure 14] HS400 Bus mode (Enhanced Strobe) selection flow diagram

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4.2.7 RPMB throughput improvement

This feature is proposed for RPMB write data size to improve the RPMB throughput in eMMC5.1 spec. In the eMMC5.0 spec, REL_WR_SEC_C[222] register shall be set to 1 (hence the granularity is always 512B.)
- For reliable write to RPMB partition, there is limitation that block count can not exceed the size of REL_WR_SEC_C x 512B. In eMMC5.1, the supported RPMB write access size is 256B, 512B, and 8KB.

■ WRITE_REL_PARAM (EXT_CSD[166]): Read only

When EXT_CSD[166][4] (R) = 0

- Device does not support large RPMB wirte transfer
- The behavior is same as eMMC v5.0 or earlier

When EXT_CSD[166][4] (R) = 1

- Device supports large RPMB wirte transfer
- Host transfers small RPMB write with block count = 1 or 2 (256/512B)
- Host transfers large RPMB write with block count = 32 (8KB)
  * the start address should be 8KB aligned, and the transferred data (8KB) is all-new or all-old

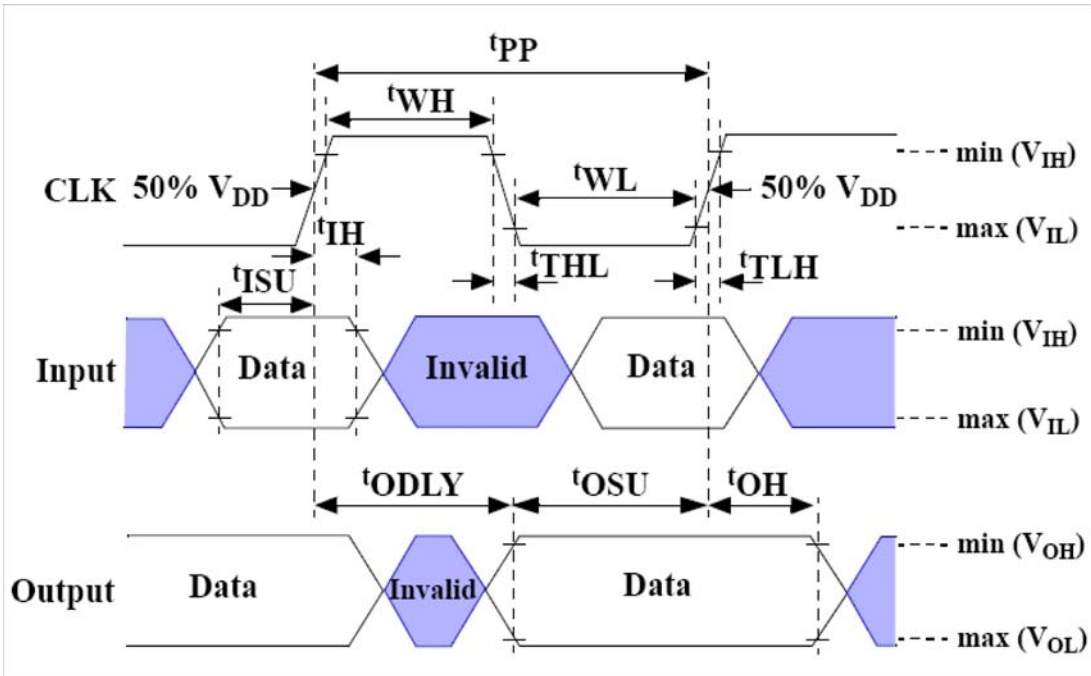
Bit	Field	Supportability
Bit[4]	EN_RPMB_REL_WR	Supported (0x01)

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5. e-NAND general parameters

5.1 Timing

5.1.1 Bus timing



Data must always be sampled on the rising edge of the clock.

[Figure 15] Timing diagram: data input/output

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Parameter	Symbol	Min	Max	Unit	Remark
Clock CLK					
Clock frequency data transfer mode (PP)	f_{PP}	0	52	MHz	C_L ≤30 pF Tolerance: +100KHz
Clock frequency identification mode (OD)	f_{OD}	0	400	KHz	Tolerance: +20KHz
Clock high time	t_{WH}	6.5		ns	C_L ≤ 30 pF
Clock low time	t_{WL}	6.5		ns	C_L ≤ 30 pF
Clock rise time	t_{TLH}		3	ns	C_L ≤ 30 pF
Clock fall time	t_{THL}		3	ns	C_L ≤ 30 pF
Inputs CMD, DAT (referenced to CLK)					
Input set-up time	t_{ISU}	3		ns	C_L ≤ 30 pF
Input hold time	t_{IH}	3		ns	C_L ≤ 30 pF
Outputs CMD, DAT (referenced to CLK)					
Output delay time during data transfer	t_{ODLY}		13.7	ns	C_L ≤ 30 pF
Output hold time	t_{OH}	2.5		ns	C_L ≤ 30 pF
Signal rise time	t_{RISE}		3	ns	C_L ≤ 30 pF
Signal fall time	t_{FALL}		3	ns	C_L ≤ 30 pF

[Table 9] High-speed e-NAND interface timing

- CLK timing is measured at 50% of VDD.
- e-NAND shall support the full frequency range from 0-26Mhz, or 0-52MHz
- CLK rising and falling times are measured by min (V_{IH}) and max (V_{IL}).
- Input CMD, DAT rising and falling times are measured by min (V_{IH}) and max (V_{IL}), and output CMD, DAT rising and falling times are measured by min (V_{OH}) and max (V_{OL}).

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Parameter	Symbol	Min	Max	Unit	Remark
Clock CLK					
Clock frequency data transfer mode (PP)	f_{PP}	0	26	400	C_L ≤30 pF
Clock frequency identification mode (OD)	f_{OD}	0	400	KHz	
Clock high time	t_{WH}	10		ns	C_L ≤ 30 pF
Clock low time	t_{WL}	10		ns	CL ≤ 30 pF
Clock rise time	t_{TLH}		10	ns	CL ≤ 30 pF
Clock fall time	t_{THL}		10	ns	CL ≤ 30 pF
Inputs CMD, DAT (referenced to CLK)					
Input set-up time	t_{ISU}	3		ns	CL ≤ 30 pF
Input hold time	t_{IH}	3		ns	CL ≤ 30 pF
Outputs CMD, DAT (referenced to CLK)					
Output set-up time	t_{OSU}	11.7		ns	CL ≤ 30 pF
Output hold time	t_{OH}	8.3		ns	CL ≤ 30 pF

[Table 10] Backward-compatible e-NAND interface timing

- e-NAND must always start with the backward-compatible interface timing. The timing mode can be switched to high-speed timing by the host sending the switch command (CMD6) with the argument for high speed interface select.
- CLK timing is measured at 50% of VDD.
- CLK rising and falling times are measured by min (V_{IH}) and max (V_{IL}).
- t_{OSU} and t_{OH} are defined as values from clock rising edge. However, there may be cards or devices which utilize clock falling edge to output data in backward compatibility mode.

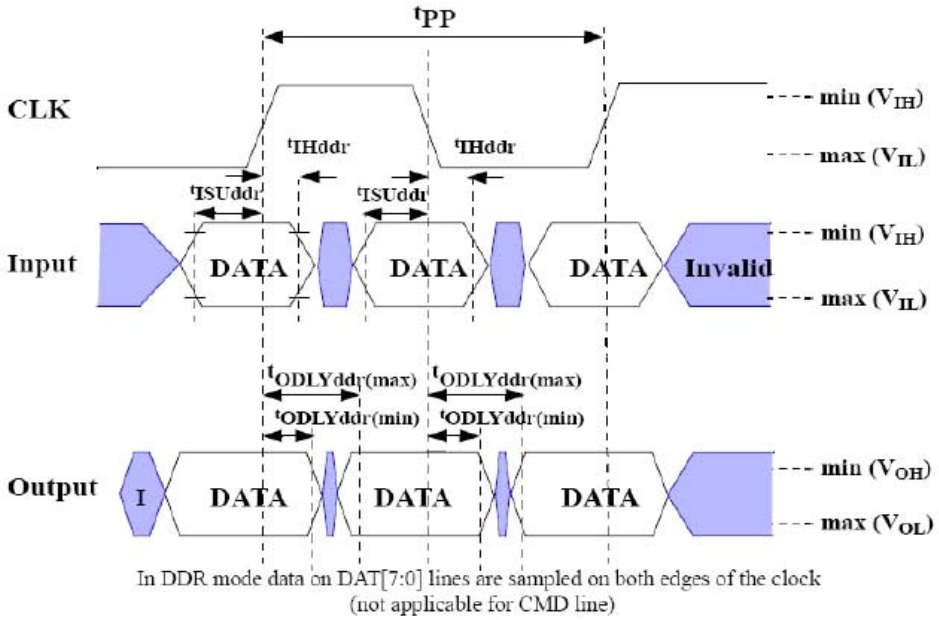
  Therefore, it is recommended for hosts either to set t_{WL} value as long as possible within the range which should not go over t_{CK}-t_{OH}(min) in the system or to use slow clock frequency, so that host could have data set up margin for those devices.

  In this case, each device which utilizes clock falling edge might show the correlation either between t_{WL} and t_{OSU} or between t_{CK} and t_{OSU} for the device.

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5.1.2 Bus timing for DAT Signals During 2x Data Rate Operation

These timings apply to the DAT[7:0] signals only when the device is configured for dual data mode operation. In dual data mode, the DAT signals operate synchronously of both the rising and the falling edges of CLK.



[Figure 16] Timing diagram: data input/output in dual data rate mode

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Parameter	Symbol	Min.	Max.	Unit	Remark
Input CLK(1)					
Clock duty cycle		45	55	%	Includes jitter, phase noise
Clock rise time	t_{TLH}		3	ns	CL≤30 pF
Clock fail time	t_{THL}		3	ns	CL≤30 pF
Input CMD (referenced to CLK-SDR mode)					
Input set-up time	t_{ISUddr}	3		ns	CL≤20 pF
Input hold time	t_{IHDDR}	3		ns	CL≤20 pF
Output CMD (referenced to CLK-SDR mode)					
Output delay time during data transfer	t_{ODLY}		13.7	ns	CL≤20 pF
Output hold time	t_{OH}	2.5		ns	CL≤20 pF
Signal rise time	t_{RISE}		3	ns	CL≤20 pF
Signal fall time	t_{FALL}		3	ns	CL≤20 pF
Input DAT (referenced to CLK-DDR mode)					
Input set-up time	t_{ISUddr}	2.5		ns	CL≤20 pF
Input hold time	t_{IHddr}	2.5		ns	CL≤20 pF
Outputs DAT (referenced to CLK-DDR mode)					
Output delay time during data transfer	$t_{ODLYddr}$	1.5	7	ns	CL≤20 pF
Signal rise time(DAT0-7)(2)	t_{RISE}		2	ns	CL≤20 pF
Signal fall time (DAT0-7)	t_{FALL}		2	ns	CL≤20 pF

[Table 11] Dual data rate interface timings

- NOTE 1. CLK timing is measured at 50% of VDD.
- NOTE 2. Inputs DAT rising and falling times are measured by min (V_{IH}) and max (V_{IL}), and outputs CMD, DAT rising and falling times are measured by min (V_{OH}) and max (V_{OL})

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5.2 Bus signal

5.2.1 Bus signal line load

The total capacitance C_L of each line of e-MMC bus is the sum of the bus master capacitance C_{HOST}, the bus capacitance C_{BUS} itself, and the capacitance C_{Device} of the eMMC connected to this line, and requiring the sum of the host and bus capacitances not to exceed 20 pF.

$$C_L = C_{HOST} + C_{BUS} + C_{Device}$$

Parameter	Symbol	Min	Typ	Max	Unit	Remark
Pull-up resistance for CMD	R_{CMD}	4.7		100	Kohm	to prevent bus floating
Pull-up resistance for DAT0-7	R_{DAT}	10		100	Kohm	to prevent bus floating
Internal pull up resistance DAT1 - DAT7	R_{int}	10		150	Kohm	
Bus signal line capacitance	C_L			30	pF	Single Device
Single Device capacitance	C_{DEVICE}			6	pF	
Maximum signal line inductance				16	nH	$f_{PP} \leq 52$ MHz
VDDi capacitor value	C_{REG}	0.1			uF	To stabilize regulator output when target device bus speed mode is either backward-compatible, high speed SDR, high speed DDR, or HS200.
		1			uF	To stabilize regulator output when target device bus speed mode is HS400
V_{ccq} decoupling capacitor	C_{H1}	1			uF	

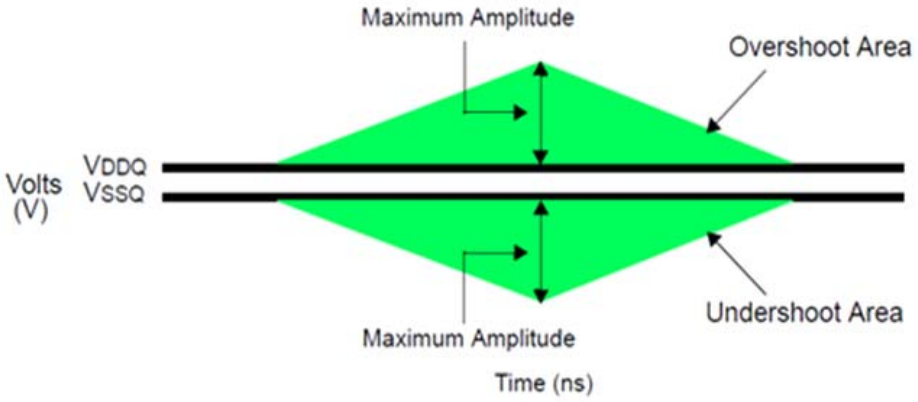
[Table 12] e-NAND capacitance

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5.2.2 Overshoot / Undershoot specification

Specification		V_{ccq} 1.70V - 1.95V	Unit
Maximum peak amplitude allowed for overshoot area.	Max	0.9	V
Maximum peak amplitude allowed for undershoot area.	Max	0.9	V
Maximum area above V_{ccq}	Max	1.5	V-ns
Maximum area below V_{ssq}	Max	1.5	V-ns

[Table 13] Overshoot / Undershoot specification

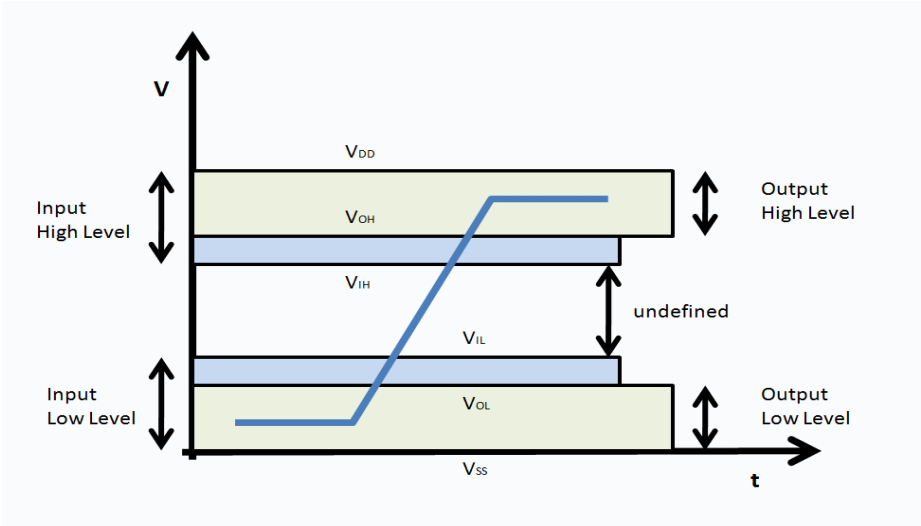


[Figure 17] Overshoot / Undershoot definition

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5.2.3 Bus Signal levels

As the bus can be supplied with a variable supply voltage, all signal levels are related to the supply voltage.



[Figure 18] e-NAND bus signal level

- **Open-Drain mode bus signal level**

Parameter	Symbol	Min.	Max.	Unit	Conditions
Output high voltage	V_{OH}	V_{DD} - 0.2		V	Note[1)]
Output low voltage	V_{OL}		0.3	V	I_{OL} = 2mA

[Table 14] Open-Drain signal level

- NOTE 1. Because Voh depends on external resistance value (including outside the package), this value does not apply as device specification. Host is responsible to choose the external pull-up and open drain resistance value to meet Voh minimum value.

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- **Push-Pull mode bus signal level**

The device input and output voltages shall be within the following specified ranges for any V_{DD} of the allowed voltage range

Parameter	Symbol	Min.	Max.	Unit	Conditions
Output HIGH voltage	V_{OH}	0.75 * V_{ccq}		V	I_{OH} = -100μA @ V_{ccq} min
Output LOW voltage	V_{OL}		0.125 * V_{ccq}	V	I_{OL} = -100μA @ V_{ccq} min
Input HIGH voltage	V_{IH}	0.625 * V_{ccq}	V_{ccq} + 0.3	V	
Input LOW voltage	V_{IL}	V_{SS} - 0.3	0.25 * V_{ccq}	V	

[Table 15] Push-Pull signal level 2.7V-3.6V V_{ccq} range

Parameter	Symbol	Min.	Max.	Unit	Conditions
Output HIGH voltage	V_{OH}	Vccq - 0.45V		V	I_{OH} = -2mA
Output LOW voltage	V_{OL}		0.45V	V	I_{OL} = -2mA
Input HIGH voltage	V_{IH}	0.65 * V_{ccq}	V_{ccq} + 0.3	V	
Input LOW voltage	V_{IL}	V_{SS} - 0.3	0.35 * V_{ccq}	V	

[Table 16] Push-pull signal level 1.65V-1.95V V_{ccq} range

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5.3 Power mode

5.3.1 e-NAND power-up guidelines

e-NAND power-up must adhere to the following guidelines:

● When power-up is initiated, either V_{cc} or V_{ccq} can be ramped up first, or both can be ramped up simultaneously.

● After power up, e-NAND enters the pre-idle state. The power up time of each supply voltage should be less than the specified tPRU (tPRUH, tPRUL or tPRUV) for the appropriate voltage range.

● If e-NAND does not support boot mode or its BOOT_PARTITION_ENABLE bit is cleared, e-NAND moves immediately to the idle state. While in the idle state, e-NAND ignores all bus transactions until receiving CMD1.
e-NAND begins boot operation with the argument of 0xFFFFFFFA. If boot acknowledge is finished, e-NAND shall send acknowledge pattern "010" to the host within the specified time. After boot operation is terminated, e-NAND enters the idle state and shall be ready for CMD1 operation. If e-NAND receives CMD1 in the pre-boot state, it begins to respond to the command and moves to the card identification mode.

● When e-NAND is initiated by alternative boot command(CMD0 with arg=0xFFFFFFFA), all the data will be read from the boot partition and then e-NAND automatically goes to idle state, but hosts are still required to issue CMD0 with arg=0x0000000000 in order to complete a boot mode properly and move to the idle state. While in the idle state, e-NAND ignores all bus transactions until it receives CMD1.

● CMD1 is a special synchronization command which is used to negotiate the operating voltage range and poll the device until it is out of its power-up sequence. In addition to the operating voltage profile of the device, the response to CMD1 contains a busy flag indicating that the device is still working on its power-up procedure and is not ready for identification. This bit informs the host that the device is not ready, and the host must wait until this bit is cleared. The device must complete its initialization within 1 second of the first CMD1 issued with a valid OCR range.

● If the e-NAND device was successfully partitioned during the previous power up session (bit 0 of EXT_CSD byte [155] PARTITION_SETTING_COMPLETE successfully set) then the initialization delay is (instead of 1s) calculated from INI_TIMEOUT_PA (EXT_CSD byte [241]). This timeout applies only for the very first initialization after successful partitioning. For all the consecutive initialization 1sec time out will be applied.

● The bus master moves the device out of the idle state. Because the power-up time and the supply ramp-up time depend on the application parameters such as the bus length and the power supply unit, the host must ensure that power is built up to the operating level (the same level that will be specified in CMD1) before CMD1 is transmitted.

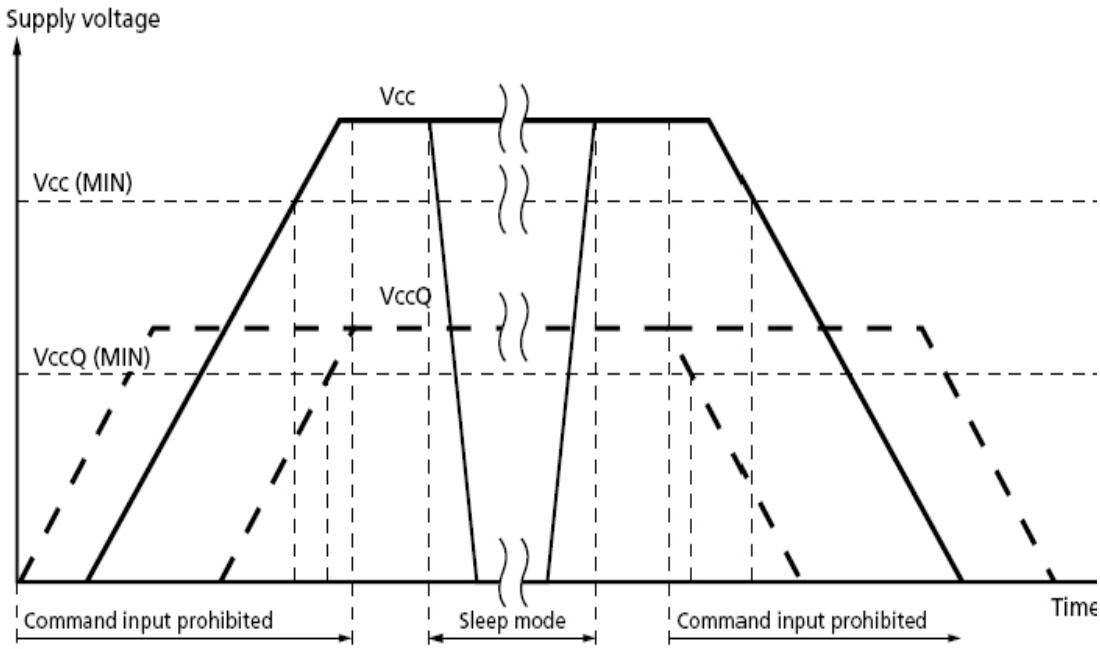
● After power-up, the host starts the clock and sends the initializing sequence on the CMD line. The sequence length is the longest of: 1ms, 74 clocks, the supply ramp-up time, or the boot operation period. An additional 10 clocks (beyond the 64 clocks of the power-up sequence) are provided to eliminate power-up synchronization problems.

● Every bus master must implement CMD1.

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5.3.2 e-NAND Power Cycling

The master can execute any sequence of V_{cc} and V_{ccq} power-up/power-down. However, the master must not issue any commands until V_{cc} and V_{ccq} are stable within each operating voltage range. After the slave enters sleep mode, the master can power-down V_{cc} to reduce power consumption. It is necessary for the slave to be ramped up to V_{cc} before the host issues CMD5 (SLEEP_AWAKE) to wake the slave unit.



[Figure 19] e-NAND power cycle

If V_{cc} or V_{ccq} is below 0.5 V for longer than 1 ms, the slave shall always return to the pre-idle state, and perform the appropriate boot behavior. The slave will behave as in a standard power up condition once the voltages have returned to their functional ranges.
An exception to this behavior is if the device is in sleep state, in which the voltage on V_{cc} is not monitored.

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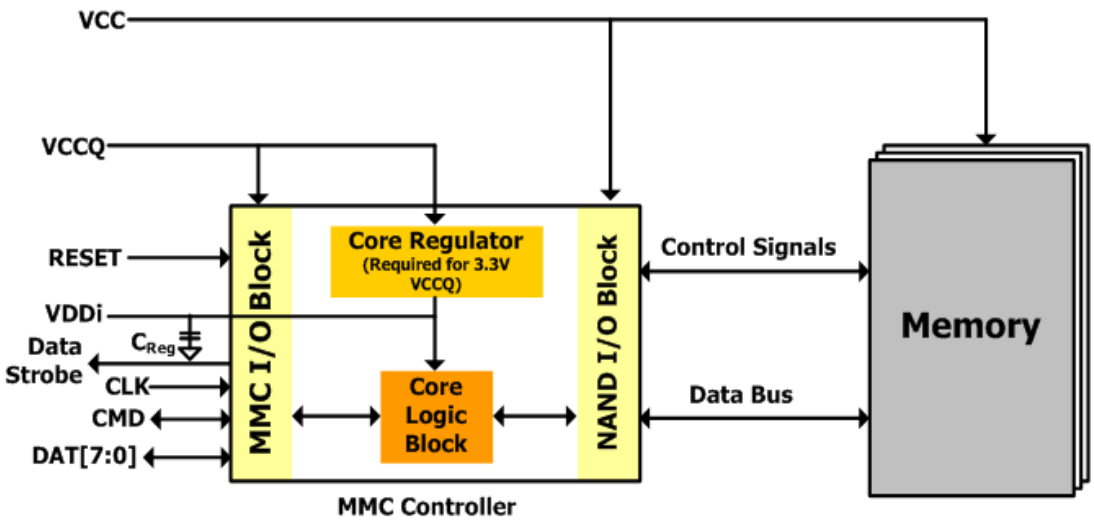
5.3.3 Leakage

Parameter	Symbol	Min	Max.	Unit	Remark
	BGA	-0.5	V_{ccq}+0.5	V	
All inputs					
Input leakage current (before initialization sequenceand/or the internalpull up resistors connected)		-100	100	μA	
All outputs					
Output leakage current (before initialization sequence)		-100	100	μA	
Output leakage current (after initialization sequence)		-2	2	μA	

[Table 17] General operation conditions

5.3.4 Power Supply

In e-NAND, V_{cc} is used for the NAND core voltage and NAND interface; V_{ccq} is for the controller core and e-NAND interface voltage shown in Figure 15. The core regulator is optional and only required when internal core logic voltage is regulated from V_{ccq}. A Creg capacitor must be connected to the VDDi terminal to stabilize regulator output on the system.



[Figure 20] e-NAND internal power diagram

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e-NAND supports one or more combinations of V_{cc} and V_{ccq} as shown in Table 18.
The available voltage configuration is shown in Table 19.

Parameter	Symbol	Min	Max.	Unit	Remark
Supply voltage (NAND)	V_{cc}	2.7	3.6	V	
		1.7	1.95	V	Not supported
Supply voltage (I/O)	V_{ccq}	2.7	3.6	V	
		1.7	1.95	V	
Supply power-up for 3.3V	t_{PRUH}		35	ms	
Supply power-up for 1.8V	t_{PRUL}		25	ms	

[Table 18] e-NAND power supply voltage

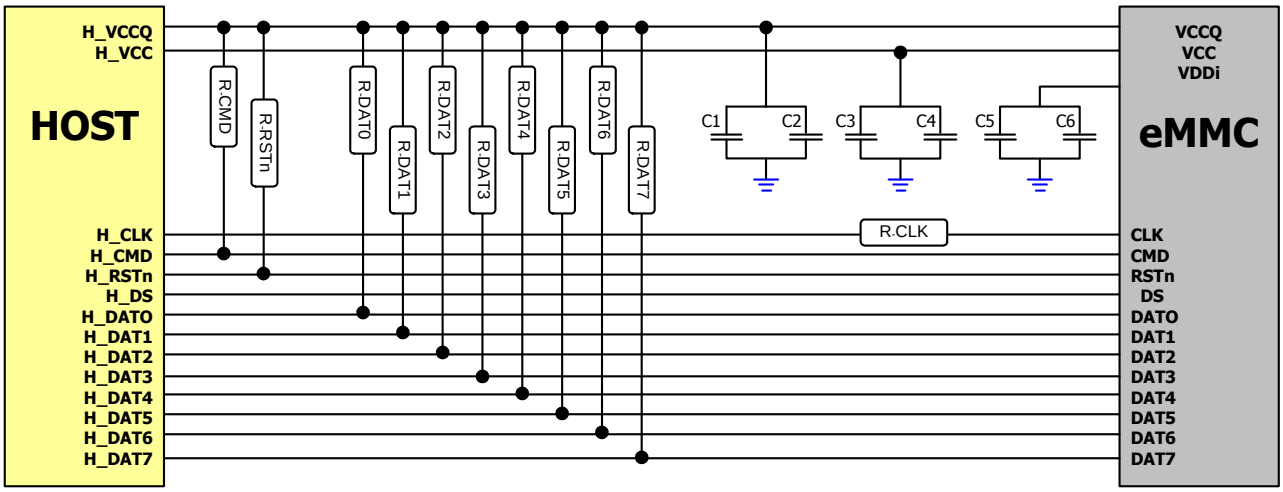
		V_{ccq}	
		1.7V ~ 1.95V	**2.7V ~ 3.6V**
V_{cc}	**2.7V–3.6V**	Valid	Valid (1)
	1.7V–1.95V	Not Valid	Not Valid

[Table 19] e-NAND voltage combinations

- NOTE 1. VccQ(I/O) 3.3 volt range is not supported in either HS200 or HS400 devices.

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5.4 Connection Guide



[Figure 21] Connection guide drawing

Parameter	Symbol	Min	Max	Recommend	Unit	Remark
Pull-up resistance for CMD	R_CMD	4.7	100	10	kohm	Pull-up resistance should be put on CMD line to prevent bus floating.
Pull-up resistance for DAT0~7	R_DAT	10	100	50	kohm	Pull-up resistance should be put on DAT line to prevent bus floating.
Data strobe(DS)	R_DS	NC	NC	NC	-	It is not necessary to put pull-up/pull-down resistance on DS line since DS is internally pulled down. Direct connection to host is required and please float this pin if it is not used
Pull-up resistance for RSTn	R_RSTn	10	100	50	kohm	It is not necessary to put pull-up resistance on RSTn line if host does not use H/W reset. (Extended CSD register [162] = 0b)
Serial resistance on CLK	R_CLK	0	30	27	ohm	To reduce overshooting/undershooting Note: If the host uses HS200, we recommend to remove this resister for better CLK signal
V_{ccq} capacitor value	C1 & C2	2±0.22	4.7	2±0.22	uF	Coupling cap should be connected with V_{ccq} closely.
V_{cc} capacitor value(≤8GB)	C3 & C4	4.72±10%	10	4.72±10%	uF	Coupling cap should be connected with V_{cc} closely. V_{cc} /V_{ccq} cap. value would be up to Host requirement and the application system characteristics.
V_{cc} capacitor value(>8GB)						
VDDi capacitor value	C5 & C6	0	2.2	0.1	uF	Coupling cap should be connected with VDDi and Vssq as closely possible. (Internal Cap : 1uF)

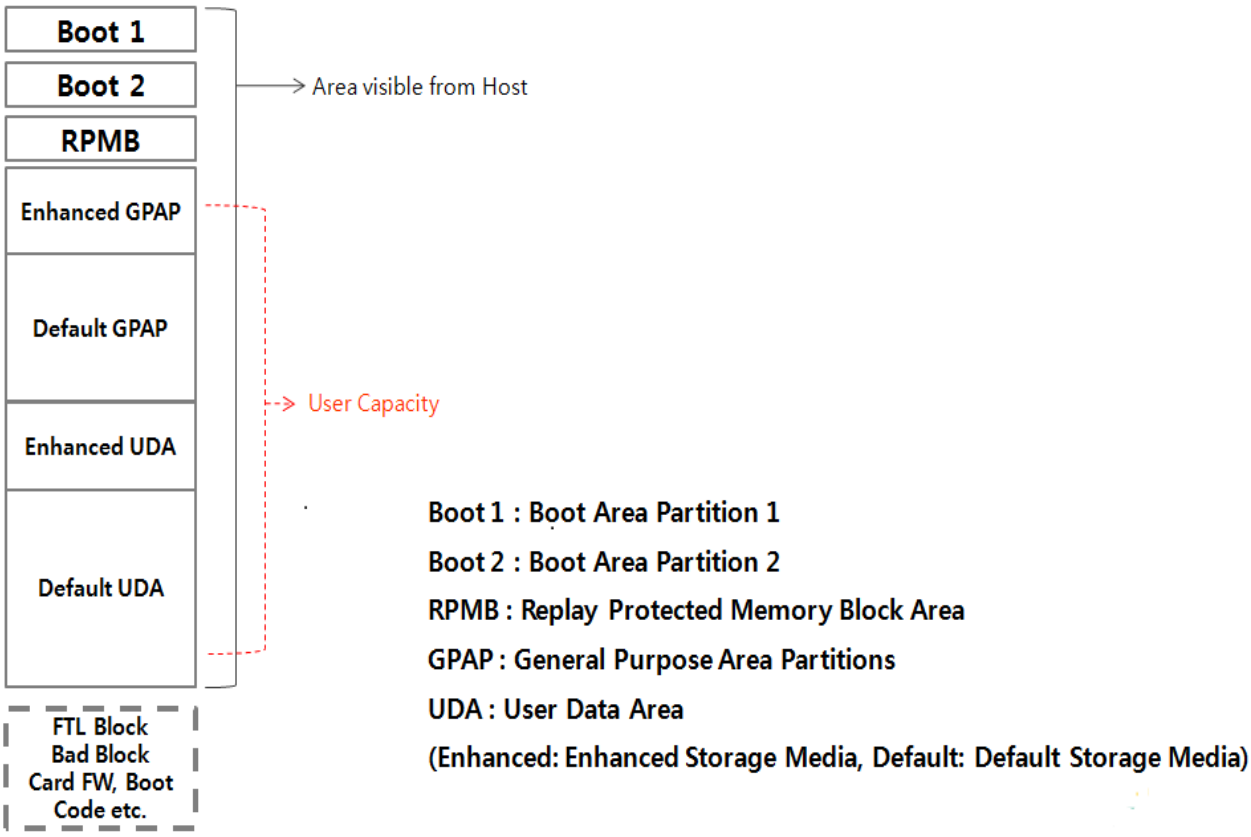
[Table 20] Connection guide specification

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6. e-NAND basic operations

6.1 Partitioning

6.1.1 User density



[Figure 22] Partition diagram

■ Boot and RPMD partition size

Density	Boot 1,2 and RPMB partition size
8GB	4096KB (4MB)
16GB	
32GB	
64GB	

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■ User density size

Capacity	SEC_COUNT	Capacity	Percentile
8GB	15,269,888 (0xE90000)	7,818,182,656 Bytes (7.28GB)	91.02%
16GB	30,777,344 (0x1D5A000)	15,758,000,128 Bytes (14.68GB)	91.72%
32GB	61,071,360 (0x3A3E000)	31,268,536,320 Bytes (29.12GB)	91.00%
64GB	122,142,720 (0x747C000)	62,537,072,640 Bytes (58.24GB)	91.00%

- 1sector=512 bytes.
- The total usable capacity of the e-NAND may be less than total physical capacity because a small portion of the capacity is used for NAND flash management and maintenance purpose.

■ Maximum enhanced partition size

Enhanced user data area can be configured to store read-centric data such as sensitive data or for other host usage models.
SK hynix e-NAND supports Enhanced User Data Area as SLC Mode. When customer adopts some portion as enhanced user data area in User Data Area, that area occupies double the size of the original set-up size.

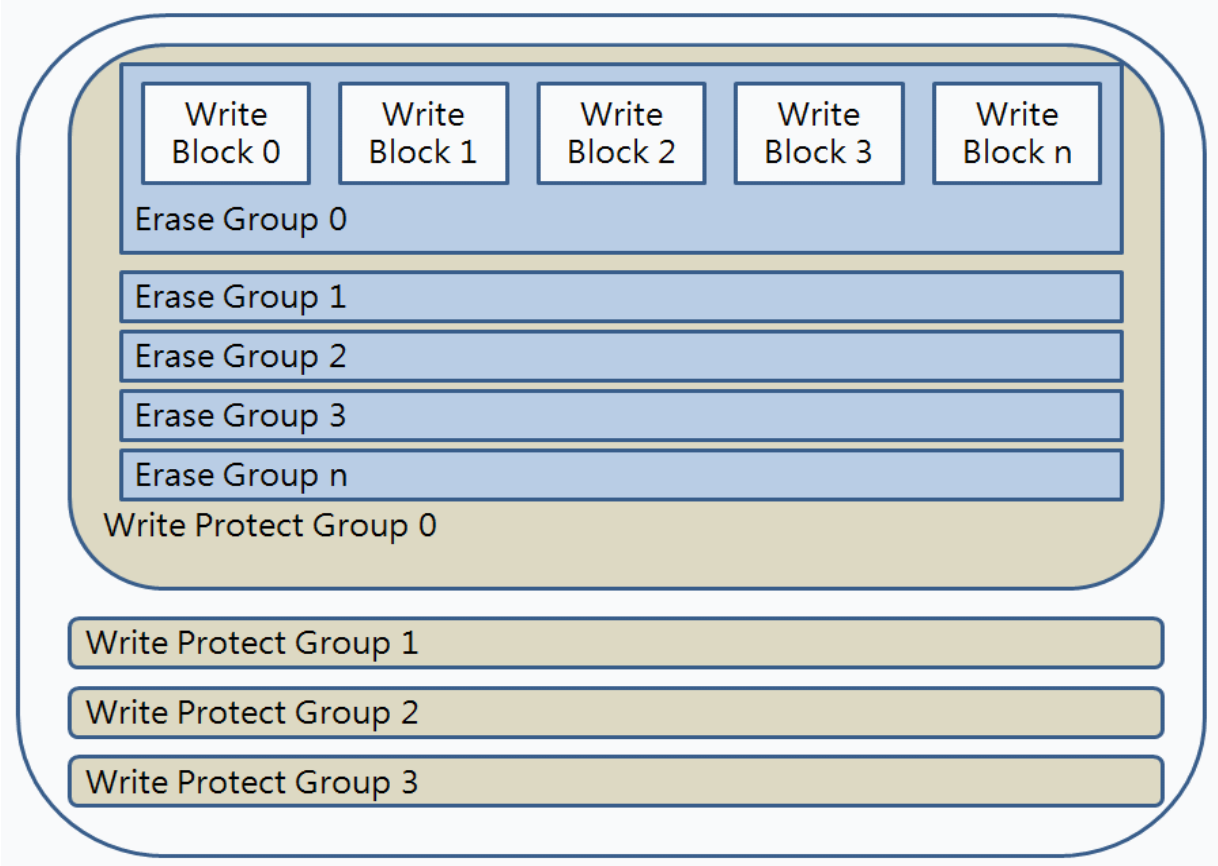
Capacity	Max ENH_SIZE_MULTI	HC_ERASE_GRP_SIZE	HC_WP_GRP_SIZE
8GB	0x0003A4	1h	08h
16GB	0x000756	1h	08h
32GB	0x000E8F	1h	08h
64GB	0x001D1F	1h	08h

- Max Enhanced Partition Size is defined as **MAX_ENH_SIZE_MULT x HC_WP_GRP_SIZE x HC_ERASE_GRP_SIZE x 512KByte.**

Capacity	Capacity (KB)
8GB	3,817,472
16GB	7,692,288
32GB	15,265,792
64GB	30,535,680

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6.1.2 Erase / Write protect group size



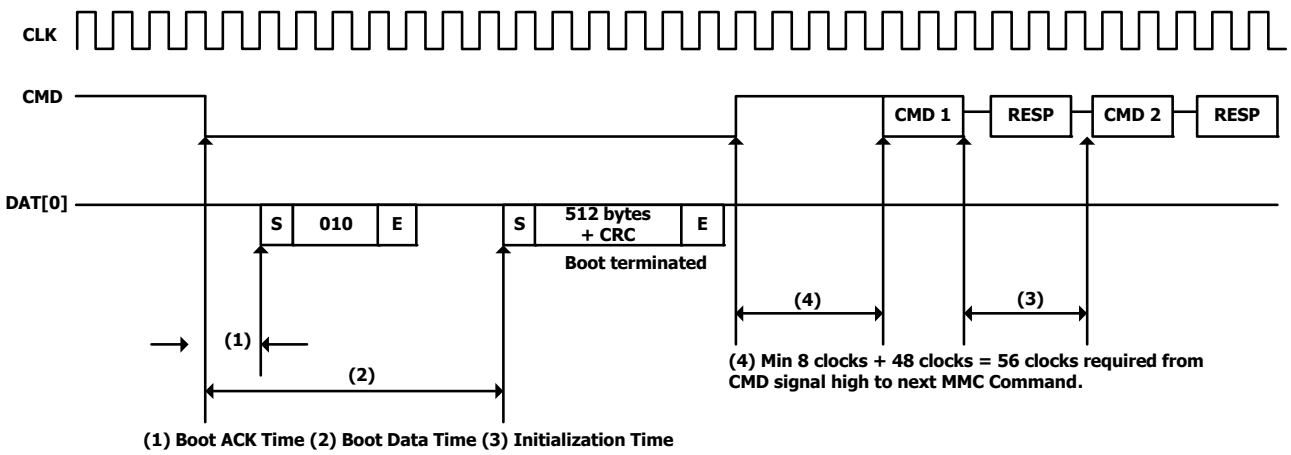
Density	Erase group size		Write protect group size
	ERASE_GROUP_DEF=0	ERASE_GROUP_DEF=1	
8GB	512KB	512KB	4MB
16GB	512KB	512KB	4MB
32GB	512KB	512KB	4MB
64GB	512KB	512KB	4MB

[Table 21] Erase/Write protect Group size

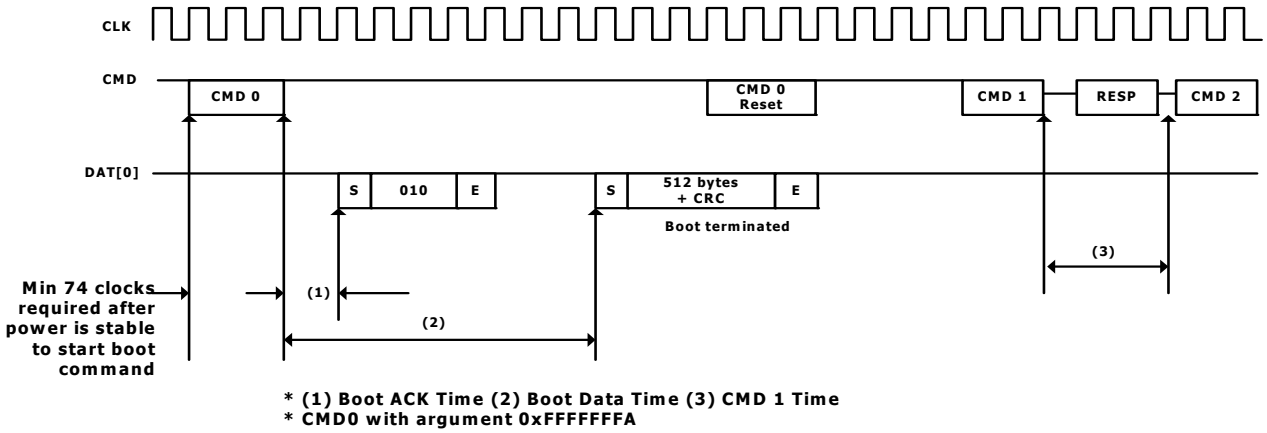
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6.2 Boot operation

e-NAND supports boot mode and alternative boot mode. e-NAND also, supports high speed timing and dual data rate during boot.



[Figure 23] e-NAND state diagram (Boot mode)



[Figure 24] e-NAND state diagram (Alternative boot mode)

Timing Factor	Value
(1) Boot ACK Time	< 50 ms
(2) Boot Data Time	< 1 sec
(3) Initialization Time	< 1 sec

- Initialization time includes partition setting, Please refer to INI_TIMEOUT_AP in 7.4 Extended CSD Register. Initialization time is completed within 1sec from issuing CMD1 until receiving response.
- The device has to send the acknowledge pattern "010" to the master within 50ms after the CMD0 with the argument of 0xFFFFFFFA is received.

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7. Time out

Latency Item	Value	Remark
Write Time out (CMD To 512KB Write Done)	Max 1s	No read/program/erase failure case
Write Time out (Data To Data)	Max 500ms	
Read Time Out (CMD To the first data out)	Max 100ms	No read/program/erase failure case
Initialization Time	Max 1s	
Initialization Time (After Partitioning)	Max 3s	
Initialization after PON (Short/long)	Max 180ms	
Pre-Boot to ACK	Max 50ms	
Pre-Boot to Boot Data	Max 200ms	
Partition Switch	Max 10ms	
CMD6 Switch	Max 50ms	
CMD8 time out	Max 5ms	
Erase (Erase Group)	Max 600ms	
Trim (512B~512KB)	Max 600ms	
Discard (512B~512KB)	Max 600ms	

[Table 22] Time out value

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Latency Item	Value		Remark
Secure Trim1 Type 0, 1 (512B~512KB)	Max 5.1s		Type 0 : information removed by an erase of the physical memory Type 1 : information removed by an overwriting the addressed locations with a character followed by an erase Type 2 : Not support Type 3 : information unmapped
Secure Trim1 Type 3 (512B~512KB)	Max 600ms		
Secure Erase Type 0,1 (Write Block 512KB)	Max 8.1s		
Secure Erase Type 3 (Write Block 512KB)	Max 600ms		
Sanitize (UDA Area)	8GB	Max 30min	
	16GB	Max 30min	
	32GB	Max 30min	
	64GB	Max 60min	
Force Erase (UDA Area)	Max 3min		
HPI	Max 50ms		
Sliding Window	Max 256ms		For 256kB randomly write case
PON Busy Time (Short/Long)	Max 50ms / 1000ms		PON long includes GC PON short not include GC
CMD6 Switch	Max 50ms		

[Table 22] Time out value (Continue)

- Be advised timeout values specified in table above are for testing purpose under SK hynix test pattern only and actual timeout situations may vary

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8. Device registers

There are six different registers within the device interface:

- Operation conditions register (OCR)
- Card identification register (CID)
- Card specific data register (CSD)
- Relative card address register (RCA)
- DSR (Driver Stage Register)
- Extended card specific data register (EXT_CSD).

These registers are used for the serial data communication and can be accessed only using the corresponding commands.
e-NAND has a status register to provide information about the current device state and completion codes for the last host command.

8.1 Operation conditions register (OCR)

The 32-bit operation conditions register (OCR) stores the VDD voltage profile of e-NAND and the access mode indication. In addition, this register includes a status information bit. This status bit is set if e-NAND power up procedure has been finished.

OCR bit	Description	SK hynix e-NAND
[6:0]	Reserved	000 0000b
[7]	1.70 - 1.95V	1b
[14:8]	2.0 - 2.6	000 0000b
[23:15]	2.7 - 3.6 (High V_{ccq} range)	1111 1111 1b
[28:24]	Reserved	000 000b
[30:29]	Access mode	10b (sector mode)
[31]	(card power up status bit (busy))**(1)**	

[Table 23] OCR register definition

● NOTE 1. This bit is set to LOW if the card has not finished the power up routine

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8.2 Card identification (CID) register

The card identification (CID) register is 128 bits wide. It contains e-NAND identification information used during e-NAND identification phase (e-NAND protocol). Every individual e-NAND has a unique identification number. The structure of the CID register is defined in the following sections.

Name	Field	Width	CID slice	CID value	Remark
Manufacturer ID	MID	8	[127:120]	0X90	
Reserved		6	[119:114]		
Card/BGA	CBX	2	[113:112]	0X1	BGA
OEM/application ID	OID	8	[111:104]	0X4A	
Product name	PNM	48	[103:56]	8GB: 0x483847346132 16GB: 0X484147346132 32GB: 0X484247346132 64GB: 0X484347346132	1)
Product revision	PRV	8	[55:48]	-	2)
Product serial number	PSN	32	[47:16]	-	3)
Manufacturing date	MDT	8	[15:8]	-	
CRC7 checksum	CRC	7	[7:1]	-	
Not used, always '1'		1	[0:0]	0X1	

1) PNM rule may be updated
2) PRV composed of the revision count of controller and the revision count of F/W patch
3) If PSN is to be used as a Unique ID, a composition PSN and MDT should be used.
Whole CID can also be used to generate a unique ID

[Table 24] Card identification (CID) fields

8.3 Card specific data register (CSD)

The card specific data (CSD) register provides information on how to access e-NAND contents. The CSD defines the data format, error correction type, maximum data access time, data transfer speed and so on. The programmable part of the register (entries marked by W or E, see below) can be changed by CMD27. The type of the CSD Registry entries in the Table 25 below is coded as follows:

- R: Read only.
- W: One time programmable and not readable.
- R/W: One time programmable and readable.
- W/E: Multiple writable with value kept after power failure, H/W reset assertion and any CMD0 reset and not readable.
- R/W/E: Multiple writable with value kept after power failure, H/W reset assertion and any CMD0 reset and readable.
- R/W/C_P: Writable after value cleared by power failure and HW/rest assertion (the value not cleared by CMD0 reset) and readable.
- R/W/E_P: Multiple writable with value reset after power failure, H/W reset assertion and any CMD0 reset and readable.
- W/E_P: Multiple writable with value reset after power failure, H/W reset assertion and any CMD0 reset and not readable.

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Name	Field	Width	Cell type	CSD slice	CSD value	Remark
CSD structure	CSD_STRUCTURE	2	R	[127:126]	0X03	
System specification version	SPEC_VERS	4	R	[125:122]	0X04	
Reserved		2	R	[121:120]	-	
Data read access-time 1	TAAC	8	R	[119:112]	0X27	
Data read access-time 2 in CLK cycles (NSAC*100)	NSAC	8	R	[111:104]	0X01	
Max. bus clock frequency	TRAN_SPEED	8	R	[103:96]	0X32	
Card command classes	CCC	12	R	[95:84]	0X8F5	
Max. read data block length	READ_BL_LEN	4	R	[83:80]	0X09	
Partial blocks for read allowed	READ_BL_PARTIAL	1	R	[79:79]	0X00	
Write block misalignment	WRITE_BLK_MISALIGN	1	R	[78:78]	0X00	
Read block misalignment	READ_BLK_MISALIGN	1	R	[77:77]	0X00	
DSR implemented	DSR_IMP	1	R	[76:76]	0X00	
Reserved		2	R	[75:74]	-	
Device size	C_SIZE	12	R	[73:62]	0XFFF	
Max. read current @ VDD min	VDD_R_CURR_MIN	3	R	[61:59]	0X07	
Max. read current @ VDD max	VDD_R_CURR_MAX	3	R	[58:56]	0X07	
Max. write current @ VDD min	VDD_W_CURR_MIN	3	R	[55:53]	0X07	
Max. write current @ VDD max	VDD_W_CURR_MAX	3	R	[52:50]	0X07	
Device size multiplier	C_SIZE_MULT	3	R	[49:47]	0X07	
Erase group size	ERASE_GRP_SIZE	5	R	[46:42]	0X1F	
Erase group size multiplier	ERASE_GRP_MULT	5	R	[41:37]	0X1F	
Write protect group size	WP_GRP_SIZE	5	R	[36:32]	8GB: 0x07 16/32GB : 0x07 64GB: 0x0F	
Write protect group enable	WP_GRP_ENABLE	1	R	[31:31]	0X01	
Manufacturer default ECC	DEFAULT_ECC	2	R	[30:29]	0X00	
Write speed factor	R2W_FACTOR	3	R	[28:26]	0X02	

[Table 25]CSD fields

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Name	Field	Width	Cell type	CSD slice	CSD value	Remark
Max. write data block length	WRITE_BL_LEN	4	R	[25:22]	0X09	
Partial blocks for write allowed	WRITE_BL_PARTIAL	1	R	[21:21]	0X00	
Reserved		4	R	[20:17]	-	
Content protection application	CONTENT_PROT_APP	1	R	[16:16]	0X00	
File format group	FILE_FORMAT_GRP	1	R/W	[15:15]	0X00	
Copy flag (OTP)	COPY	1	R/W	[14:14]	0X00	
Permanent write protection	PERM_WRITE_PROTECT	1	R/W	[13:13]	0X00	
Temporary write protection	TMP_WRITE_PROTECT	1	R/W/E	[12:12]	0X00	
File format	FILE_FORMAT	2	R/W	[11:10]	0X00	
ECC code	ECC	2	R/W/E	[9:8]	0X00	
CRC	CRC	7	R/W/E	[7:1]	-	
Not used, always '1'		1		[0:0]	0X01	

[Table 25] CSD fields (continued)

The following sections describe the CSD fields and the relevant data types. If not explicitly defined otherwise, all bit strings are interpreted as binary coded numbers starting with the left bit first.

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8.4 Extended CSD register

The Extended CSD register defines e-NAND properties and selected modes. It is 512 bytes long. The most significant 320 bytes are the Properties segment, which defines e-NAND capabilities and cannot be modified by the host. The lower 192 bytes are the modes segment, which defines the configuration e-NAND is working in. These modes can be changed by the host by means of the switch command.

Name	Field	CSD slice	Cell Type	CSD value	Remark
Properties segment					
Reserved		[511:506]			
Extended Security Commands Error	EXT_SECURITY_ERR	[505]	R	0x00	
Supported command sets	S_CMD_SET	[504]	R	0x01	
HPI features	HPI_FEATURES	[503]	R	0x01	
Background operations support	BKOPS_SUPPORT	[502]	R	0x01	
Max packed read commands	MAX_PACKED_READS	[501]	R	0x3F	
Max packed write commands	MAX_PACKED_WRITES	[500]	R	0x3F	
Data Tag Support	DATA_TAG_SUPPORT	[499]	R	0x01	
Tag Unit Size	TAG_UNIT_SIZE	[498]	R	0x00	
Tag Resources Size	TAG_RES_SIZE	[497]	R	0x00	
Context management capabilities	CONTEXT_CAPABILITIES	[496]	R	0x78	
Large Unit size	LARGE_UNIT_SIZE_M1	[495]	R	0x01	
Extended partitions attribute support	EXT_SUPPORT	[494]	R	0x03	
Supported modes	SUPPORTED_MODES	[493]	R	0x01	
FFU features	FFU_FEATURES	[492]	R	0x00	
Operation codes timeout	OPERATION_CODE_TIME OUT	[491]	R	0x00	
FFU Argument	FFU_ARG	[490:487]	R	0xFFFAFFF0	
Barrier support	BARRIER_SUPPORT	[486]	R	0x01	
Reserved		[485:309]		-	
CMD Queuing Support	**CMDQ_SUPPORT**	**[308]**	R	**0x1**	
CMD Queuing Depth	**CMDQ_DEPTH**	**[307]**	R	**0x1F**	
Reserved		[306]		-	
Number of FW sectors correctly programmed	NUMBER_OF_FW_SECTORS_CORRECTLY_PROGRAMMED	[305:302]	R	0x00000000	
Vendor proprietary health report	VENDOR_PROPRIETARY_HEALTH_REPORT	[301:270]	R	-	None

[Table 26] Extended CSD

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Name	Field	CSD slice	Cell Type	CSD value	Remark
Device life time estimation type B	DEVICE_LIFE_TIME_EST_TYP_B	[269]	R	0x01	
Device life time estimation type A	DEVICE_LIFE_TIME_EST_TYP_A	[268]	R	0x01	
Pre EOL information	PRE_EOL_INFO	[267]	R	0x01	
Optimal read size	OPTIMAL_READ_SIZE	[266]	R	0x40	
Optimal write size	OPTIMAL_WRITE_SIZE	[265]	R	0x40	
Optimal trim unit size	OPTIMAL_TRIM_UNIT_SIZE	[264]	R	0x07	
Device version	DEVICE_VERSION	[263:262]	R	-	Not fixed
Firmware version	FIRMWARE_VERSION	[261:254]	R	-	Same to PRV
Power class for 200MHz, DDR at Vcc=3.6V	PWR_CL_DDR_200_360	[253]	R	0x22	
Cache size	CACHE_SIZE	[252:249]	R	0x0000400	
Generic CMD6 timeout	GENERIC_CMD6_TIME	[248]	R	0x05	
Power off Notification (long) timeout	POWER_OFF_LONG_TIME	[247]	R	0x64	
Background operations status	BKOPS_STATUS	[246]	R	0x00	
Number of correctly programmed sectors	CORRECTLY_PRG_SECTORS_NUM	[245:242]	R	-	Not fixed
1st initialization time after partitioning	INI_TIMEOUT_AP	[241]	R	0x0A	
Cache Flushing Policy	CACHE_FLUSH_POLICY	[240]	R	0x01	
Power class for 52MHz, DDR at Vcc=3.6V	PWR_CL_DDR_52_360	[239]	R	0x11	
Power class for 52MHz, DDR at Vcc=1.95V	PWR_CL_DDR_52_195	[238]	R	0x00	Not support
Power class for 200MHz at Vccq=1.95, Vcc=3.6V	PWR_CL_200_195	[237]	R	0x22	
Power class for 200MHz at Vccq=1.3, Vcc=3.6V	PWR_CL_200_130	[236]	R	0x00	Not support
Minimum write performance for 8bit at 52MHz in DDR mode	MIN_PERF_DDR_W_8_52	[235]	R	0x78	
Minimum read performance for 8bit at 52MHz in DDR mode	MIN_PERF_DDR_R_8_52	[234]	R	0x8C	
Reserved		[233]			
TRIM multiplier	TRIM_MULT	[232]	R	0x02	
Secure feature support	SEC_FEATURE_SUPPORT	[231]	R	0x55	
Secure erase multiplier	SEC_ERASE_MULT	[230]	R	8GB : 0x19 16GB : 0x32 32/64GB : 0x64	
Secure TRIM multiplier	SEC_TRIM_MULT	[229]	R	0x0A	

[Table 26] Extended CSD(Continued)

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Name	Field	CSD slice	Cell Type	CSD value	Remark
Boot information	BOOT_INFO	[228]	R	0x07	
Reserved		[227]		-	
Boot partition size	BOOT_SIZE_MULTI	[226]	R	0x20	
Access size	ACC_SIZE	[225]	R	0x06	
High-capacity erase unit size	HC_ERASE_GRP_SIZE	[224]	R	0x01	
High-capacity erase timeout	ERASE_TIMEOUT_MULT	[223]	R	0x02	
Reliable write sector count	REL_WR_SEC_C	[222]	R	0x01	
High-capacity write protect group size	HC_WP_GRP_SIZE	[221]	R	8GB : 0x08 16/32GB : 0x08 64GB : 0x10	
Sleep current(Vcc)	S_C_Vcc	[220]	R	0x07	
Sleep current(Vccq)	S_C_Vccq	[219]	R	0x07	
Production state awareness timeout	PRODUCTION_STATE_ AWARENES S_TIMEOUT	[218]	R	0x00	
Sleep/awake timeout	S_A_TIMEOUT	[217]	R	0x11	
Sleep Notification Timeout	SLEEP_NOTIFICATION_TIME	[216]	R	0x0C	
Sector count	SEC_COUNT	[215:212]	R	8GB: 0xE90000 16GB: 0X1D5A000 32GB: 0X03A3E000 64GB: 0X747C000	
Secure Write Protect information	**SECURE_WP_INFO**	**[211]**	**R**	**0x01**	
Minimum write performance for 8bit at52MHz	MIN_PERF_W_8_52	[210]	R	0x8C	
Minimum read performance for 8bit at 52MHz	MIN_PERF_R_8_52	[209]	R	0x8C	
Minimum write performance for 8bit at 26MHz, for 4bit at 52MHz	MIN_PERF_W_8_26_4_52	[208]	R	0x46	
Minimum read performance for 8bit at 26MHz, for 4bit at 52MHz	MIN_PERF_R_8_26_4_52	[207]	R	0x46	
Minimum write performance for 4bit at 26MHz	MIN_PERF_W_4_26	[206]	R	0x1E	
Minimum read performance for 4bit at 26MHz	MIN_PERF_R_4_26	[205]	R	0x1E	
Reserved		[204]			
Power class for 26MHz at 3.6V	PWR_CL_26_360	[203]	R	0x00	
Power class for 52MHz at 3.6V	PWR_CL_52_360	[202]	R	0x00	
Power class for 26MHz at 1.95V	PWR_CL_26_195	[201]	R	0x00	Not support
Power class for 52MHz at 1.95V	PWR_CL_52_195	[200]	R	0x00	Not support

[Table 26] Extended CSD(Continued)

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Name	Field	CSD slice	Cell Type	CSD value	Remark
Partition switching timing	PARTITION_SWITCH_TIME	[199]	R	0x01	
Out-of-interrupt busy timing	OUT_OF_INTERRUPT_TIME	[198]	R	0x05	
I/O Driver Strength	DRIVER_STRENGTH	[197]	R	0x1F	
Device type	DEVICE_TYPE	[196]	R	0x57	
Reserved		[195]		-	
CSD structure	CSD_STRUCTURE	[194]	R	0x02	
Reserved		[193]		-	
Extended CSD revision	EXT_CSD_REV	[192]	R	0x08	
Modes Segment					
Command set	CMD_SET	[191]	R/W/E_P	0x00	
Reserved		[190]		-	
Command set revision	CMD_SET_REV	[189]	R	0x00	
Reserved		[188]		-	
Power class	POWER_CLASS	[187]	R/W/E_P	0x00	
Reserved		[186]		-	
High-speed interface timing	HS_TIMING	[185]	R/W/E_P	0x00	
Strobe Support	**STROBE_SUPPORT**	**[184]**	**R**	**0x01**	
Bus width mode	BUS_WIDTH	[183]	W/E_P	0x00	
Reserved		[182]		-	
Erased memory content	ERASED_MEM_CONT	[181]	R	0x00	
Reserved		[180]		-	
Partition configuration	PARTITION_CONFIG	[179]	R/W/E & R/W/E_P	0x00	
Boot config protection	BOOT_CONFIG_PROT	[178]	R/W/E & R/W/C_P	0x00	
Boot bus conditions	BOOT_BUS_CONDITIONS	[177]	R/W/E	0x00	
Reserved		[176]		-	
High-density erase group definition	ERASE_GROUP_DEF	[175]	R/W/E_P	0x00	
Boot write protection status registers	BOOT_WP_STATUS	[174]	R	0x00	
Boot area write protection register	BOOT_WP	[173]	R/W/E & R/W/C_P	0x00	
Reserved		[172]		-	

[Table 26] Extended CSD(Continued)

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Name	Field	CSD slice	Cell Type	CSD value	Remark
User area write protection register	USER_WP	[171]	R/W, R/W/C_P & /W/E_P	0x00	
Reserved		[170]		-	
FW configuration	FW_CONFIG	[169]	R/W	0x00	
RPMB Size	RPMB_SIZE_MULT	[168]	R	0x20	
Write reliability setting register	WR_REL_SET	[167]	R/W	0x1F	
Write reliability parameter register	WR_REL_PARAM	[166]	R	0x15	
Sanitize start	SANITIZE_START	[165]	W/E_P	0x00	
Manually start background operations	BKOPS_START	[164]	W/E_P	0x00	
Enable background operations Handshake	BKOPS_EN	[163]	R/W	0x00	
H/W reset function	RST_n_FUNCTION	[162]	R/W	0x00	
HPI management	HPI_MGMT	[161]	R/W/E_P	0x00	
Partitioning support	PARTITIONING_SUPPORT	[160]	R	0x07	
Max enhanced area size	MAX_ENH_SIZE_MULT	[159:157]	R	8GB: 0x0003A4 16GB: 0X000756 32GB: 0X000E8F 64GB: 0X000E8F	
Partitions attribute	PARTITIONS_ATTRIBUTE	[156]	R/W	0x00	
Partitioning setting	PARTITION_SETTING_COMPLETED	[155]	R/W	0x00	
General purpose partition size	GP_SIZE_MULT	[154:143]	R/W	0x00	
Enhanced user data area size	ENH_SIZE_MULT	[142:140]	R/W	0x00	
Enhanced user data start address	ENH_START_ADDR	[139:136]	R/W	0x00	
Reserved		[135]		-	
Bad Block management mode	SEC_BAD_BLK_MGMNT	[134]	R/W	0x00	
Production state awareness	PRODUCTION_STATE_AWARENESS	[133]	R/W/E	-	
Package Case Temperature is Controlled	TCASE_SUPPORT	[132]	W/E_P	0x00	
Periodic Wake-up	PERIODIC_WAKEUP	[131]	R/W/E	0x00	
Program CID/CSD in DDR mode support	PROGRAM_CID_CSD_DDR_SUPPORT	[130]	R	0x00	
Reserved		[129:128]		-	
Vendor Specific Fields	VENDOR_SPECIFIC_FIELD	[127:64]	Vendor specific	-	

[Table 26] Extended CSD(Continued)

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Name	Field	CSD slice	Cell Type	CSD value	Remark
Native sector size	NATIVE_SECTOR_SIZE	[63]	R	0x01	
Sector size emulation	USE_NATIVE_SECTOR	[62]	R/W	0x00	
Sector size	DATA_SECTOR_SIZE	[61]	R	0x00	
1st initialization after disabling sector size emulation	INI_TIMEOUT_EMU	[60]	R	0x0A	
Class 6 commands control	Class6_CTRL	[59]	R/W/E_P	0x00	
Number of addressed group to be Released	DYNCAP_NEEDED	[58]	R	0x00	
Exception events control	EXCEPTION_EVENTS_CTRL	[57:56]	R/W/E_P	0x00	
Exception events status	EXCEPTION_EVENTS_STATUS	[55:54]	R	0x0000	
Extended Partitions Attribute	EXT_PARTITIONS_ATTRIBUTE	[53:52]	R/W	0x0000	
Context configuration	CONTEXT_CONF	[51:37]	R/W/E_P	0x00...00	
Packed command status	PACKED_COMMAND_STATUS	[36]	R	0x00	
Packed command failure index	PACKED_FAILURE_INDEX	[35]	R	0x00	
Power Off Notification	POWER_OFF_NOTIFICATION	[34]	R/W/E_P	0x00	
Control to turn the Cache ON/OFF	CACHE_CTRL	[33]	R/W/E_P	0x00	
Flushing of the cache	FLUSH_CACHE	[32]	W/E_P	0x00	
Control to turn the barrier ON/OFF	**BARRIER_CONTROL**	**[31]**	**R/W**	**0x00**	
Mode config	MODE_CONFIG	[30]	R/W/E_P	0x00	
Mode operation codes	MODE_OPERATION_CODES	[29]	W/E_P	0x00	
Reserved		[28:27]		-	
FFU Status	FFU_STATUS	[26]	R	0x00	
Pre loading data size	PRE_LOADING_DATA_SIZE	[25:22]	R/W/E_P	0X00000000	
Max pre loading data size	MAX_PRE_LOADING_DATA_SIZE	[21:18]	R	8GB: 0x00E90000 16GB: 0X01D5A000 32GB: 0X03A3E000 64GB: 0X747C000	
Product state awareness enablement	PRODUCT_STATE_AWARENESS_ ENABLEMENT	[17]	R/W/E & R	0x01	
Secure Removal Type	SECURE_REMOVAL_TYPE	[16]	R/W & R	0x3B	
Command Queue Mode Enable	**CMDQ_MODE_EN**	**[15]**	**R/W/E_P**	**0x00**	
Reserved		[14:0]		-	

[Table 26] Extended CSD(Continued)

- **Reserved bits should read as "0"**
- **Obsolete values should be don't care**

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8.5 RCA (Relative card address)

The writable 16-bit relative card address (RCA) register carries the card address assigned by the host during the card identification. This address is used for the addressed host-card communication after the card identification procedure. The default value of the RCA register is 0x0001. The value 0x0000 is reserved to set all cards into the Stand-by State with CMD7.

8.6 DSR (Driver stage register)

It can be optionally used to improve the bus performance for extended operating conditions (depending on parameters like bus length, transfer rate or number of Devices). The CSD register carries the information about the DSR register usage. The default value of the DSR register is 0x404.

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