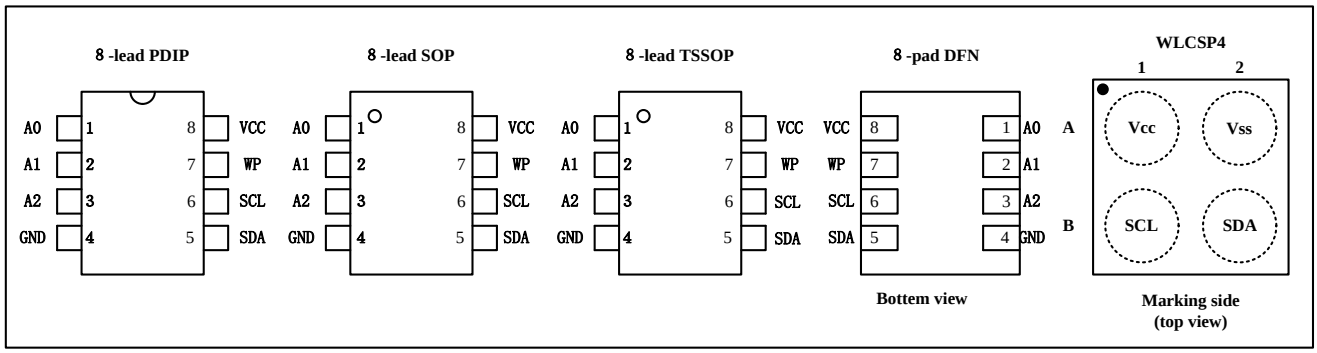
Features

- Compatible with all data transfer protocol
  - 1 MHz
  - 400 kHz
  - 100 kHz
- Memory array:
  - 128 Kbit (16 Kbytes) of EEPROM
  - Page size: 64 bytes
  - Additional Write lockable page
- Single supply voltage and high speed:
  - 1 MHz
- Write:
  - Byte Write within 3 ms
  - Page Write within 3 ms
- Operating Ambient Temperature:
  - From -40 °C up to +85 °C
- High-reliability
  - Endurance: 1 Million Write Cycles
  - Data Retention: 100 Years
- Internally Organized:
  - BL24C128A, 16,384 X 8 (128K bits)
- Two-wire Serial Interface
- Schmitt Trigger, Filtered Inputs for Noise Suppression
- Bidirectional Data Transfer Protocol
- Write Protect Pin for Hardware Data Protection
- Partial Page Writes Allowed
- Self-timed Write Cycle (5 ms max)
- 8-lead PDIP/SOP/TSSOP/UDFN/WLCSP4 packages

Description

The BL24C128A provides 131,072 bits of serial electrically erasable and programmable read-only memory (EEPROM), organized as 16,384 words of 8 bits each. The device is optimized for use in many industrial and commercial applications where low-power and low-voltage operation are essential. The BL24C128A is available in space-saving 8-lead PDIP, 8-lead SOP, and 8-lead TSSOP , WLCSP4 packages and is accessed via a two-wire serial interface. In addition, the BL24C128A is available in 1.7V (1.7V to 5.5V) version.

Pin Configuration

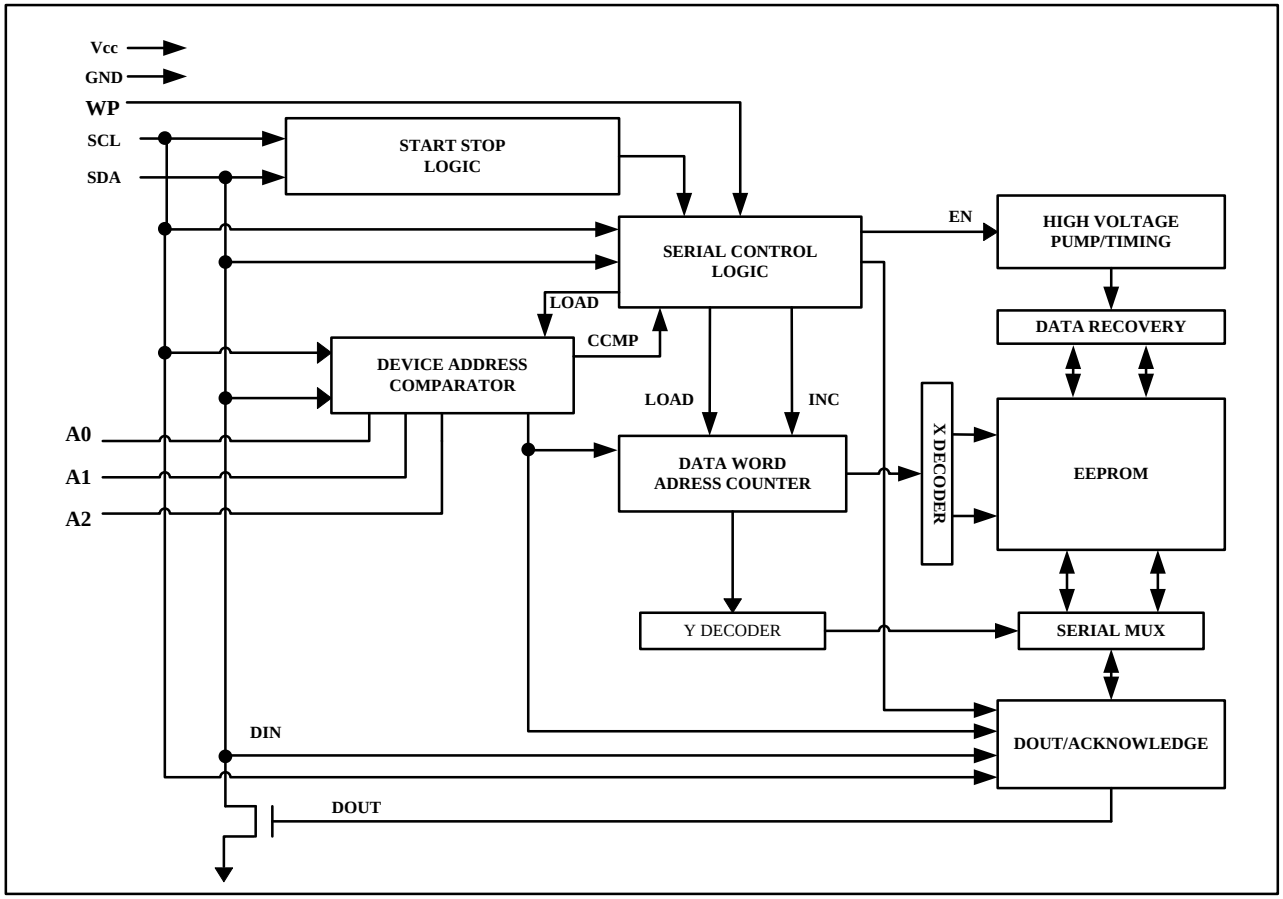


Pin Descriptions

Pin Name	Type	Functions
A0-A2	I	Address Inputs
SDA	I/O&Open-drain	Serial Data
SCL	I	Serial Clock Input
WP	I	Write Protect
GND	P	Ground
Vcc	P	Power Supply

Table 1

Block Diagram



DEVICE/PAGE ADDRESSES (A2, A1 and A0): The A2, A1 and A0 pins are device address inputs that are hard wire for the BL24C128A. Eight 128K devices may be addressed on a single bus system (device addressing is discussed in detail under the Device Addressing section).

SERIAL DATA (SDA): The SDA pin is bi-directional for serial data transfer. This pin is open-drain driven and may be wire-ORed with any number of other open-drain or open- collector devices.

SERIAL CLOCK (SCL): The SCL input is used to positive edge clock data into each EEPROM device and negative edge clock data out of each device.

WRITE PROTECT (WP): The BL24C128A has a Write Protect pin that provides hardware data protection. The Write Protect pin allows normal read/write operations when connected to ground (GND). When the Write Protection pin is connected to Vcc, the write protection feature is enabled and operates as

深圳市满度科技有限公司 ©2016 Belling All Rights Reserved www.belling.com.cn Tel:150-1290-5940
Web:www.manduic.com Email:sales@manduic.com

shown in the following Table 2.

WP Pin Status	BL24C128A
At VCC	Full(128K)Array
At GND	Normal Read/Write Operations

Table2

Functional Description

1. Memory Organization

BL24C128A, 128K SERIAL EEPROM: Internally organized with 256 pages of 64 bytes each, the 128K requires a 14-bit data word address for random word addressing.

2. Device Operation

CLOCK and DATA TRANSITIONS: The SDA pin is normally pulled high with an external device. Data on the SDA pin may change only during SCL low time periods (see Figure 1). Data changes during SCL high periods will indicate a start or stop condition as defined below.

START CONDITION: A high-to-low transition of SDA with SCL high is a start condition which must precede any other command (see Figure 2).

STOP CONDITION: A low-to-high transition of SDA with SCL high is a stop condition. After a read sequence, the stop command will place the EEPROM in a standby power mode (see Figure 2).

ACKNOWLEDGE: All addresses and data words are serially transmitted to and from the EEPROM in 8-bit words. The EEPROM sends a "0" to acknowledge that it has received each word. This happens during the ninth clock cycle.

STANDBY MODE: The BL24C128A features a low-power standby mode which is enabled: (a) upon power-up and (b) afer the receipt of the STOP bit and the completion of any internal operations.

MEMORY RESET: After an interruption in protocol, power loss or system reset, any two-wire part can be reset by following these steps:

1. Clock up to 9 cycles.

2. Look for SDA high in each cycle while SCL is high.

3. Create a start condition

深圳市满度科技有限公司 ©2016 Belling All Rights Reserved www.belling.com.cn Tel:150-1290-5940
Web:www.manduic.com Email:sales@manduic.com

Figure 1. Data Validity

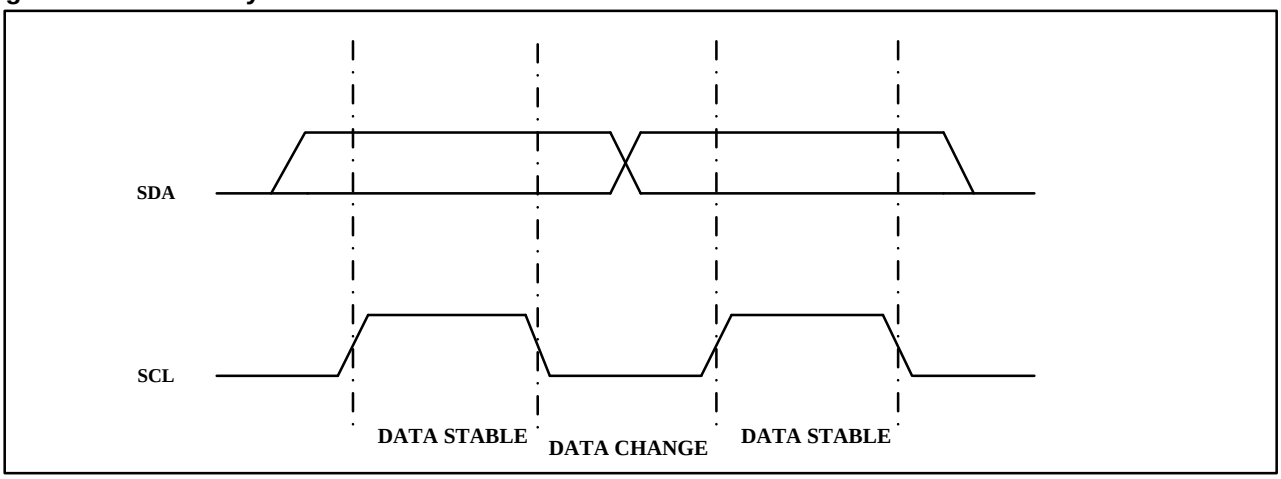


Figure 2. Start and Stop Definition

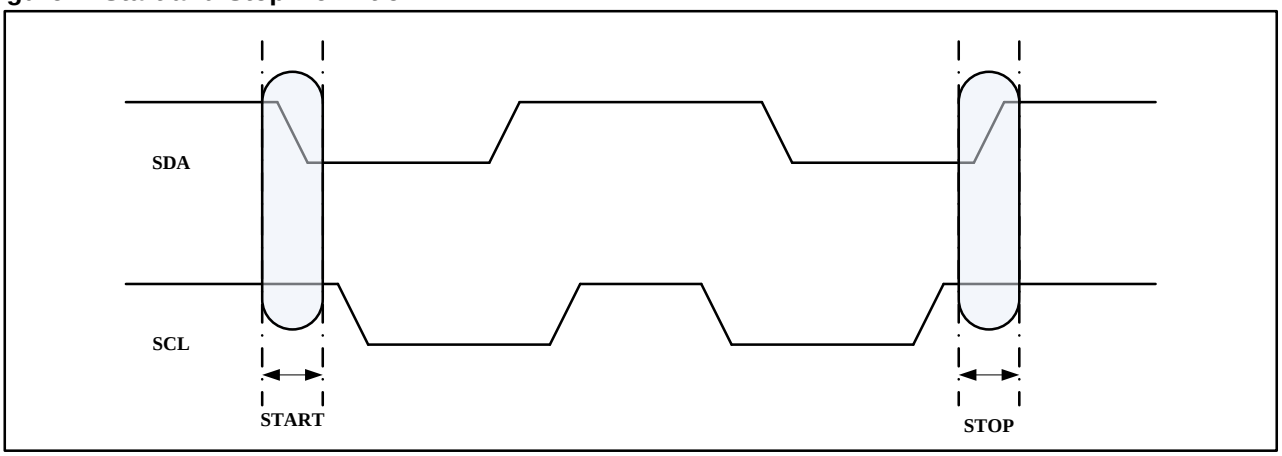
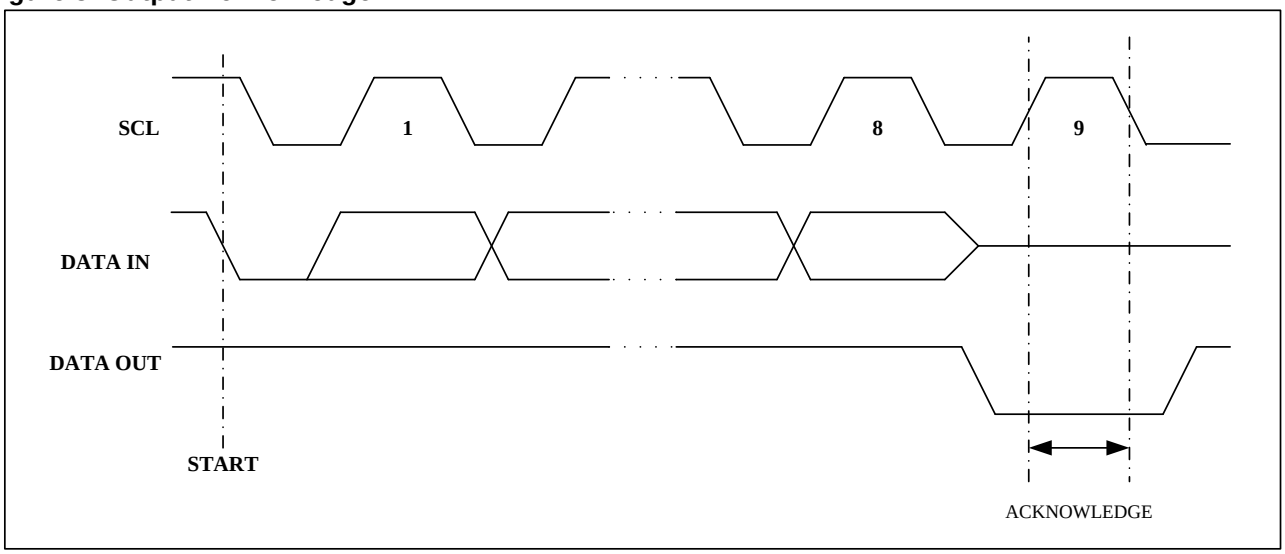


Figure 3. Output Acknowledge



深圳市满度科技有限公司
Web:www.manduic.com
©2016 Belling All Rights Reserved www.belling.com.cn
Tel:150-1290-5940
Email:sales@manduic.com

3. Device Addressing

The 128K EEPROM devices all require an 16-bit device address word following a start condition to enable the chip for a read or write operation (see Figure 4)

The device address word consists of a mandatory "1", "0" sequence for the first four most significant bits as shown. This is common to all the Serial EEPROM devices.

The 128K EEPROM uses A2, A1 and A0 device address bits to allow as much as eight devices on the same bus. These 3 bits must be compared to their corresonding hardwired input pins. The A2, A1 and A0 pins use an internal proprietary circuit that biases them to a logic low condition if the pins are allowed to float.

The eighth bit of the device address is the read/write operation select bit. A read operation is initiated if this bit is high and a write operation is initiated if this bit is low.

Upon a compare of the device address, the EEPROM will output a "0". If a compare is not made, the chip will return to a standby state.

DATA SECURITY: The BL24C128A has a hardware data protection scheme that allows the user to write protect the entire memory when the WP pin is at VCC.

4. Write Operations

BYTE WRITE: A write operation requires two 8-bit data word address following the device address word and acknowledgment. Upon receipt of every 8-bit address, the EEPROM will respond with a "0" and then clock in the first 8-bit data word. Following receipt of the 8-bit data word, the EEPROM will output a "0" and the addressing device, such as a microcontroller, must terminate the write sequence with a stop condition. At this time the EEPROM enters an internally timed write cycle, tWR, to the nonvolatile memory. All inputs are disabled during this write cycle and the EEPROM will not respond until the write is complete (see Figure 5).

PAGE WRITE: The 128K EEPROM is capable of an 64-byte page writes. A page write is initiated the same as a byte write, but the microcontroller does not send a stop condition after the first data word is clocked in. Instead, after the EEPROM acknowledges receipt of the first data word, the microcontroller can transmit up to 63 more data words. The EEPROM will respond with a “0” after each data word received. The microcontroller must terminate the page write sequence with a stop condition (see Figure 6).

The data word address lower six bits are internally incremented following the receipt of each data word. The higher data word address bits are not incremented, retaining the memory page row location. When the word address, internally generated, reaches the page boundary, the following byte is placed at the beginning of the same page. If more than 64data words are transmitted to the EEPROM, the data word address will “roll over” and previous data will be overwritten.

ACKNOWLEDGE POLLING: Once the internally timed write cycle has started and the EEPROM inputs are disabled, acknowledge polling can be initiated. This involves sending a start condition followed by the device address word. The read/write bit is representative of the operation desired. Only if the internal write cycle has completed will the EEPROM respond with a "0", allowing the read or write

深圳市满度科技有限公司 ©2016 Belling All Rights Reserved www.belling.com.cn Tel:150-1290-5940
Web:www.manduic.com Email:sales@manduic.com

sequence to continue.

5. Read Operations

Read operations are initiated the same way as write operations with the exception that the read/write select bit in the device address word is set to "1". There are three read operations: current address read, random address read and sequential read.

CURRENT ADDRESS READ: The internal data word address counter maintains the last address accessed during the last read or write operation, incremented by one. This address stays valid between operations as long as the chip power is maintained. The address "roll over" during read is from the last byte of the last memory page to the first byte of the first page. The address "roll

over" during write is from the last byte of the current page to the first byte of the same page.

Once the device address with the read/write select bit set to "1" is clocked in and acknowledged by the EEPROM, the current address data word is serially clocked out. The microcontroller does not respond with an input "0" but does generate a following stop condition (see Figure 7).

RANDOM READ: A random read requires a "dummy" byte write sequence to load in the data word address. Once the device address word and data word address are clocked in and acknowledged by the EEPROM, the microcontroller must generate another start condition. The microcontroller now initiates a current address read by sending a device address with the read/write select bit high. The EEPROM acknowledges the device address and serially clocks out the data word. The microcontroller does not respond with a "0" but does generate a following stop condition (see Figure 8)

SEQUENTIAL READ: Sequential reads are initiated by either a current address read or a random address read. After the microcontroller receives a data word, it responds with an acknowledge. As long as the EEPROM receives an acknowledge, it will continue to increment the data word address and serially clock out sequential data words. When the memory address limit is reached, the data word address will "roll over" and the sequential read will continue. The sequential read operation is terminated when the microcontroller does not respond with a "0" but does generate a following stop condition (see Figure 9).

Figure 4: Device Address

MSB							LSB
1	0	1	0	0	0	0	R/W

Figure 5: Byte Write

深圳市满度科技有限公司 ©2016 Belling All Rights Reserved www.belling.com.cn Tel:150-1290-5940
Web:www.manduic.com Email:sales@manduic.com

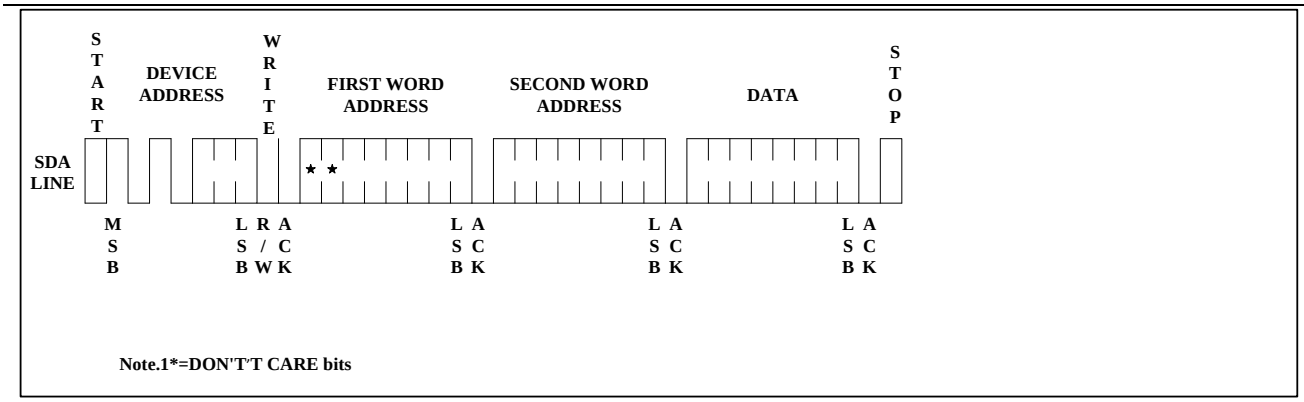


Figure 6: Page Write

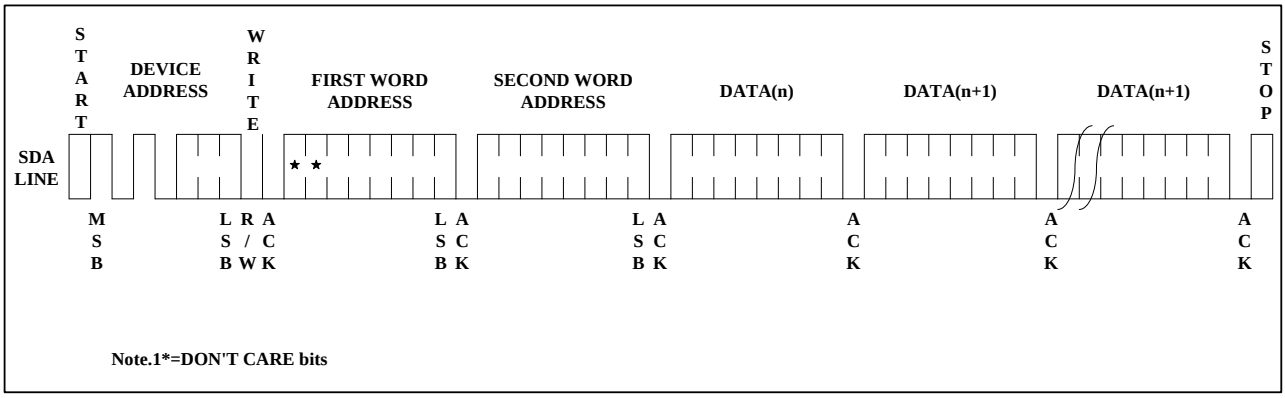


Figure 7: Current Address Read

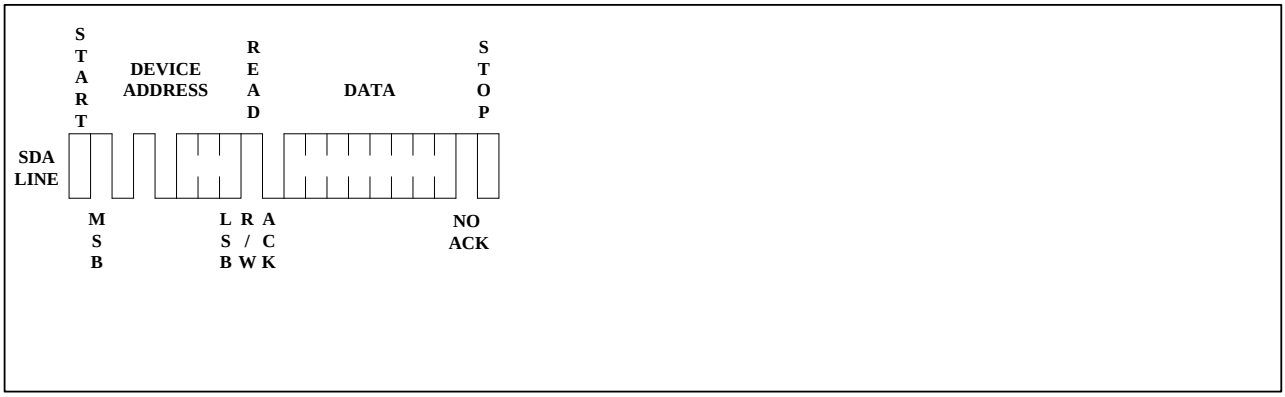
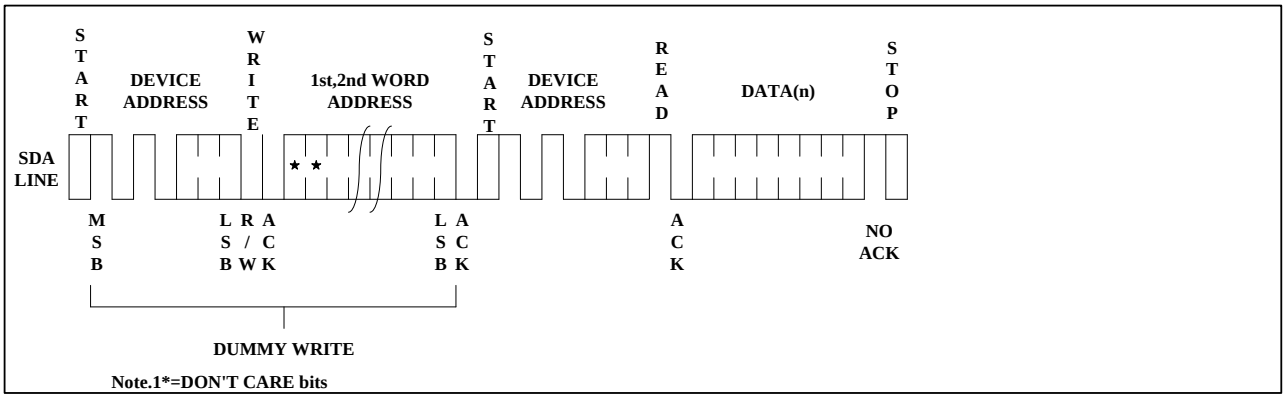
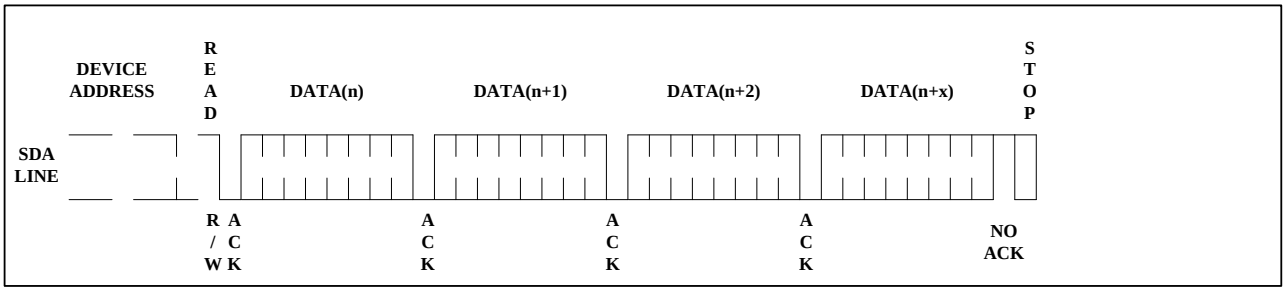


Figure 8: Random Read



深圳市满度科技有限公司 ©2016 Belling All Rights Reserved www.belling.com.cn Tel:150-1290-5940
Web:www.manduic.com Email:sales@manduic.com

Figure 9: Sequential Read



Electrical Characteristics

Absolute Maximum Stress Ratings：

- DC Supply Voltage . . . . . .-0.3V to +6.5V
- Input / Output Voltage. . . . . .GND-0.3V to VCC+0.3V
- Operating Ambient Temperature……-40℃ to +85℃
- Storage Temperature . . . . . .-65℃ to +150℃

- Comments:

  Stresses above those listed under "Absolute Maximum Ratings" may cause permanent damage to this device. These are stress ratings only. Functional operation of this device at these or any other conditions above those indicated in the operational sections of this specification is not implied or intended. Exposure to the absolute maximum rating conditions for extended periods may affect device reliability.

深圳市满度科技有限公司 ©2016 Belling All Rights Reserved www.belling.com.cn Tel:150-1290-5940
Web:www.manduic.com Email:sales@manduic.com

DC Electrical Characteristics

Applicable over recommended operating range from: TA = -40℃ to +85℃, VCC = +1.7V to +5.5V (unless otherwise noted)

Parameter	Symbol	Min	Typ	Max	Unit	Condition
Supply Voltage	V_{CC1}	1.7	-	5.5	V	-
Supply Voltage	V_{CC2}	2.5	-	5.5	V	-
Supply Voltage	V_{CC3}	2.7	-	5.5	V	-
Supply Voltage	V_{CC4}	4.5	-	5.5	V	-
Supply Current VCC=5.0V	I_{CC1}	-	0.4	1.0	mA	READ at 400KHZ
Supply Current VCC=5.0V	I_{CC2}	-	2.0	3.0	mA	WRITE at 400KHZ
Supply Current VCC=1.7V	I_{SB1}	-	0.6	1.0	μA	V_{IN}=Vcc or Vss
Supply Current VCC=2.5V	I_{SB2}	-	1.0	2.0	μA	V_{IN}=Vcc or Vss
Supply Current VCC=2.7V	I_{SB3}	-	1.0	2.0	μA	V_{IN}=Vcc or Vss
Supply Current VCC=5.0V	I_{SB4}	-	2.0	5.0	μA	V_{IN}=Vcc or Vss
Input Leakage Current	I_{L1}	-	0.10	3.0	μA	V_{IN}=Vcc or Vss
Output Leakage Current	I_{LO}	-	0.05	3.0	μA	V_{OUT}=Vcc or Vss
Input Low Level	V_{IL1}	-0.3	-	Vcc×0.3	V	Vcc=1.8V to 5.5V
Input High Level	V_{IH1}	Vcc×0.7	-	Vcc+0.3	V	Vcc=1.8V to 5.5V
Input Low Level	V_{IL2}	-0.3	-	Vcc×0.2	V	Vcc=1.7V
Input High Level	V_{IH2}	Vcc×0.7	-	Vcc+0.3	V	Vcc=1.7V
Output Low Level VCC=5.0V	V_{OL3}	-	-	0.4	V	I_{OL}=3.0mA
Output Low Level VCC=3.0V	V_{OL2}	-	-	0.4	V	I_{OL}=2.1mA
Output Low Level VCC=1.7V	V_{OL1}	-	-	0.2	V	I_{OL}=0.15mA

Pin Capacitance

Applicable over recommended operating range from TA = 25℃, f = 1.0 MHz, VCC = +1.7V

Parameter	Symbol	Min	Typ	Max	Unit	Condition
Input/Output Capacitance(SDA)	$C_{I/O}$	-	-	8	pF	V_{IO}=0V
Input Capacitance(A0,A1,A2,SCL)	C_{IN}	-	-	6	pF	V_{IN}=0V

深圳市满度科技有限公司 ©2016 Belling All Rights Reserved www.belling.com.cn Tel:150-1290-5940
Web:www.manduic.com Email:sales@manduic.com

AC Electrical Characteristics

Applicable over recommended operating range from TA = -40℃ to +85℃, VCC = +1.7V to +5.5V, CL = 1 TTL Gate and 100 pF (unless otherwise noted)

Parameter	Symbol	1.7V≤Vcc＜2.5V			2.5V≤Vcc＜5.5V			Units
		Min	Typ	Max	Min	Typ	Max	
Clock Frequency,SCL	f_{SCL}	-	-	400	-	-	1000	KHZ
Clock Pulse Width Low	t_{LOW}	1.2	-	-	0.6	-	-	μs
Clock Pulse Width High	t_{HIGH}	0.6	-	-	0.4	-	-	μs
Noise Suppression Time	t_I	-	-	50	-	-	50	ns
Clock Low to Data Out Valid	t_{AA}	0.1	-	0.9	0.05	-	0.9	μs
Time the bus must be free before a new transmission can start	t_{BUF}	1.2	-	-	0.5	-	-	μs
Start Hold Time	$t_{HD:STA}$	0.6	-	-	0.25	-	-	μs
Start Setup Time	$t_{SU:DAT}$	0.6	-	-	0.25	-	-	μs
Data In Hold Time	$t_{HD:DAT}$	0	-	-	0	-	-	μs
Data in Setup Time	$t_{SU:DAT}$	100	-	-	100	-	-	ns
Input Rise Time(1)	t_R	-	-	0.3	-	-	0.3	μs
Input Fall Time(1)	t_F	-	-	300	-	-	300	μs
Stop Setup Time	$t_{Su:STO}$	0.6	-	-	0.25	-	-	μs
Data Out Hold Time	t_{DH}	50	-	-	50	-	-	ns
Write Cycle Time	t_{WR}	-	3.3	5	-	3.3	5	ms
5.0V,25℃,Byte Mode(1)	Endurance	1M	-	-	-	-	-	Write Cycle

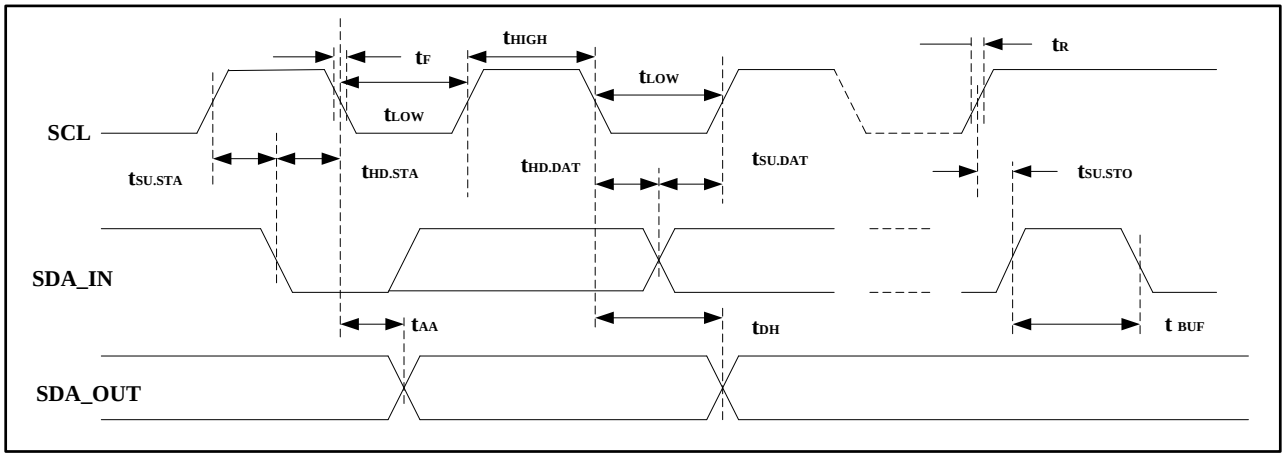
Note:
1. This parameter is characterized and is not 100% tested.
2. AC measurement conditions:

RL (connects to VCC): 1.3 k (2.5V, 5V), 10 k (1.7V) Input pulse voltages: 0.3 VCC to 0.7 VCC
Input rise and fall time: 50 ns
Input and output timing reference voltages: 0.5 VCC
The value of RL should be concerned according to the actual loading on the user's system.

深圳市满度科技有限公司
Web:www.manduic.com
©2016 Belling All Rights Reserved www.belling.com.cn
Tel:150-1290-5940
Email:sales@manduic.com

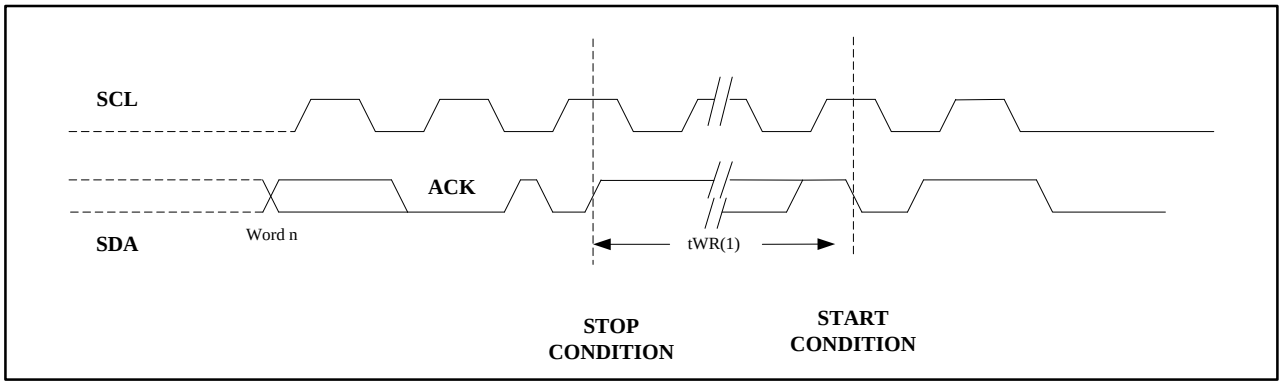
Bus Timing

Figure 10: SCL: Serial Clock, SDA: Serial Data I/O



Write Cycle Timing

Figure 11: SCL: Serial Clock, SDA: Serial Data I/O



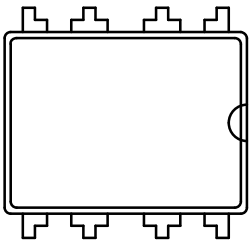
Note:

The write cycle time tWR is the time from a valid stop condition of a write sequence to the end of the internal clear/write cycle.

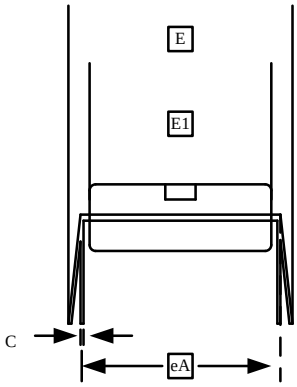
深圳市满度科技有限公司 ©2016 Belling All Rights Reserved www.belling.com.cn Tel:150-1290-5940
Web:www.manduic.com Email:sales@manduic.com

Package Information

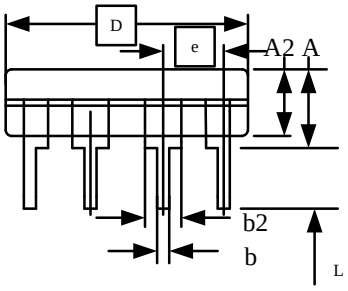
PDIP Outline Dimensions



Top View



End View



Side View

COMMON DIMENSIONS
Unit of Measure=mm

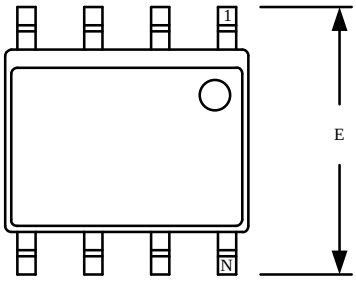
SYMBOL	MIN	NOM	MAX	NOTE
A	3.60	3.80	4.00	2
A2	3.00	3.30	3.40	
b	0.44	-	0.53	5
b2		1.52BSC		6
c	0.24	-	0.32	
D	9.05	9.25	9.45	3
E	7.62	-	9.30	4
E1	6.15	6.35	6.55	3
e		2.54BSC		
eA		7.62BSC		4
L	3.00	-	-	2

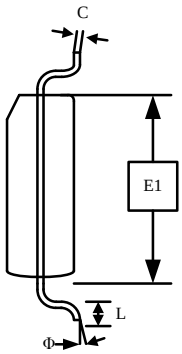
Note:

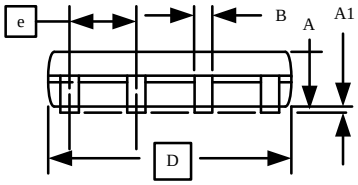
1. This drawing is for general information only; refer to JEDEC Drawing MS-001, Variation BA for additional information.
2. Dimensions A and L are measured with the package seated in JEDEC seating plane Gauge GS-3.
3. D, D1 and E1 dimensions do not include mold Flash or protrusions. Mold Flash or protrusions shall not exceed 0.010 inch.
4. E and eA measured with the leads constrained to be perpendicular to datum.
5. Pointed or rounded lead tips are preferred to ease insertion.
6. b2 and b3 maximum dimensions do not include Dambar protrusions. Dambar protrusions shall not exceed 0.010 (0.25 mm).

深圳市满度科技有限公司 ©2016 Belling All Rights Reserved www.belling.com.cn Tel:150-1290-5940
Web:www.manduic.com Email:sales@manduic.com

SOP







COMMON DIMENSIONS
Unit of Measure=mm

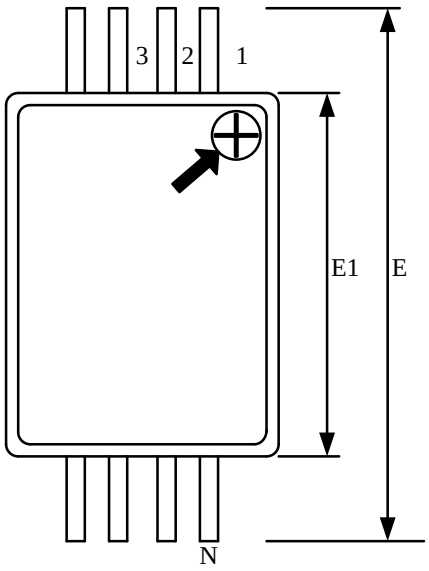
SYMBOL	MIN	NOM	MAX	NOTE
A	1.35	–	1.75	
A1	0.10	–	0.23	
B	0.39	–	0.48	
C	0.21	–	0.26	
D	4.70	4.90	5.10	
E1	3.70	3.90	4.10	
E	5.80	6.00	6.20	
e	1.27BSC			
L	0.50	–	0.80	
Φ	0°	–	8°	

Note:

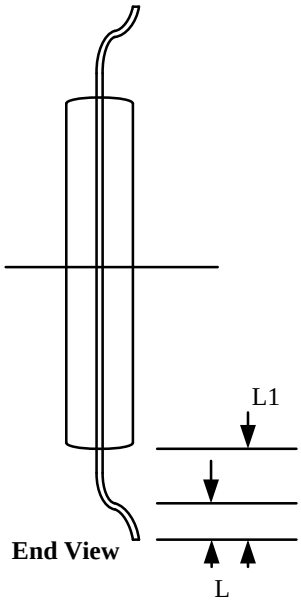
These drawings are for general information only. Refer to JEDEC Drawing MS-012, Variation AA for proper dimensions, tolerances, datums, etc.

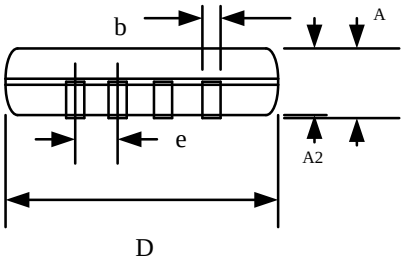
深圳市满度科技有限公司 ©2016 Belling All Rights Reserved www.belling.com.cn Tel:150-1290-5940
Web:www.manduic.com Email:sales@manduic.com

TSSOP



Top View





Side View

COMMON DIMENSIONS
Unit of Measure=mm

SYMBOL	MIN	NOM	MAX	NOTE
A	–	–	1.20	
A2	0.90	1.00	1.05	
b	0.21	–	0.30	4
D	2.90	3.00	3.10	2, 5
E	6.20	6.40	6.60	
E1	4.30	4.40	4.50	3, 5
e	0.65BSC			
L	0.45	–	0.75	
L1	1.00REF			

Note:

1. This drawing is for general information only. Refer to JEDEC Drawing MO-153, Variation AA, for proper dimensions, tolerances, datums, etc.

2. Dimension D does not include mold Flash, protrusions or gate burrs. Mold Flash, protrusions and gate burrs shall not exceed 0.15 mm (0.006 in) per side.

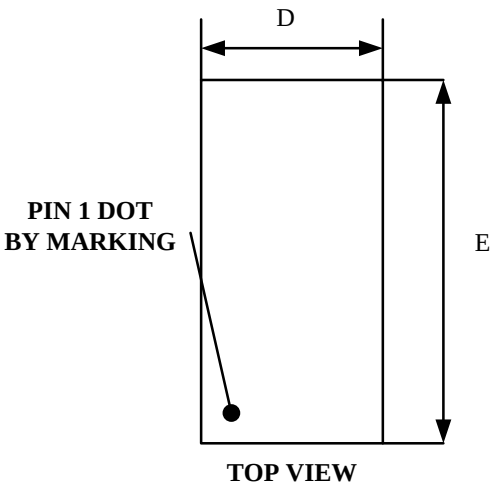
3. Dimension E1 does not include inter-lead Flash or protrusions. Inter-lead Flash and protrusions shall not exceed 0.25 mm (0.010 in) per side.

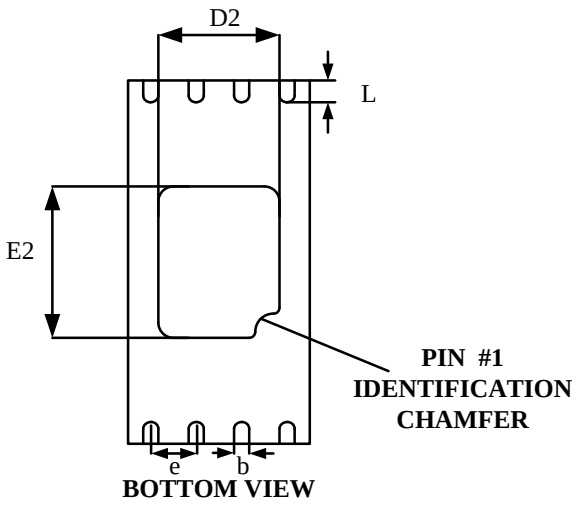
4. Dimension b does not include Dambar protrusion. Allowable Dambar protrusion shall be 0.08 mm total in excess of the b dimension at maximum material condition. Dambar cannot be located on the lower radius of the foot. Minimum space between protrusion and adjacent lead is 0.07 mm.

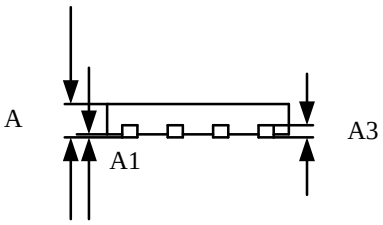
5. Dimension D and E1 to be determined at Datum Plane H.

深圳市满度科技有限公司 ©2016 Belling All Rights Reserved www.belling.com.cn Tel:150-1290-5940
Web:www.manduic.com Email:sales@manduic.com

UDFN





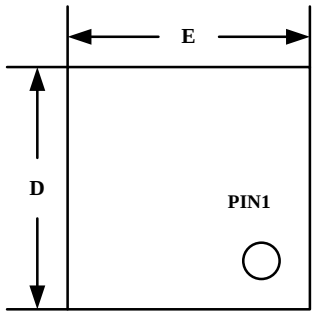


COMMON DIMENSIONS
Unit of Measure=mm

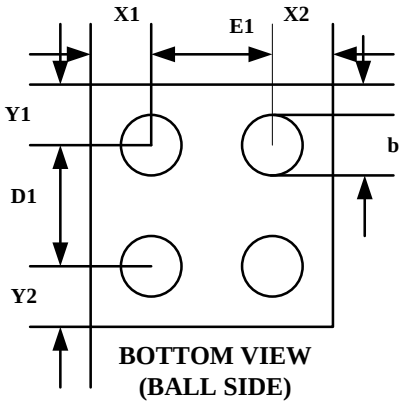
PKG	UT:ULTRA THIN		
SYMBOL	MIN	NOM	MAX
A	>0.50	0.55	0.60
A1	0.00	-	0.05
A3	0.15REF		
D	1.95	2.00	2.05
E	2.95	3.00	3.05
b	0.20	0.25	0.30
L	0.20	0.30	0.40
D2	1.25	1.40	1.50
E2	1.15	1.30	1.40
e	0.50BSC		

深圳市满度科技有限公司
Web:www.manduic.com
©2016 Belling All Rights Reserved www.belling.com.cn
Tel:150-1290-5940
Email:sales@manduic.com

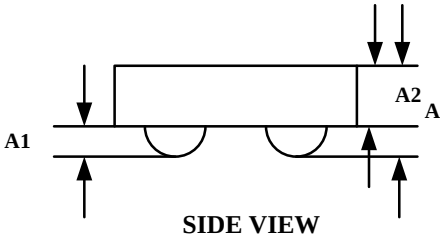
WLCSP



TOP VIEW
(MARK SIDE)



BOTTOM VIEW
(BALL SIDE)



SIDE VIEW

COMMON DIMENSIONS
Unit of Measure=mm

SYMBOL	MIN	NOM	MAX
A	0.270	0.290	0.310
A1	0.045	0.055	0.065
A2	0.215	0.235	0.255
D	0.738	0.758	0.778
D1		0.400BSC	
E	0.668	0.668	0.708
E1		0.400BSC	
b	0.160	0.180	0.200
x1		0.144 REF	
x2		0.144 REF	
y1		0.179 REF	
y2		0.179 REF	

NOTES:

All wafer orientation notch down

深圳市满度科技有限公司 ©2016 Belling All Rights Reserved www.belling.com.cn Tel:150-1290-5940
Web:www.manduic.com Email:sales@manduic.com

Ordering Information

BL24C128A – 1 2 3

Code	Description
1	Package type PA: SOP-8L SF: TSSOP-8L DA: PDIP-8L NT: UDFN-8L TC: SOT23-5L RR: TSOT23-5L MA: M2.2 MB: M3.2
2	Packing type R: Tape and Reel T: Tube
3	Feature S: Standard (default, Pb Free RoHS Std.) C: Green (Halogen Free)

BL24C128A - 1 - 2

Code	Description
1	Package type CS: WLCSP-4
2	Packing type R: Tape and Reel

深圳市满度科技有限公司
Web:www.manduic.com
©2016 Belling All Rights Reserved www.belling.com.cn
Tel:150-1290-5940
Email:sales@manduic.com

Revision history

Vision 1.7 BL24C128A
Add Write lockable page in Features Random and sequential Read modes Enhanced ESD/ Latch-up protection UDFN packages
Add Table First/Second address Write Identification Page/ Lock Identification Page Read Identification Page
Modify DC/AC Electrical Characteristics
Vision 1.8 BL24C128A
Modify the format
Vision 1.91 BL24C128A
Modify AC/DC Electrical Characteristics
Vision 1.92 BL24C128A
Modify Package Information

©2016 Belling All Rights Reserved www.belling.com.cn

深圳市满度科技有限公司
Web:www.manduic.com
Tel:150-1290-5940
Email:sales@manduic.com